

# Mitsubishi Limiservo X G series TECHNICAL INFORMATION MANUAL

Motor XL-G554-10(Y), XL-G554-20(Y)

Control box XC-GMFY(CE)

# Induction type AC servo motor and control box with automatic needle positioner



Thank you for purchasing this product.

Please read this manual thoroughly before use to ensure safe and proper use.

Please read the instruction manual for the machine head together with this manual.

Save this manual for future reference.

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# 2 | Safety Instructions

#### 1. To ensure safe use

\*Always observe the following items to ensure safe use of the industrial sewing machine drive unit (motor and control box).

#### 1.1 Before starting

Read all instruction manuals thoroughly before starting use of this drive unit, and follow the technical manuals. Also read the instruction manuals for the installed sewing machine.

# 1.2 Application and purpose

This drive unit is designed to drive a sewing machine and must not be used for other applications or purposes. Do not use this drive unit until it can be confirmed that safety measures for the installed sewing machine have been taken.

### 1.3 Work environment

Use this drive unit in dry and well-kept clean locations, e.g. in the clothing industry, and which process dry sewing material. Avoid using this control unit in the following types of environments.

- Place where voltage fluctuation exceeds ±10% of the rated voltage. (1) Power voltage

- Place where the specified power capacity cannot be secured. (Refer to page 10)

- Place where strong electric or magnetic fields are generated such as near a large-output high frequency (2) Electromagnetic oscillator or high frequency welding machine. noise (3) Temperature

- Place where atmospheric temperature is 35 degree or higher and 5 degree or lower.

and humidity - Place subject to direct sunlight or outdoors.

- Near a heat source such as a heater. - Place where relative humidity is 45% or less and 85% or more, or where dew condensation occurs.

(4) Atmosphere - Atmosphere with dust or corrosive gases. - Atmosphere with combustible gases or explosive atmosphere.

(5) Altitude - Place where altitudes exceeds 1,000m above mean sea level.

(6) Storage - Place where storage temperature is 55 °C or higher and -25°C or lower.

(7) Vibration - If excessive vibration occurs when the control box is installed on the sewing machine, install it separately.

### 2. Installation

#### 2.1 Motor and control box

- Correctly install according to the attached technical manuals.

#### 2.2 Accessories

- Always disconnect this control unit from the main power supply when installing any accessories listed in the technical manual. (Turn the main switch OFF, and remove the plug from the outlet (power supply line).)

#### 2.3 Cable

- (1) Arrange the connection cable so that excessive force is not applied during use, and do not excessively bend the cable.
- (2) Cables near moving parts (e.g., pulley) must be wired at a minimum distance of 25mm.
- (3) Confirm that the power voltage of the power cable for supplying to the control box meets the specifications on the motor and control box rating nameplates before connecting it to the power line. Connect it to the designated places to supply the power. Perform this step with the power switch turned OFF.

# 2.4 Grounding

- Correctly connect the power cable grounding to the power supply grounding.
- 2.5 Accompanying appliances and accessories
  - Electric accompanying appliances and accessories must be connected to the place listed in this manual.

- (1) Turn the power switch OFF and remove the plug from the outlet (power supply line) before removing the motor or control box.
- (2) Do not pull on the cord when removing the plug. Always hold the plug itself.
- (3) There is a high voltage applied inside the control box, so always wait at least 10 minutes after running the power switch OFF and remove the plug from the outlet (power supply line) before opening the control box panel.

# 3. Maintenance, inspection and repairs

- Follow the technical manuals for maintenance and inspection of this control unit.
- Repairs and maintenance must be done and approved by specially trained personnel.
- Do not run this control with the ventilation openings of the motor's dust-proof filter blocked or clogged with dust, loose cloth, etc.
- Always turn the power switch OFF and remove the plug from the outlet (power supply line) before replacing the sewing machine needle or bobbin, etc.
- Always use original replacement parts for repairs or maintenance.

# Other safety measures

- Keep fingers away from all moving machine parts (especially near sewing machine needle, etc.).
- Do not drop this control unit.
- Do not operate this product without parts such as the protective cover or protective devices such as the safety breaker.
- The servomotor surface may reach high temperatures depending on the operation conditions and loads. Do not touch directly.
- If any damage is observed on this control unit, if the drive does not run properly or if operator is uncertain about operation, do not operate the drive unit. Operate the drive only after adjustments, repairs and approvals have been made by qualified personnel.
- The user must avoid making modifications or changes based on user's judgment.
- When system have to be stop in case of emergency, remove the power supply plug from the power supply line.

# 5. Hazard display, warning display

- (1) This symbol indicates risk that may cause personal injury or risk to the machine when mishandling of products.
- (2) This symbol indicates electrical risks and warnings.
- (3) This symbol indicates thermal risks and warnings.
- Always deliver this instruction manual to the end user. - Save these technical manuals for future reference.







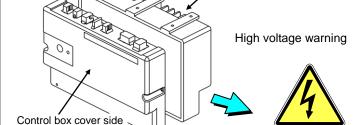
# Caution

- 1. Please remove your foot from the pedal when turning the power ON.
- 2. Always turn the power OFF when leaving the machine.
- 3. Do not inspect the control circuit with a tester.
- 4. Always turn the power switch OFF before tilting the sewing machine, replace the needle or threading the needle.
- 5. Always ground the grounding wire.
- 6. Do not use branched wiring.
- 7. The brakes may not function when the power is turned OFF or when there is a power failure during sewing machine operation.
- 8. Match the connector shape and direction, and insert securely.
- 9. Keep the signal wire as short as possible when connecting the external switch to the connector of control box. If it is long, malfunctions may occur. Use a shield wire when possible.
- 10. Install the sewing machine away from sources of strong noise such as high-frequency welders.
- 11. An optical method is used for the detector's detection element so take care not to let dust or oils get on the detection plate when removing the cover for adjustment, etc. If these do get on the plate, wipe off with a soft cloth and do not scratch the plate. Take care not to let oils enter between the detector discs.
- 12. When the position detector connector or the belt has come off or when the sewing machine is completely locked, the motor will be automatically turned OFF after a set time to prevent damage to the motor. (The motor may not turn OFF if the locking is not complete.) After the problem has been resolved, turn the power OFF and ON and normal operation will be possible. The same operation should be taken when the position detector or wires are broken.
- 13. Be sure to ground the lever unit when using it to separate from the control box.
- 14. Always turn off the power switch before connecting or disconnecting each connector
- 15. Do not alter this motor and control box including accessories to avoid any accident

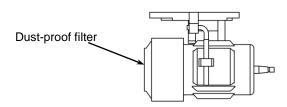
The altered examples: To connect the power supply to the other device through the push button switch, to take out signals of the encoder and the detector to use the external devices.

Our company does not assume the responsibility on any accident caused by altering.

16. A high voltage is applied inside the machine, so wait at least 10 minutes after turning the power OFF before opening the control box. There is a cable connecting the PCB on the cover side with the PCB on the box side. When disconnecting the cable, gently disconnect at the connector section. Do not pull with force. Control box side

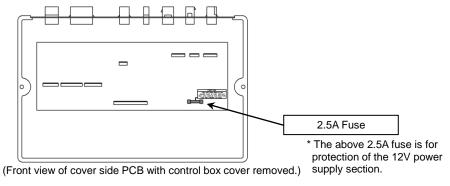


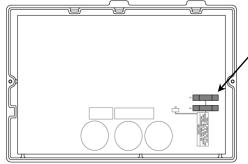
17. Remove the dust that has adhered on the motor's dust-proof filter once every two to three weeks.



If the motor is run while the filter is clogged, the motor may overheat and affect the motor life.

18. If the fuse blows, remove the cause, and replace the blown fuse with one having the same capacity.





Two 20A Fuses

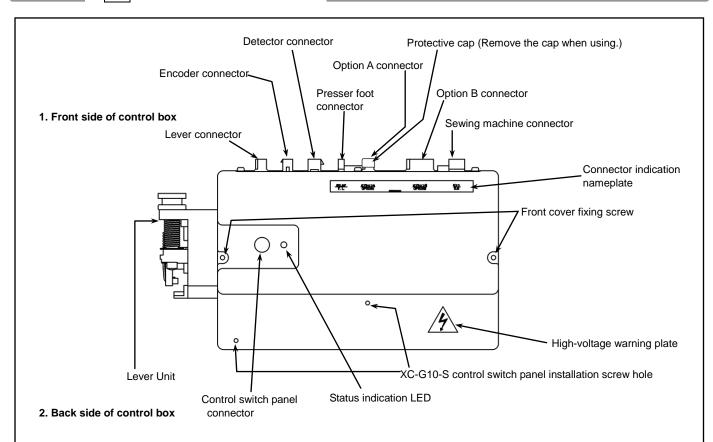
\* The above fuses are for protection of the control box power supply section.

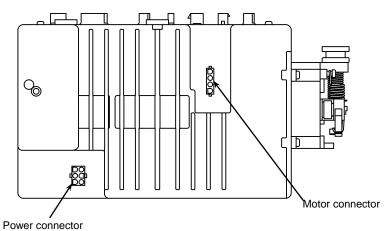


Always wait at least 10 minutes after turning the power switch OFF before opening the control box cover.

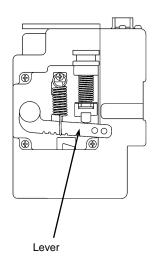
(Front view of box side PCB with control box cover removed.)

# 4 Names of Each Part





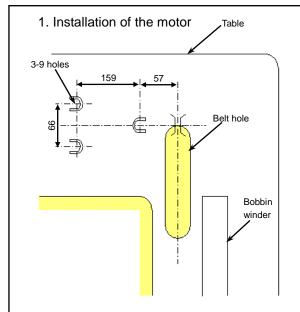
# 3. Left side of control box





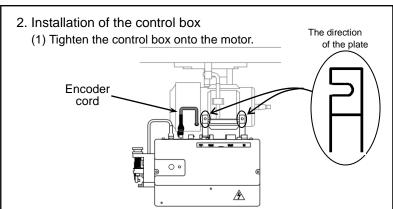
Be sure to ground the lever unit when using it to separate from the control box.

# Installation

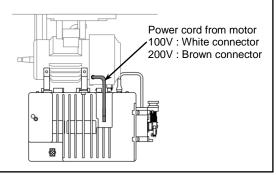


Open three 9mm holes on the table as seen from the above. Install the motor securely using the installation bolts, washers, spring washers and

The installation bolts, etc, are included with the motor as accessories.



(2) Insert the power cord from the motor into the connector on the back of the control box. Insert the encoder cord from the motor into the encoder connector on the front of the control box.



3. Installation of the pulley

\* To properly install, the protective cover A (motor side of the protective cover) must be installed onto the motor before the pulley is installed. (Refer to "5. Installing the protective cover".)

Securely tighten the pulley.

Caution Incomplete tightening may cause malfunctions.

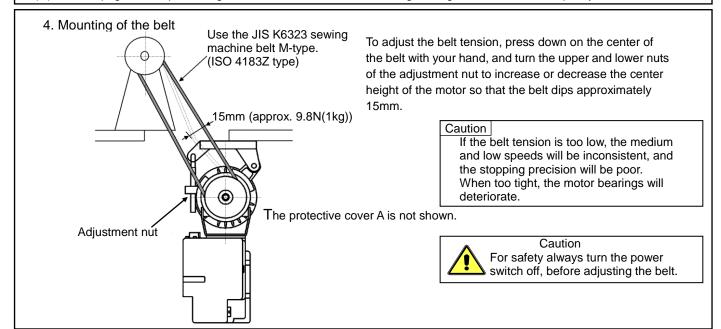
Select the correct pulley diameter to ensure complete use of the motor performance.

Selection of the motor pulley:

Sewing machine pulley diameter + 5 mm Normal sewing machine speed x Motor pulley outer diameter (mm) = (effective diameter) (\*) Motor speed

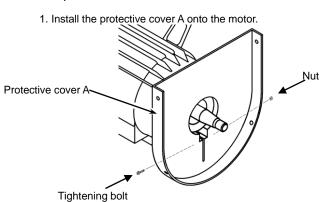
(\*) The motor speed should be set at 3,600rpm. When the motor pulley diameter is selected with the above method and the pulley diameter is too small, select the minimum pulley in the range that the belt will not slip.

(\*\*) Refer to page 24 Simple setting table for Mitsubishi thread trimming sewing machine and motor pulley outside diameter.

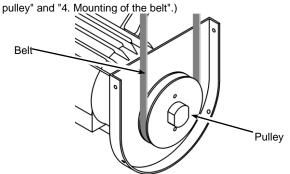


5. Installation of the protective cover (with belt slip off prevention part)

The protective cover is enclosed with the motor as an accessory.

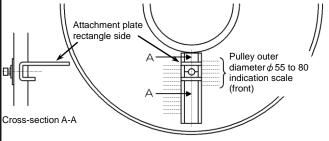


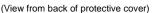
2. Install the pulley and attach the belt. (Refer to "3. Installing the

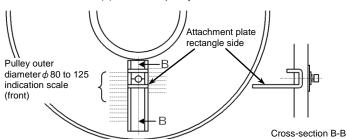


- 3. Install the "belt slip off prevention part mounting plate" onto protective cover B with the following procedures.
  - \* Change the direction of the long and short side of the attachment plate according to the motor pulley outer diameter.
- (a) For motor pulley outer diameter  $\phi$  55 to  $\phi$  80

(b) For motor pulley outer diameter  $\phi$  80 to  $\phi$  125

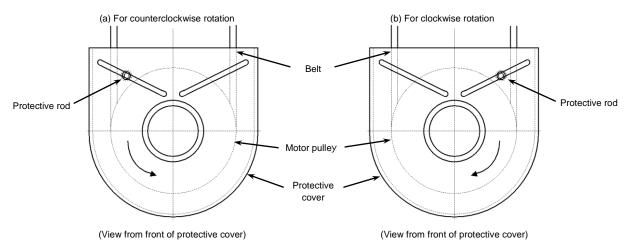




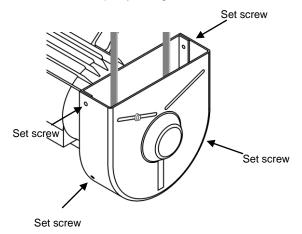


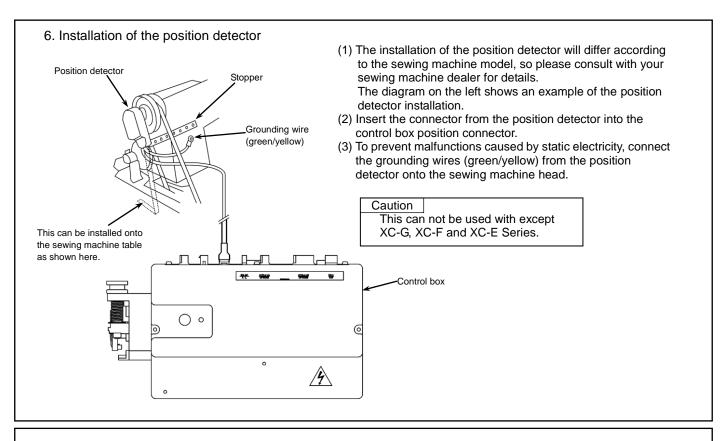
(View from back of protective cover)

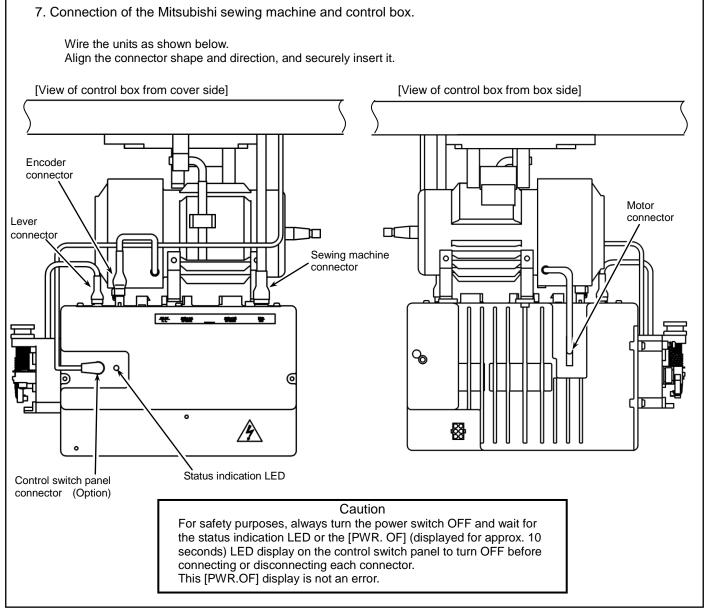
- \* Set the center of the washer to the pulley diameter indication scale and tighten the bolt.
- \* Confirm that the belt does not contact the attachment plate.
- 4. Install the "protective rod" onto the protective cover B with the following steps.
  - \* Set the protective rod to the motor pulley rotation direction and install between the belt and motor pulley.



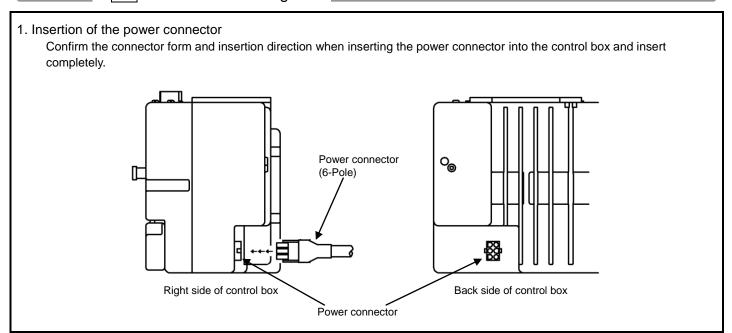
- \* Set the center of the protective rod to the position at the center of the belt and motor pulley and tighten the bolt
- 5. Set protective cover B onto protective cover A, and tighten with the four set screws.
- \* Confirm that the belt and motor pulley do not contact the protective rod.
- If necessary, adjust the position of the "protective rod" and "belt slip off prevention part mounting plate". Securely tighten after adjusting.

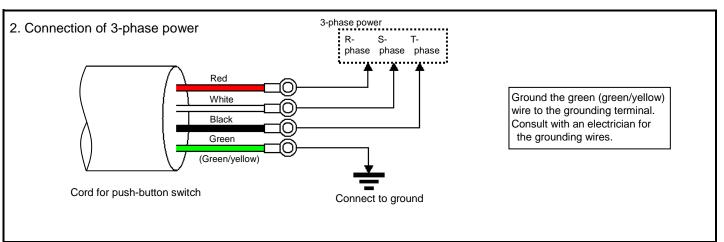






# 6 Wire and Grounding

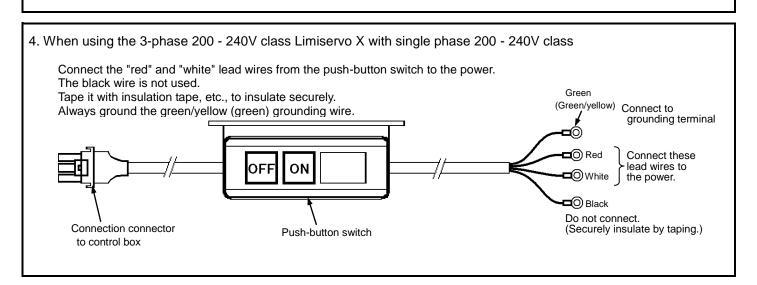




3. Current capacity

Use a fuse or complete breaker for the power.

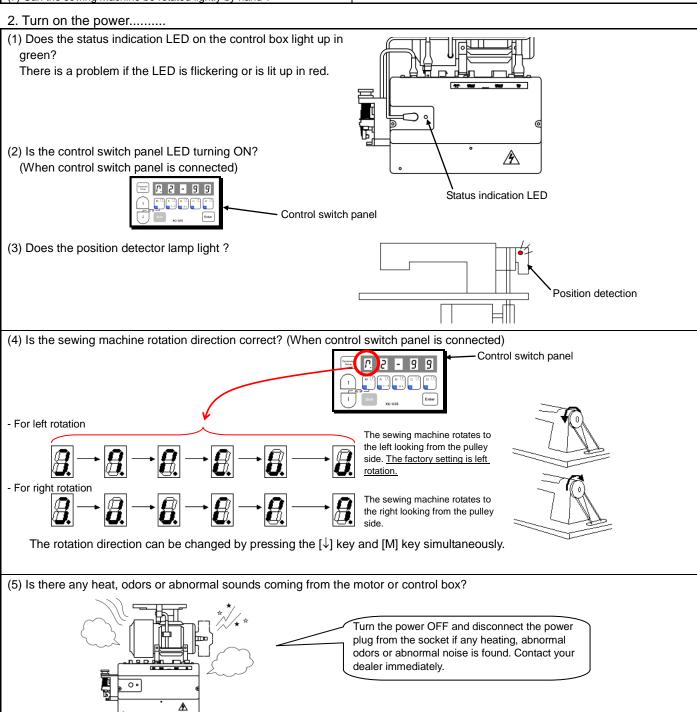
Power	Recommended current capacity
Single phase 100 to 120V 550W 200 to 240V 550W / 750W	15A
3- phase 200 to 240V 550W / 750W	10A



# 7 Confirmation

# 1. Before turning switches on.........

Places to confirm	Reference
(1) Is the power and capacity suitable ?	Current capacity on page 10.
(2) Is the power voltage the same as the factory preset voltage of t rated nameplate on the side of the control box?	he Voltage value given on rated nameplate on side of control box.  XC-GMFY-20-05: 200 to 240V  XC-GMFY-10-05: 100 to 120V
(3) Are the connectors inserted correctly?  -Power connector from push-button switch -Motor connector -Motor encoder connector -Position detection connector	Insertion of the power connector on page 10. Connection of the Mitsubishi sewing machine and control box on page 9. Insertion of the position detector on page 9.
(4) Is the lead wire contacting the V belt ?	-
(5) Is the belt tension okay?	Mounting of the belt on page 7.
(6) Are the pulley nuts securely tightened?	Installation of the pulley on page 7.
(7) Can the sewing machine be rotated lightly by hand?	-



# 1. Adjustment of stopping position

Adjust this position with the detector installed onto the sewing machine and while stopping at the UP and DOWN positions.

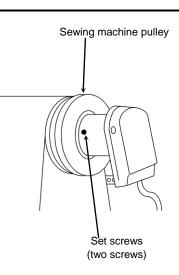
For safety, disconnect the connector for the sewing machine.

# (1) Adjustment of UP position

- -Loosen the two set screws on the detector joint, and set the stop position by rotating by hand.
- -If adjustment is not possible by turning the joint, loosen the cross-recessed screw A shown of the following figure, and turn all detector plates simultaneously to adjust to the designated stop position.

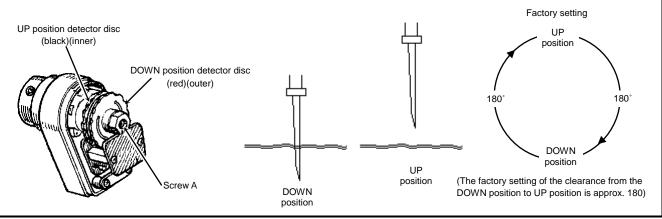
# (2) Adjustment of DOWN position

- -The relation of the DOWN position and UP position will differ according to the model, so adjust this according to the sewing machine.
- -When changing the DOWN position, remove the detector cover, and turn only the red detector plate to adjust to the designated stop position.
- (The cross-recessed screw A does not need to be loosened at this time.)
- -Always replace the cover after adjustment.



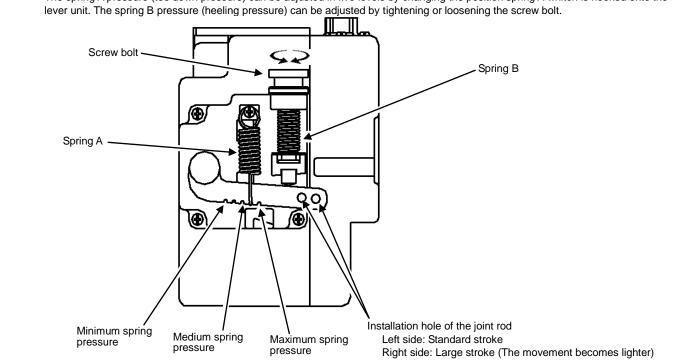
### Caution

Refer to the sewing machine instruction manual when adjusting for use with the Mitsubishi sewing machine.



# 2. Adjustment of pedal toe down pressure, and heeling pressure

The spring A pressure (toe down pressure) can be adjusted in five levels by changing the position spring A whitch is hooked onto the



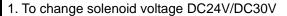
# 3. Adjustment of operation speed

Adjustment of each speed		Reference	Factory setting (speed)
Maximum speed	Н	Page 25 "To change the maximum speed"	4000
Low speed	L	_	250
Thread trimming speed	Т	-	200
Start tack speed	N	-	1700
End tack speed	V	-	1700
Slow start speed	S	-	250
Operation speed		Adjust between the low speed [L] and hig the [C] and [D] keys on the control switch	
			It is possible to adjust between 0 and 99.%  Jkey  Adjustment range with the [C] key and [D] key.

# Caution

No matter how large the motor pulley diameter is, the speed will not rise higher than the maximum speed H and the speed set with the [C] key and [D] key.

# 9 Changing the solenoid voltage and output voltage

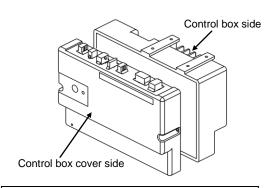


To change solenoid voltage from 24V to 30V

- (1) Remove the front cover from the control box.
- (2) Reconnect the connector inserted in JP1 on the PCB to the 30V side.
- (3) Set the cover to the original position after change.

To change solenoid voltage from 30V to 24V

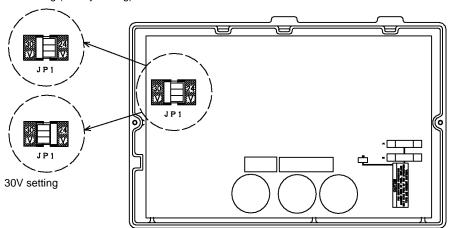
- (1) Remove the front cover from the control box.
- (2) Reconnect the connector inserted in JP1 on the PCB to the 24V side.
- (3) Set the cover to the original position after change.





Wait at least 10 minutes after turning the power switch OFF before opening the control box.

24V setting (factory setting)



Control box side

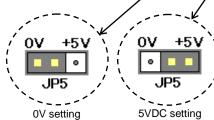
5VDC setting

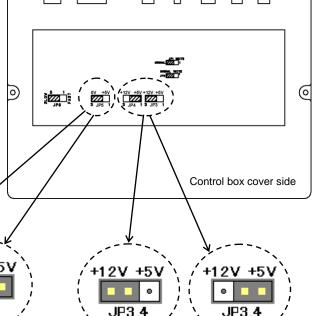
- 2. Changing the output voltage between 0VDC and 5VDC
  - (1) Remove the control box cover.
  - (2) Change the output voltage 5/12VDC with the jumper JP3 and JP4 on the front cover PCB as shown on the right. Change the output voltage 0/5VDC with the jumper JP5 on the front cover PCB.
  - (3) The output voltage can be changed by reconnecting the connector as shown on the right.

(4) The factory setting

(1) 1110	ractory cotting	
Connector	factory setting	Connector (Pin No.)
JP3	+12V	No.3 pin of the option A
JP4	+5V	No.7 pin of the option B
JP5	0V	No.10 pin of the sewing machine

(5) After change, always set the cover to the control box







Wait at least 10 minutes after turning the power switch OFF before opening the control box.



Do not change the JP1,JP2 and JP6 from the factory setting.

12VDC setting

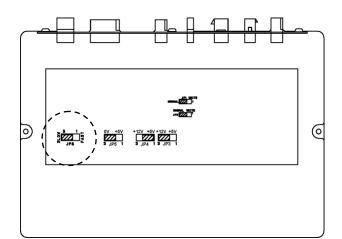
3. How to set the switch for increasing the solenoid return speed.



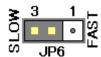
For safety, turn the power switch OFF before opening cover

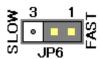
(1) Remove the cover.

(2) The solenoid return speed can be increased with the setting of the JP6 connector on the front cover PCB as shown on the right.



(3) To change the solenoid return speed, pull out the connector and reinsert it into the FAST side.





Normal setting

FAST setting

(4) Connector factory settings and solenoid return

Connector	Factory setting	Output during simple setting	Solenoid return	Output
JP6	SLOW	Sewing machine connector 3-4 pin output	Normal	OA

(5) After change, always set the cover to the control box.

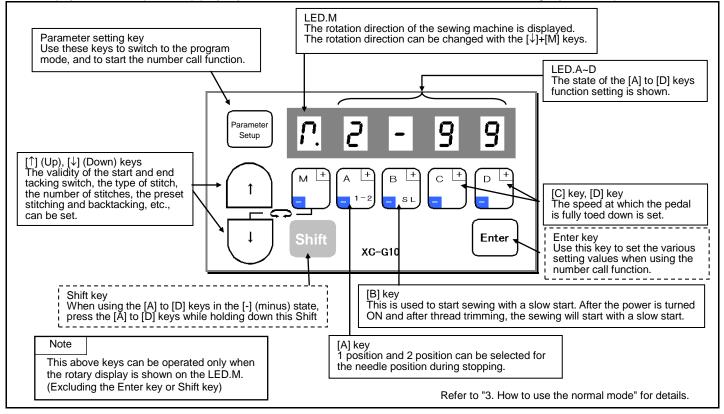


When you set the JP6 connector to the FAST side, be sure to set the function [OAC] to [OF] in the program mode [C]. If the [OAC] is still set to [ON], which means chopping duty [OAC] still operates, the resistance on the PWB will be burnt out.

# 10 Operation of the Control Switch Panel Keys(When using XC-G10 type control switch panel)

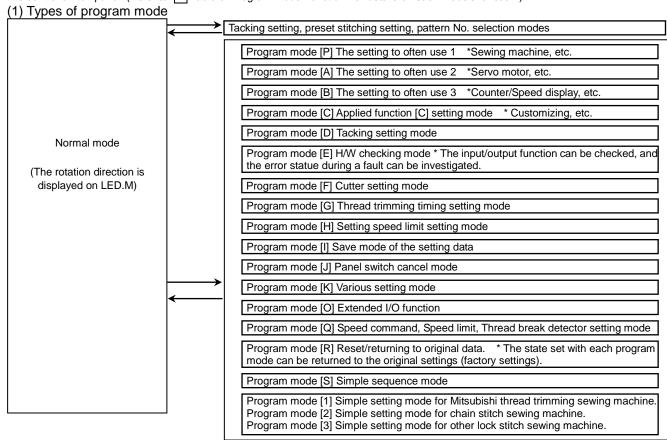
# 1. Displays during normal mode and functions of each key

When the power supply switch is turned ON, the rotation direction will display on the LED.M shown below. When the rotation direction is not displayed on LED.M, press the  $[\downarrow]$  key any time. This state is called **the normal mode**, and the following keys can be operated.



### Selection of each mode

The modes can be changed from the normal mode to various program modes and various basic functions and application functions set with this control switch panel. (Refer to "24 Table of Program Mode Function" for details on each mode's function.)

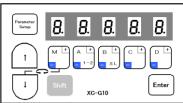


Caution: A program mode cannot be entered from an other program mode.

Always return to the normal mode once before changing the program mode.

Note that when the program mode is selected with the "Direct number call function", a selection exceeding the program mode type can be made with the number selection.

(2) Selection of each program mode from the normal mode.



Mode name	Key operation		Digital display		Return to the normal mode							
Tacking type setting mode	Press the [↑] key one time from the normal mode.		8 - 2 - 2	*The tacking setting mode will be entered.	Press the [↓] key one time.							
No. of tacking stitch setting mode	Press the [↑] key two times the normal mode.	from	Note) Skipping this menu at	*The tacking stitches setting mode will be entered. the time of pattern No.=4.	Press the [↓] key two times.							
Preset stitching setting mode	Press the [↑] key three time the normal mode.	es from	-   4 4	*The preset stitching setting mode.  t the time of pattern No.= A to H.	Press the [↓] key three times.							
Pattern No. selection mode	Press the [1] key four times the normal mode.	from	P. 5 F F. L	*The pattern No. selection mode will be entered.	Press the [↓] key four times.							
Program mode [P]	While holding down the [↓] key, press the [↑] key for 2 seconds or more from the normal mode.		H 4 0 0 0	*The display will flicker.  *The program mode [P] will be entered. Switch the function item with the [↓] or [↑] key.	Press down [↓] key, press [↑] key.							
Program mode [A]	While holding down the [↓] key, press the [A] key for 2 seconds or more from the normal mode.		6 R . L	*The display will flicker.  *The program mode [A] will be entered. Switch the function item with the [↓] or [↑] key.	Press down [↓] key, press [↑] key.							
Program mode [B]	While holding down the [↓] key, press the [B] key for 2 seconds or more from the normal mode.	eration". rt section.)	Б. Р - Б 5. О	*The display will flicker.  *The program mode [B] will be entered. Switch the function item with the [↓] or [↑] key.	Press down [↓] key, press [↑] key.							
Program mode [C]	While holding down the [↓] key, press the [C] key for 2 seconds or more from the normal mode.	ed with the "Direct number call operation". (Refer to the next section.)	ted with the "Direct number call op (Refer to the ne)	sted with the "Direct number call or (Refer to the ne	be selected with the "Direct number call operation". (Refer to the next section	cted with the "Direct number call o	. R. P. S. U	*The display will flicker.  *The program mode [C] will be entered. Switch the function item with the [↓] or [↑] key.	Press down [↓] key, press [↑] key.			
Program mode [D]	While holding down the [\psi] key, press the [D] key for 2 seconds or more from the normal mode.						cted with the "Di	cted with the "Di	cted with the "Di	cted with the "Di	cted with the "Di	cted with the "Di
Program mode [E]	While holding down the [↓] key , press the [A] key and the [↑] key for 2 seconds or more from normal mode.	can also be sele	1 E	*The display will flicker.  *The program mode [E] will be entered. Switch the function item with the [↓] or [↑] key.	Press down [↓] key, press [↑] key.							
Program mode [F]	While holding down the [↓] key, press the [B] key and the [↑] key for 2 seconds or more from normal mode.	The mode	The mode	The mode can also	Switch the function item with the [\div		Press down [↓] key, press [↑] key.					
Program mode [G]	While holding down the [↓] key , press the [C] key and the [↑] key for 2 seconds or more from normal mode.		■	*The display will flicker.  *The program mode [G] will be entered. Switch the function item with the [↓] or [↑] key.	Press down [↓] key, press [↑] key.							
Program mode [H]	While holding down the [↓] key , press the [D] key and the [↑] key for 2 seconds or more from normal mode.		L H H. 9 0	*The display will flicker.  *The program mode [H] will be entered. Switch the function item with the [↓] or [↑] key.	Press down [↓] key, press [↑] key.							

Program mode [J]	While holding down the [↓] key, press the [↑] key and the [A] and the [B] key for 2 seconds or more from normal mode.	reration". rt section.)	Π R C. o F	*The display will flicker.  *The program mode [J] will be entered. Switch the function item with the [↓] or [↑] key.	Press down [↓] key, press [↑] key.
Program mode [K]	While holding down the [↓] key, press the [↑] key and the [A] and the [C] key for 2 seconds or more from normal mode.	ed number call operation". (Refer to the next section.)	P 2 1 0 F	*The display will flicker.  *The program mode [K] will be entered. Switch the function item with the [↓] or [↑] key.	Press down [↓] key, press [↑] key.
Program mode [O]	While holding down the [↓] key, press the [↑] key and the [B] and the [D] key for 2 seconds or more from normal mode.	The mode can also be selected with the "Direct number call operation". (Refer to the next section	1 R 1 n o	*The display will flicker.  *The program mode [O] will be entered. Switch the function item with the [↓] or [↑] key.	Press down [↓] key, press [↑] key.
Program mode [Q]	While holding down the [↓] key , press the [A] key and the [C] key for 2 seconds or more from normal mode.	can also be sele	U C S. o F	*The display will flicker.  *The program mode [Q] will be entered. Switch the function item with the [↓] or [↑] key.	Press down [↓] key, press [↑] key.
Program mode [S]	While holding down the [↓] key , press the [B] key and the [D] key for 2 seconds or more from normal mode.		■	*The display will flicker.  *The program mode [S] will be entered. Switch the function item with the [↓] or [↑] key.	Press down [↓] key, press [↑] key.
Program mode [I]	While holding down the [↓] press the [↑] key and the [E the [C] key for 2 seconds of from normal mode.	] and	5 R U E I.	*The display will flicker.  *The program mode [I] will be entered.	Press [D] key for 2 seconds or more. [*1]
Program mode [R]	While holding down the [↓] key, press the [B] and the [C] key for 2 seconds or more from normal mode.		■	*The display will flicker.  *The program mode [R] will be entered.	Press [D] key for 2 seconds or more. [*1]
Program mode [1] Simple setting	While holding down the [↓] press the [A] and the [B] ke seconds or more from norm mode.	y for 2	2800	*The display will flicker.  *The program mode [1] will be entered. Switch the function item with the [↓] or [↑] key.	Press [D] key for 2 seconds or more. [*1]
Program mode [2] Simple setting	While holding down the [↓] key, press the [C] and the [D] key for 2 seconds or more from normal mode.		P - 2	*The display will flicker.  *The program mode [2] will be entered. Switch the function item with the [↓] or [↑] key.	Press [D] key for 2 seconds or more. [*1]
Program mode [3] Simple setting	While holding down the [\display] press the [A] and the [D] ke seconds or more from norm mode.	y for 2 nal	d 6 9 7 I	*The display will flicker.  *The program mode [3] will be entered. Switch the function item with the [↓] or [↑] key.	Press [D] key for 2 seconds or more. [*1]

<sup>[\*1]</sup> To return to the normal mode without executing each function in mode [I], [R], [1], [2]or [3], press the [\$\dgree\$] and [\$\\uparrow\$] keys simultaneously.

(3) Direct number call function (Directly selecting program mode function item from normal mode) The number of each function listed in section "23 Function list" can be directly designated to call the function item. [Basic procedures] (1) (The normal mode) in the normal mode and switch to the number selection mode. Enter (2) (1000th) (100th) (10th) (1st place) (The number 0 selection mode) Press the keys to display the target function item number. (To use the above "+/-" key as a "-" key, press while holding down When the target function item number appears, (3)press (Number 33 is called out in this example.) This completes calling of the function item. (In this example, function name [AT.] was called out.) 13 Function list Function No. Maximum speed 0000 0001 Low speed ÷ Thread trimming protection signal (S6) logical 0032 ΑT [Miscellaneous/Precautions] - Press to return to the normal mode. The display will return in the order of [Function item]  $\rightarrow$  [number selection mode]  $\rightarrow$  [normal mode]. after changing the setting for each function item. - Press The display LED will flicker, and after the changed items are set, the mode will change to the [number selection mode]. (The changed items will be canceled if the normal mode is returned to without pressing - The display LED will flicker if a function number that does not exist is displayed. Select a number that exists. entering the [number selection - The range of the number designation can be limited as shown below by pressing

- mode] and then pressing the
  - (1) Selection of number for each mode (P, A, B, C...)



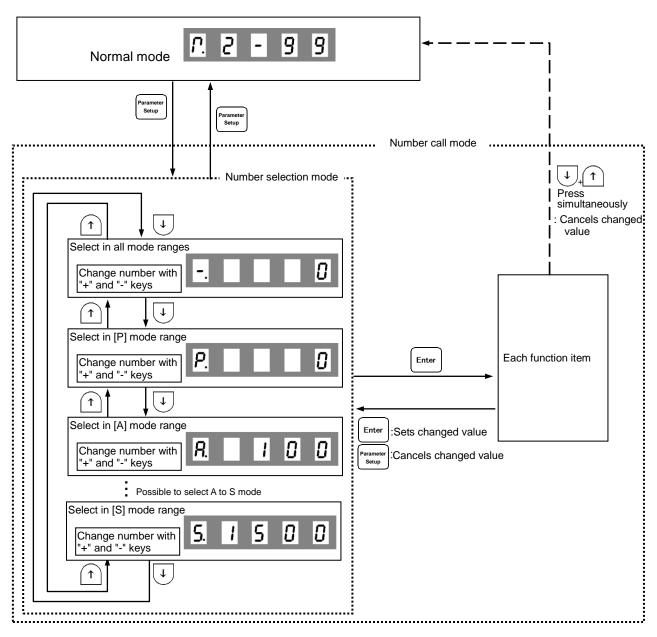
(Selection can be made in A mode range)

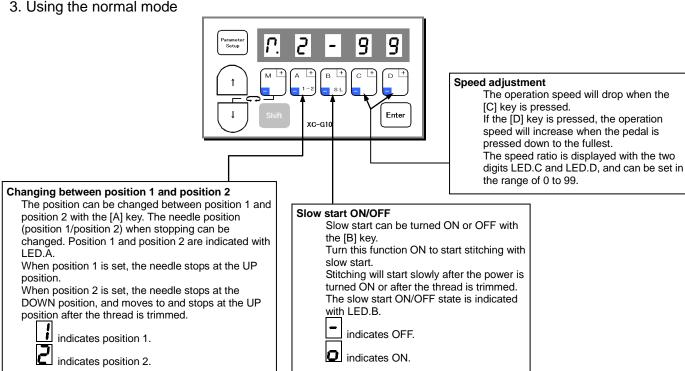
(2) Selection of all mode numbers



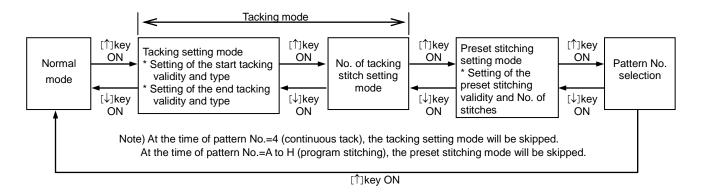
(Selection can be made in all mode ranges)

\* Refer to the status transition diagram given on the next page.



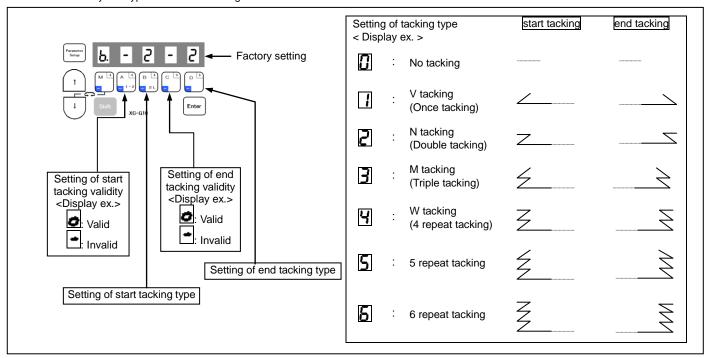


# 4. Changing to the tacking, preset, pattern NO. selection mode



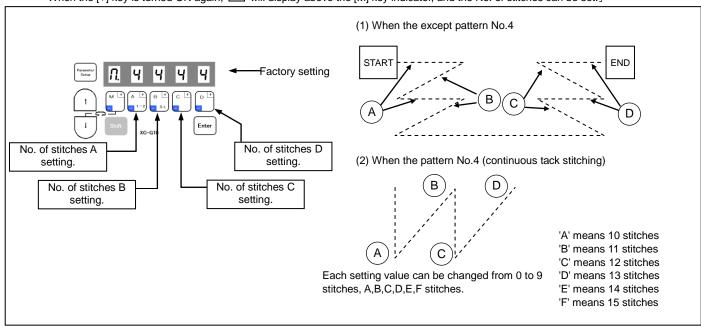
# (1) Tacking setting mode (At the time of pattern No.=4, this mode will be skipped.)

When the [↑] key is turned ON, will display above the [M] key, and the tacking setting mode will be entered. The validity and type of start and tacking can be set here.



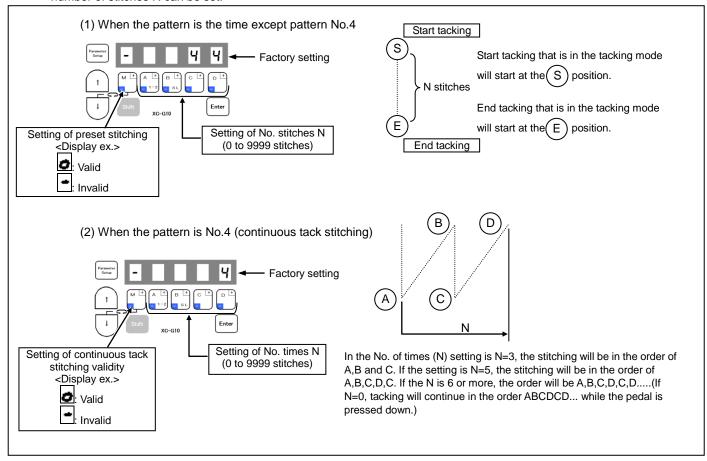
# (2) No. of tacking stitches setting mode

When the [↑] key is turned ON again, iil will display above the [M] key indicator, and the No. of stitches can be set.]



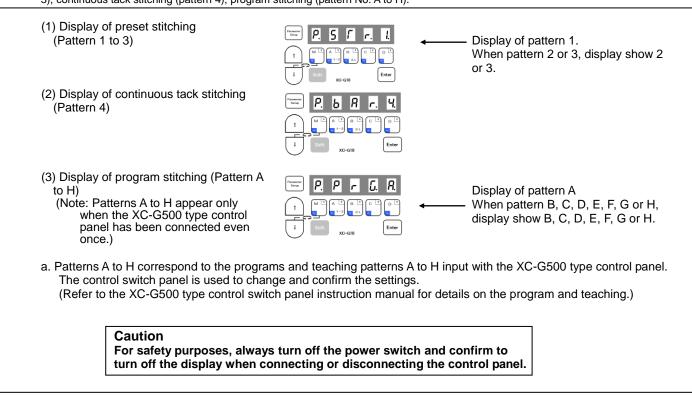
# (3) Preset stitching setting mode

The preset stitching setting mode is entered when the [↑] key is turned ON again. The validity of preset stitching and the number of stitches N can be set.



# (4) Pattern No. selection mode

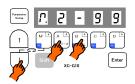
When the [↑] key is turned ON again, and the pattern No. selection mode will be entered. Selecting of preset stitching setting (pattern 1 to 3), continuous tack stitching (pattern 4), program stitching (pattern No. A to H).



# 5. Using the program mode [1] simple setting

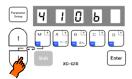
To set the settings to a specific machine in simple setting. (For example, to set to "LU2-4410-B1T" ... Function setting [410B])

(1)



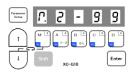
\*Enter the program mode [1].  $([\downarrow] + [A] + [B] \text{ keys})$ 

(3)



\*Press the  $[\downarrow]$  key or  $[\uparrow]$  key to change the function to [410B].

(5)

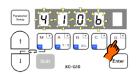


\*The mode will return to the normal mode when the [D] key is held down over two seconds or more. (This completes the settings.)



\*The mode will change to the program mode [1].





\*When the [D] key is held down, [410B] will flicker, and the changes to the setting will be set.

# Description

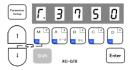
- A. Select the function name corresponding to the sewing machine model from the following simple setting table. The item will change sequentially each time the  $[\downarrow]$  or  $[\uparrow]$  key is pressed in step (3). (The factory setting is [280M].)
- B. After selecting the function name, holds down the [D] key over 2 seconds or more. The function name's set speed and function setting will be set automatically. To return to the normal mode without setting the function name here, press the [ $\uparrow$ ] key while holding down the [ $\downarrow$ ] key.

## Caution

When this function is set, all previously set details will be cleared. The set speed and function setting corresponding to the selected sewing machine model will be set automatically.

- C. The set function settings (simple setting value (type)) can be confirmed with the function name corresponding to the set sewing machine model using the following procedures (E mode).
  - (1) Call out the program mode [E] function [T]. (The mode can also be called out directly with a number[772]. Refer to pages 17 to 20.)

(2)



The function name corresponding to the set sewing machine model will appear.

(For example when [3750] is set.)

(3) Return to the normal mode.

(Press [↓]+[↑] or Parameter Setup

# Simple setting table for Mitsubishi thread trimming sewing machine and motor pulley outside diameter.

					S	peed settin	g		Fun	ction sett	ing	Motor	
	Function name	Digital display	Sewing machine type	High speed (H)	Low speed (L)	Thread trimming speed (T)	Start tacking speed (N)	End tacking speed (V)	D mode tack alignment (BM)	A mode weak brake (BK)	A mode gain selection (GA)	pulley outside diameter (mm)	
*3 I	280M	280N	LS2-1280-M1T (W)	4000	250	200	1700	1700	OFF	OFF	L		*1
	280H	580H	LS2-1280-H1T(W)	3000	250	200	1200	1200	OFF	OFF	L		
	280B	580P	LS2-1280-B1T	3000	250	200	1200	1200	OFF	OFF	L		
•	380M	380N	LS2-1380-M1T(W)	4000	250	200	1700	1700	OFF	OFF	L		
	380H	380x	LS2-1380-H1T(W)	3000	250	200	1200	1200	OFF	OFF	L		
	380B	3806	LS2-1380-B1T	3000	250	200	1200	1200	OFF	OFF	L	85	
	210M	5 10N	LS2-2210-M1T(W)	4000	250	200	1700	1700	OFF	OFF	L		
	230M	230N	LT2-2230-M1TW	3700	250	175	1200	1200	OFF	OFF	Н		
	230B	530P	LT2-2230-B1T	3000	250	175	1200	1200	OFF	OFF	Н		
	250M	2500	LT2-2250-M1TW	3000	250	175	1200	1200	OFF	OFF	Н		
	250B	250b	LT2-2250-B1T	3000	250	175	1200	1200	OFF	OFF	Н		
	3310	33 10	LY2-3310-B1T	2000	250	225	700	700	ON	OFF	Н		
	3319	33 !9	LY2-3319-B1T	2000	250	225	700	700	ON	OFF	Н		*2
	3750	3750	LY2-3750-B1T	2000	250	200	700	700	ON	OFF	L		
	6840	5840	LY3-6840-B0T	2000	250	150	700	700	ON	OFF	Н	65	
	6850	585O	LY3-6850-B1T	2000	250	150	700	700	ON	OFF	L		
	410B	7 IOP	LU2-4410-B1T	2000	250	175	700	700	ON	OFF	L		
*8	412B	7.5P	LU2-4412-B1T	2000	250	175	700	700	ON	OFF	L		
	430B	430b	LU2-4430-B1T	2000	250	175	700	700	ON	OFF	L		
	4650	4650	LU2-4650-B1T	3000	250	175	700	700	ON	OFF	L		
*8	4652	4852	LU2-4652-B1T	3000	250	175	700	700	ON	OFF	L	85	
	4710	47 IO	LU2-4710-B1T	3000	250	175	700	700	ON	OFF	L	85	
	4730	4730	LU2-4730-B1T	2500	250	175	700	700	ON	OFF	L		
	630	<i>630</i>	LX2-630-M1	800	280	160	500	500	ON	ON	L	65	
٨	280E	280E	LS2-1280-M1T(W)	5000	250	200	1700	1700	OFF	OFF	Н	110	
	FL	FL	*5	5000	250	200	1700	1700	OFF	OFF	L		
	N	ú	*6	5000	250	200	1700	1700	OFF	OFF	L		
'	LOAD2	rods	*7										
*4	LOAD1	Lod!	*7										

<sup>\*1</sup> Factory setting is [280M].

(Note: In case of LY2-3310/3319/3750 it is 80 mm, LU2-4410/4412/4430/4650/4652/4710/4730 it is 85 mm.)

<sup>\*2</sup> The effective diameter of the sewing machine pulley is 70 mm.

<sup>\*3</sup>  $\dot{}$  A function name is displayed in order to the direction of  $[\downarrow]$  every time it presses a  $[\downarrow]$  key.

<sup>\*4</sup> A function name is displayed in order to the direction of [1] every time it presses a [1] key.

<sup>\*5</sup> For sewing machine with foot lifter, without thread trimmer.

<sup>\*6</sup> For needle positioner.

<sup>\*7</sup> It is possible to load the saved setting data by the function of [SAVE\*] in the program mode [1]. ( Program mode [1]:  $[\downarrow]+[\uparrow]+[B]+[C]$  key )

<sup>(</sup>The factory setting of [LOAD1] is the setting data of [412B] and the factory setting of [LOAD2] is the setting data of [280M].)

<sup>\*8</sup> The short remaining thread trimming function is set.

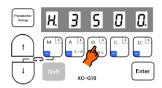
# 11 Example of setting the program mode

1. To change the maximum speed (Ex. to change to 3500 rotations) ...... Function setting [H.3500]

(1) Call out the program mode [P] function [H].

(This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "0000"))

(2)



Press the [+] and [-] keys ([A], [B], [C], [D]), and set to "3500".

(3) Entering the normal mode

For mode call:  $[\downarrow] + [\uparrow]$ 

For direct number call: Set with and then press

# Description

A. The setting range of the maximum speed is 0 to 8999 rotations.

- B. By pressing each of the [A], [B], [C] and [D] keys, the setting value will change between 0 and 9. (However, the [A] key is only between 1 and 8.) To lower the value, press the [A], [B], [C], [D] keys while holding down the [Shift] key.
- C. The factory setting is [4000 rotations].
- D. Low speed, thread trimming speed, start tacking speed, end tacking speed, medium speed and slow start speed can be set in the same manner.

Memo

The LED.D dot will flicker after the setting is changed. This indicates that the factory setting value (default value) has been changed.



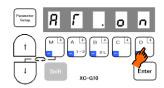
(This explanation regarding the flickering dot is omitted in the following explanations.)

2. To set the standing work type ......Function setting [AT.ON]

(1) Call out the program mode [P] function [AT].

(This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "0033"))

(2)



\*Press the [D] key and set to "ON" for the setting value.

Entering the normal mode

For mode call:  $[\downarrow] + [\uparrow]$ 

For direct number call: Set with enter and then press

# Description

A. This is used for high speed operation during standing operations.

When setting it to turning ON, it operates at the speed with the rate which has been set with the [C] and the [D] key in normal mode regardless of the pedal stepping quantity.

- B. This setting is first priority to the key switch [AUTO] of control switch panel (XC-G500 type).
- C. The setting value will alternate between [OF] and [ON] with each press of the [D] key in step (2). (The factory setting is [OF])

Note: The switches for standing operation are connected as shown on 27-3-(2) page 210. Be sure to set the function [PDS] to ON in the program mode [C] as shown on page 210.

- 3. To operate Half-stitch operation with a backstitching switch ........ Function setting [IE.UDS]
  - (1) Call out the program mode [C] function [IE].

(This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "0312"))



\*Press the [D] key and set to "UDS" for the setting value.

(3)Entering the normal mode For mode call:  $[\downarrow] + [\uparrow]$ 

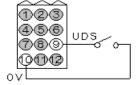
> Enter For direct number call: Set with and then press

Description

- A. Turning ON the backstitching switch connected No.9 pin in sewing machine connector, backstitching (reverse feed) will start while the sewing machine is running. Half-stitch operation will start while the sewing machine is stopped.
- B. The setting value will be changed with each press of the [D] key in step (2). (The factory setting is [S7])

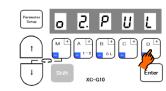
Note) When using this function, always return to the normal mode before starting operations.

sewing machine connector



- 4. Outputting puller output to spare output 02 ...... Function setting [O2.PUL] + [O2C.ON] (Example: To set to half-wave 50%duty)
  - (1) Call out the program mode [C] function [O2]. (This can be called with mode call or direct number call. Refer to

pages 17 to 20. (Direct call number = "0421"))



(2)

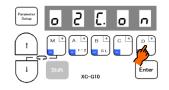
(4)

\*Press the [D] key and set to "PUL" for the setting value.

(3)Call out the program mode [C] function [O2C]

For mode call: [1]

Enter For direct number call: Set with select the number [423], and then press



\*Press the [D] key and set to "ON" for the setting value.

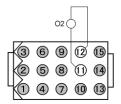
(5) Entering the normal mode For mode call:  $[\downarrow] + [\uparrow]$ 

For direct number call: Set with and then press

Description

A. Select puller output [PUL]. Set to connect [O2] and [PUL].

B. The spare output O2 turns ON only when the presser foot lifter is operating.



- 5. To confirm the position where the needle passed through the fabricated to raise the penetration strength of the first stitch with the external switch. ....... function setting [IC.BCR]
  - (1) Call out the program mode [C] function [IC].

(This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "0306"))

\*Press the [D] key and set to "BCR" for the setting value.

(3) Entering the normal mode For mode call:  $[\downarrow] + [\uparrow]$ 

For direct number call: Set with and then press

tegeription

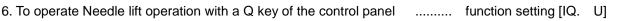
# Description

A. This is used to increase the penetration strength of the first stitch when the fabric is thick. Each time the switch [BCR] connected to the No.6 pin in the option A connector is turned ON, the (forward)-(reverse) operation will be repeated, and the needle will stop right with forward operation, above the fabric. However, when the operation signal is turned ON and the needle is stopped the sewing machine will operate forward after reversing once. When stopped with reverse operation, forward operation will start from that position.

\*The needle position stop angle is set with the needle position stop angle [C8] in the program mode [P]

B. Each time the [D] key is pressed in step 2), the set value will be changed. (factory setting is [S0])

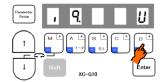
Note) When using this function, always return to the normal mode before starting operations.



(1) Call out the program mode [C] function [IQ].

(This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "0351"))

(2)



\*Press the [D] key and set to "U" for the setting value.

(3) Entering the normal mode

For mode call:  $[\downarrow] + [\uparrow]$ 

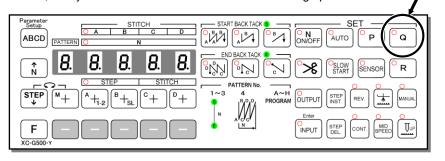
For direct number call: Set with and then press Parameter and then press

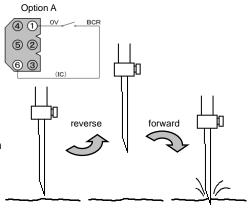
# Description

A. When the [Q] key of the control panel is pushed, the needle lift oparation will start.

B. The setting value will be changed with each press of the [D] key in step 2). (Factory setting is [NO])

Note) When using this function, always return to the normal mode before starting operations.





[Q] key

7. Setting the number of stitches to the UP position stop after fabric end is detected with optical sensor, etc.

(2)

(5)

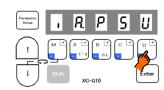
..... Function setting C mode [IA. PSU] and P mode [PSU.10]

(Example: Setting to 10 stitches)

(1) Call out the program mode [C] function [IA].

(This can be called with mode call or direct number call. Refer to pages 17 to 20.

(Direct call number = "0300"))



\* Press the [D] key and set the value to "PSU".

(3) Set the function [IA] settings.

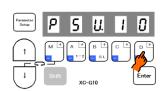
For mode call:  $[\downarrow] + [\uparrow]$ 

For direct number call: Set with

(4) Call out the program mode [P] function [PSU].

(This can be called with mode call or direct number call. Refer to pages 17 to 20.

(Direct call number = "0012"))



\* Press the [C] and [D] keys and set the value to

(6) Entering the normal mode

For mode call:  $[\downarrow] + [\uparrow]$ 

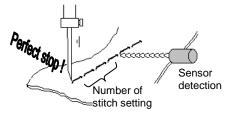
For direct number call: Set with

Enter and then press

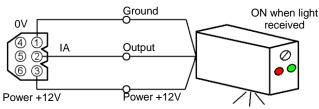
Description

A. Set both the C mode [IA] and P mode [PSU] functions.

- B. When the output from the optical sensor, etc., connects with the No. 2 pin of the option A connector and the optical sensor turns ON, the thread will be trimmed and the needle will stop at the UP position after ten stitches.
- C. The setting value will change sequentially each time the [D] key is pressed in step (2). (The factory setting is [PSU].)
- D. The number of stitch setting range is 0 to 99 stitches.
- E. The setting value will change between 0 and 9 each time the [C] and [D] keys are pressed in step (5).



# Connection example



Option A connector

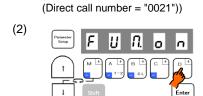
(\* Refer to the Instruction Manual enclosed with the sensor for details on handling the sensor.)

Please choose the one of the following specification to be an optical sensor.

Sensor supply source : DC12V (40mA max.) Sensor output type : NPN open collector type (Residual voltage : 0.4V max. when 5V / 2.0mA)

8. To continue pres	sser foot lifting after the thread trimming, and to bring down the presser foot after the time
	set on the timer has passed Function setting [FUM.ON]+ [FU.C]
(4)	
(1)	Call out the program mode [P] function [FUM].

(This can be called with mode call or direct number call. Refer to pages 17 to 20.

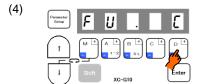


\*Press the [D] key and set to "ON" for the setting value.

(3) Call out the program mode [P] function [FU].

For mode call: [\$\dplu\$]

For direct number call: Set with enter select the direct call number "0022", and then press



\*Press the [D] key and set to "C" for the setting value.

(5) Entering the normal mode

For mode call: [↓] + [↑]

For direct number call: Set with Enter and then press

# Description

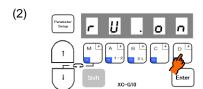
A. Set both [FUM](21) and [FU](22) functions.

- B. Each time of the [D] key is pressed in step (2), the set value will alternate between [OF] and [ON]. (The factory setting is [OF])
- C. Each time the [D] key is pressed in step (4), the set value will change in order of [M][C][A][T]. (The factory setting is [M])
- D. The timer time can be adjusted with the FUM timer setting [FCT](23) in the [C] mode. (The factory setting is 12 sec.)
- 9. When after trimming thread while sewing thick fabric, needle is stuck and fabric cannot be removed ....... Function setting [RU.ON]
  - (1)

    Call out the program mode [P] function [RU].

    (This can be called with mode call or direct number call. Refer to pages 17 to 20.

    (Direct call number = "0036"))



\* Press the [D] key and set the value to "ON".

(3) Entering the normal mode

For mode call: [↓] + [↑]

For direct number call: Set with Enter and then press Parameter Setup

# Description

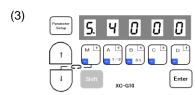
- A. After the thread is trimmed, the motor is run in reverse, and the needle is stopped near the needle bar top dead center. The reverse run angle can be set with [R8] in two-degree increments between 0 and 500. (The factory setting is [30 degrees].) [R8] can be set by pressing the [↓] key after setting the [RU] function in step (2).
- B. The setting value will alternate between [OF] and [ON] each time the [D] key is pressed in step (2). (The factory setting is [OF].)

10. To display the rotation speed on the control switch panel ...... Function setting [S.\*\*\*\*]

(1) Call out the program mode [B] function [S].

(This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "0200"))

\* The rotation speed is indicated as "0" when the sewing machine stops.



\* For example, if the maximum speed setting is 4000 rotations, the displayed speed will be [S.4000] when the pedal is fully toed down as shown above.

(4) Return to the normal mode after confirming

For mode call:  $[\downarrow] + [\uparrow]$ 

For direct number call: Press twice.

# Description

A. The rotational speed at which the sewing machine is in running is displayed.

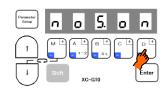
B. If the speed differs from the predicted speed, check the P mode's maximum speed setting [H.] or the speed adjustment setting for the normal mode.

11. To run without the detector ( when the detector is broken ) ......... function setting [NOS.ON]

Call out the program mode [A] function [NOS].

(This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "0112"))

(2)



\* Press the [D] key and set the value to "ON".

(3) Entering the normal mode

For mode call:  $[\downarrow] + [\uparrow]$ For direct number call: Set with and then press Parameter setup

# Description

A. Only variable-speed operation will be possible. Set position stopping and thread trimming will not be possible

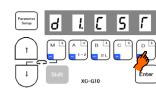
B. Each time the [D] key is pressed, the setting will alternate between [OF] and [ON]

# 12. To adjust the tacking accurately

(1) To adjust tacking surely ........ Function setting [D1. CST] + [CT. 10] (To set the stop time at each tacking corner to 100 msec.)

(1) Call out the program mode [D] function [D1].

(This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "0600"))



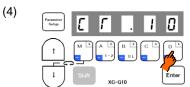
(2)

\*Press the [D] key and set to "CST" for the setting value.

(3) Call out the program mode [D] function [CT].

For mode call: [\$\sqrt{}\$]

For direct number call: Set with \_\_\_\_\_\_, select the number \_\_\_\_\_\_, and then press \_\_\_\_\_\_.



\*Press the [C], [D] key and set to "10" for the setting value.

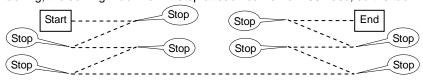
(5) Entering the normal mode

For mode call:  $[\downarrow]$  +  $[\uparrow]$ For direct number call: Set with and then press Parameter Setup

# Description

A. Set the start/end tacking and No. of switches with Page 21 before making the above setting.

B. When using W tacking, the sewing machine will stop at each corner for 100msec, so the tacking is surely executed.

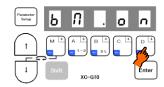


- C. Each time the [D] key is pressed in step (2), the setting will change in the order of [M], [D], [N], [CST], [CSU] and [CSD]. (The factory setting is [M])
- D. The setting range of the stop time is 0 to 990 msec. in 10-msec. intervals. The setting display 10 refers to 100 msec., and 20 to 200 msec. . (The factory setting is 50 msec.)
- E. The setting value will change between 0 and 9 each time the [C] and [D] key is pressed in step (4). To lower the value, press the [C] or [D] key while holding down the [Shift] key.
  - (2) To align tacking when start/end tacking speed is less than 1000 rpm. ....... Function setting [BM. ON]

(1) Call out the program mode [D] function [BM].

(This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "0603"))

(2)



\*Press the [D] key and set to "ON" for the setting value.

(3) Entering the normal mode For mode call:  $[\downarrow] + [\uparrow]$ 

For direct number call: Set with and then press

# Description

A. Set function [BM] to [ON] when start/end tacking speed is less than 1000rpm

- B. Set function [BM] to [OF] when start/end tacking speed is 1000rpm or higher. This BM function can be used for a rough tacking alignment of the start and end tacking.
- C. Each time the [D] key is pressed in step (2), the setting will alternate between [OF] and [ON]. (The factory setting is [OF].)

Note) This function can be used for normal tacking (not to stop at each corner).

When the function setting [D1. CST] is set, this function setting [BM. ON] will be invalidated.

13	Application	example	of the	tacking	function
ıo.	Application	CAUTIPIC	OI LIIC	tacking	IUIICUOII

(1) To adjust tacking accurately by the stop time at each tacking corner to short time

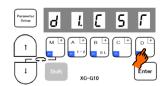
. [D1. CST] + [CT. 1]

(To set the stop time at each tacking corner to 10 msec.)

(1) Call out the program mode [D] function [D1].

(This can be called with mode call or direct number call. Refer to pages 17 to 20.

(Direct call number = "0600"))



(2)

(4)

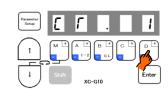
\*Press the [D] key and set to "CST" for the setting value.

(3) Call out the program mode [D] function [CT].

For mode call: [↓]

For direct number call: Set with \_\_\_\_\_, select the number

"0602", and then press



\*Press the [C], [D] key and set to "1" for the setting value.

(5) Entering the normal mode

For mode call:  $[\downarrow] + [\uparrow]$ 

For direct number call: Set with

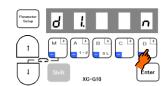
Enter and then press Parameter Setup

# Description

- A. Set the type of start/end tacking and the no.of stitches before making the above setting. (Refer to page 21)
- B. This setting is good for adjust tacking accurately.
- C. Each time the [D] key is pressed in step 2), the setting will change in the order of [M], [D], [N], [CST], [CSU] and [CSD]. (factory setting is [M])
- D. The setting range of the stop time is 0 to 990 milliseconds in 10-millisecond intervals. The setting display 1 refers to 10 milliseconds, and 10 to 100 milliseconds. (factory setting is 50 milliseconds)
- E. Each time the [C] key is pressed in the step 6), the set value will change from 0 to 9, and each time the [D] key is pressed, will change from 0 to 9.
  - (2) To be continuous sewing the next straight line stitching without speed down when start tacking is completed. ...... function setting [D1. N]
    - (1) Call out the program mode [D] function [D1].

(This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "0600"))

(2)



\*Press the [D] key and set to "N" for the setting value.

(3) Entering the normal mode

For mode call:  $[\downarrow] + [\uparrow]$ 

For direct number call: Set with and then press

# Description

- A. This function is available when the start tacking speed is high.
- B. It can be continuous sewing the next straight line stitching without speed down when start tacking is completed. This is valid when the Operation mode during start tack completion D2 is ICONI.
- C. Each time the [D] key is pressed in step 3), the setting will change in the order of [M], [D], [N], [CST], [CSU] and [CSD]. (factory setting is [M])

14. Setting the tacking stitch correction

To correct when the set number of tacking stitches does not match the number of actual stitches ......Function setting [BT1.4] + [BT2.4] + [BT3.8]

(To stitch three start and end tacking stitches (Fig. 1), but actual stitches as shown in (Fig. 2).)

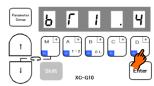
(1) Call out the program mode [D] functions [BT1] to [BT4].

(This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = from "0604" to "0606"))

- Confirm that [BT1] to [BT4] are all set to "0". If not set to "0", reset to "0", and then stitch to check the number of tacking stitches. (If the stitches does not match, correct with the following steps.)
- In Fig.2, there are four stitches at the forward section of the start tacking. Since there is one extra stitch, decrement the number of correction stitches by 1. (Point A)

Call out the program mode [D] function [BT1].

(This can be called with mode call or direct number call "604". Refer to pages 17 to 20.)



In the following table, the number of correction stitches "-1" corresponds to 4. Set [BT1] to 4.

After (3) is set (Fig. 3), there will be one less stitch at the forward section. The backward section is then incremented by one stitch for a total of four stitches. Decrement the number of correction stitches by 1. (Point B)

# Call out the program mode [D] function [BT2].

For mode call: [\$\frac{1}{2}\$]

For direct number call: Set with select the number "605", and then press

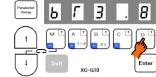
In the following table, the number of correction stitches "-1" corresponds to 4. Set [BT2] to 4. (This completes correction of the start tacking section.)

In Fig. 4, the backward section of the end tacking has five stitches, which is two stitches over. Decrement the number of correction stitches by 2. (Point

# Call out the program mode [D] function [BT3].

For mode call: [\]

select the number "606", and then For direct number call: Set with press

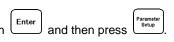


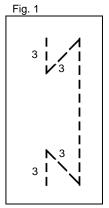
In the following table, the number of correction stitches "-2" corresponds to 8. Set [BT3] to 8. (The backward section now has three stitches. The forward section is increased to two stitches for a total of three stitches.) (Fig. 1)

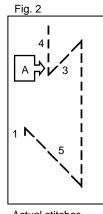
#### (6) Entering the normal mode

For mode call:  $[\downarrow] + [\uparrow]$ 

For direct number call: Set with

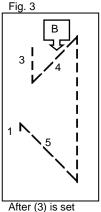


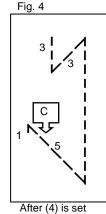


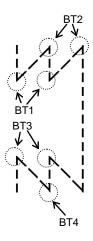


Set stitches

Actual stitches







- BT1: Correction for forward start tacking. BT2: Correction for backward start tacking.
- BT3: Correction for backward end tacking.
- BT4: Correction for forward end tacking.

Relation of number of correction stitches and setting value

	Relation of number of correction stitches and setting value															
Setting value	9	8	7	6	5	4	3	2	1	0	Α	В	C	D	Е	F
Number of correction stitches	-2 <sup>1</sup> / <sub>4</sub>	-2	-1 <sup>3</sup> / <sub>4</sub>	-1 <sup>2</sup> / <sub>4</sub>	-1 <sup>1</sup> / <sub>4</sub>	-1	- <sup>3</sup> / <sub>4</sub>	-2/4	-1/4	0	+1/4	+2/4	+3/4	+1	+1 <sup>1</sup> / <sub>4</sub>	+12/4

# 15. Example of setting counter function (1) UP counter for product amount (one hundred times) [1] Up counter amount "U" is add at each thread trimming. [2] When up counter amount "U" become the setting amount "P", sewing will be prohibited. [3] When the input signal "I1" is turned on, Up counter amount become zero and sewing become possible. (1) (2)Call out the program mode [C] function [I1]. (This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "0357")) \* Press the [D] key and set the value to "CCU". (3) Set the function [I1]. For mode call: $[\downarrow] + [\uparrow]$ For direct number call: Set with (4) (5)Call out the program mode [B] function [P]. (This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "0203")) Press the [A] to [D] keys and set the value to "100". (6)(7)Call out the program mode [B] function [CUP]. For mode call: [\d] For direct number call: Set with select number [205], and Enter \* Press the [D] key and set the value to "PR". then press (8) Call out the program mode [B] function [UPC]. (9)For mode call: [\$\frac{1}{2}\$] For direct number call: Set with select number [208], and \* Press the [D] key and set the value to "ON". then press

Call out the program mode [B] function [PRN].

For mode call: [\dot]

For direct number call: Set with select number [216], and then press

(12)Entering the normal mode For mode call:  $[\downarrow] + [\uparrow]$ 

For direct number call: Set with and then press

(11)

\* Press the [D] key and set the value to "1".

Note) [P] key function selection (Factory setting is [CCU].)[C] mode [IP]=[CCU] : Clear UP counter (counter with control panel [P] key clearness)

# Description

[C] mode function selection

[I1.CCU]: Input signal "I1" is set to UP counter clear function.

[B] mode function selection

[P. 100] Set the setting amount of up counter "P". This amount become the target amount for up counter.

\*[U. 0] Current up counter amount "0"

[ CUP.PR]: "PRN" function is that up counter is added at each trimming time.

("PRN" is set "1", up counter is added each trimming time in this example )

\*[USC. ST]:When the amount of current up counter "U" become setting amount "P", sewing will be prohibited Input signal "I1" is set to the following function. When it is turned on, sewing become possible.

[UPC.ON] Set "UPC" to "ON" to use up counter.

[PRN. 1] one trimming time add one count amount.

Items marked with an asterisk \* are the factory settings.

- (2) When using down counter as a bobbin thread level counter (Ending count after 10,000 stitches)
  - [1] The current down counter value [D] is decremented by one each time ten stitches are stitched.
  - [2] When the remaining down counter [D] reaches 0, stitching is prohibited after trimming (Stitching is possible until the thread is trimmed.)
  - [3] When the external switch I1, set with the [C] mode function selection, turns ON, the current down counter value [D] value is set to the down counter value [N], and the next stitching is enabled.

#### (1) (2)Call out the program mode [C] function [I1]. (This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "0357")) Press the [D] key and set the value to "CCD". (3)Set the function [I1] For mode call: $[\downarrow]$ + $[\uparrow]$ Enter For direct number call: Set with (4) (5)Call out the program mode [B] function [N]. (This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "0201")) Press the [A] to [D] keys and set the value to "1000". (6)Call out the program mode [B] function [D] (7) d. 1 0 0 0 For mode call: [1] Enter For direct number call: Set with select number [202], and Enter Press the [A] to [D] keys and set the value to "1000". then press (8) (9)Call out the program mode [B] function [CDN]. For mode call: [1] For direct number call: Set with select number [210], and Enter \* Press the [D] key and set the value to "ST". then press (10)(11)Call out the program mode [B] function [DNC] For mode call: [\dot] Enter select number [213], and For direct number call: Set with Enter Press the [D] key and set the value to "ON". then press

(12) Call out the program mode [B] function [CNU].

For mode call: [↓]
For direct number call: Set with Enter, select number [217], and then press Enter.

(13) Property [ n U I O

\* Press the [C] and [D] keys and set the value to "10".

(14) Entering the normal mode

For mode call:  $[\downarrow] + [\uparrow]$ 

For direct number call: Set with

Enter and then press Parameter Setup

Note) To clear the down counter with the P key on the control switch panel set the following.

[C] mode function selection

[IP.CCD]: Sets the P key on the control switch panel to the counter clear signal [CCD].

## Description

[C] mode function selection

[I1.CCD]: Sets the external input I1 to the counter clear signal [CCD].

[B] mode function selectior

[N.1000]: Sets the down counter value. The down counter counts (subtracts) from the value set here.

[D.1000]: Current down counter value.

[CDN.ST]: The down counter is decremented by one each time the number of stitches set in [CNU] is stitched. (In this example, [CNU] is set to 10, so the down counter is decremented by one each time 10 stitches are stitched.)

\* [DSC.ST]: When the current down counter [D] reaches 0, the next stitching is prohibited after trimming. The next stitching is enabled when the external input I1, set with [C] mode function selection, turns ON.

[DNC. ON]: Down counter is validated. Set this to ON to use the down counter.

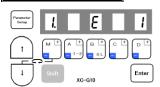
[CNU.10]: Set this to count every 10 stitches.

Items marked with an asterisk \* are the factory settings.

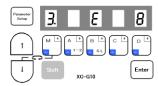
- 16. To check the error code history and input/output signal
  - (1) How to view the error code history ......... Function setting [1.E--], [2.E--], [3.E--], [4.E--]
- (1) Call out the program mode [E] function [1].

(This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "0700"))

(2) Call out function [1].



- \* The last error code is displayed. (Ex. error code E1 is displayed.)
- (4) Call out function [3].



- \* The error code before the second is displayed. (Ex. error code E8 is displayed.)
- (6) Entering the normal mode

For mode call:  $[\downarrow] + [\uparrow]$ 

For direct number call: Press

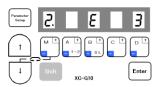


#### Description

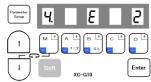
A. 4 times errors from the last to the fourth error can be viewed.

B. Refer to page 211 for the error code.

(3) Call out function [2].



- \* The error code before the last is displayed. (Ex. error code E3 is displayed.)
- (5) Call out function [4].



\* The error code before the third is displayed. (Ex. error code E2 is displayed.)

(2) To check input signals

(1) Call out the input signal in program mode [E] to be checked. (In this example, call out [IA].)

(This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "0706"))

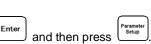
- \* Turn the input for the input terminal to be viewed ON and OFF, and confirm that the LED C.D changes between [ON] and [OF].
- \* If the input to be viewed is UP or DN, turn the sewing machine shaft. If ECA or ECB, turn the motor shaft.

Caution To turn the signals related to the sewing machine operation ON and OFF when the signal is turned ON and OFF, normal operation will take place.

(3) Entering the normal mode

For mode call:  $[\downarrow] + [\uparrow]$ 

For direct number call: Set with



Input signal (Factory setting)	Display
Variable speed run signal (S1)	IG
Thread trimming (S2)	IH
Presser foot lifter (S3)	II
Presser foot lifter signal (F)	IF
Thread trimmer cancel signal (TL)	ID
Backstiting signal (S7)	IE
Needle UP position priority stop signal (PSU)	al IA
Needle DOWN position priority stop signal (PSD)	IB
Low speed run signal (S0)	IC
Input signal (IO1)	I1
Needle lift signal (U)	l2
No setting (NO)	14
No setting (NO)	15
Encoder signal display (A phase)	ECA
Encoder signal display (B phase)	ECB
Detector signal display (UP signal)	UP
Detector signal display (DOWN signa	al) DN
Display the angle from down position	DR DR
Display the voltage of VC	VC
Display the voltage of VC2	V2

# Description

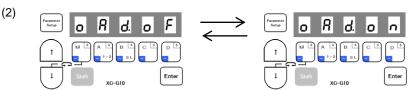
- A. It is possible to check whether or not input signal is wired right.
  - When the display is not turned [ON][OF] even if the signal is turned ON/OFF, check wiring to a control box from the signal. Note that the sewing machine will run when checking the input of signal terminals related to operation.
- B. Refer to the "Connector layout" on page 208 for the input terminals, and "Table of input/output function for signal on C mode" on page 199 for details on the input function names.

(3) To check output signal (check in operation)

........... Function setting [OAD] - [ODD], [OFD], [OPD] - [ORD], [O1D] - [O7D]

(1) Call out the output signal in program mode [E] to be checked. (In this example, call out [OAD].)

(This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "737"))



\*Confirm the display ON during full pedal heeling operation

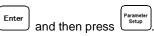
Caution Be careful to sewing machine operation when turned ON the signal which the sewing machine operation relates to.

ean named = 707 ))						
Output signal (Factory setting)	Display					
Thread trimming output (T)	OAD					
Wiper output (W)	OBD					
Backstitch output (B)	OCD					
Thread release output (L)	ODD					
Presser foot lifter output (FU)	OFD					
O1 output (OT1)	O1D					
Output for needle cooler (NCL)	O2D					
TF output (TF)	O3D					

(3) Entering the normal mode

For mode call:  $[\downarrow] + [\uparrow]$ 

For direct number call: Set with



# Description

A. This is useful for setting the various items and checking the operation before connecting the output to the solenoid, etc.

B. Refer to the "Connector Layout" on page 208 for the output terminals, and "Table of input/output function for signal on C mode" on page 199 for details on the output function names.

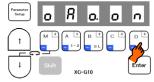
(4)To check an output terminal (To forcibly turn the output ON without running the sewing machine.)
.......... Function setting [OAO] - [ODO], [OFO], [OPO] - [ORO], [O1O] - [O7O]

(1) Call out the output signal in program mode [E] to be checked. (In this example, call out [OAO].)

(This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "752")

Permeter O R O F

1 Shift Enter



\* Output signal is turned ON while pressing the [D] key. Note) While displaying this function, sewing machine can not operate.

Output signal (Factory setting)	Display
Thread trimming output (T)	OAO
Wiper output (W)	OBO
Backstitch output (B)	OCO
Thread release output (L)	ODO
Presser foot lifter output (FU)	OFO
O1 output (OT1)	010
Output for needle cooler (NCL)	020
TF output (TF)	030

(3) Entering the normal mode

For mode call:  $[\downarrow] + [\uparrow]$ 

For direct number call: Set with

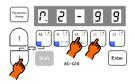
and then press

# Description

A. This is useful for checking that the wiring to the solenoid, etc., from the control box's output terminals is correct.

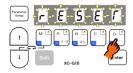
B. Refer to the "Connector Layout" on page 208 for the output terminals, and "Table of input/output function for signal on C mode" on page 199 for details on the output function names.

(1)



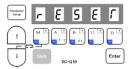
\* Enter program mode [R]  $([\downarrow] + [B] + [C] keys)$ 

(3)



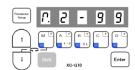
\* [RESET] will flicker when the [D] key is held down, and the reset process will be executed.

(2)



\* Program mode [R] will be entered.

(4)



\* The data will be set to the factory setting when the [D] key is pressed over 2 seconds or more, and then the normal mode will be returned to. (Process is completed)

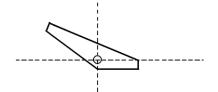
# Description

- A. All settings will be returned to the factory settings when the [D] key is held down for two or more seconds while [RESET] is displayed. The display will return to the normal mode.
- B. To return to the normal mode from the [RESET] display without executing the reset process, press the [↑] key while holding down the  $[\downarrow]$  key. In this case, the settings will not be returned to the factory setting.

# Caution

When this function is set, the contents of all settings to this point will be cleared, and will return to the factory settings. Please take care when using this function.

(1) Set the pedal (lever unit) to the neutral position.

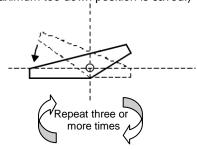


(3)

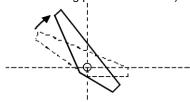


[VCSET] will flicker when the [D] key is held down.

Fully toe down the pedal (lever unit). (5) (The maximum toe down position is saved.)

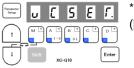


Fully heeling the pedal (lever unit). (The maximum heeling position is saved.)



#### (2)Call out the program mode [Q] function [VCSET].

(This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "1427"))



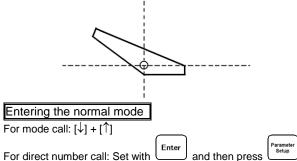
\* Enter program mode [Q]  $([\downarrow] + [A] + [C] keys)$ 

(4)



The display will change to [START]. (The neutral position is saved at this point.)

(6)Return the pedal (lever unit) to the neutral position.



# Description

The lever's neutral, toe down and heeling positions can be adjusted.

If the [D] key is held down when the pedal is at the neutral position, the display will flicker and change to the [START] display. (The neutral position is saved at that point.)

After that, repeat the pedal toe down and heeling operation three or more times. (The maximum toe down position and maximum heeling position are saved at this time.)

When finished, always return the pedal to the neutral state, and then return to the normal mode.

# Note

- To enter the [VCSET] state with mode call and then return to the normal mode, press down the  $[\downarrow]$  and  $[\uparrow]$  keys simultaneously. The lever unit's neutral, toe down and heeling positions are not adjusted in this case.
- The error "MA" will appear as shown on note 1, when the position data for the lever unit is faulty. The error "MA" is released by note 2, and confirm the neutral position of the pedal (lever unit), and then save the neutral, toe down and heeling positions again with the above steps.
- 1. The error "MA" appears as follows.
  - · When the neutral position is moved.
  - When returning to the original lever unit from external variable speed pedal or the external switches operation.
- 2. How to release the error "MA".
  - It is released after 1 msec when the pedal return the neutral position.
  - · It is released by pressing [D] key.

(1) Call out the program mode [P] function [S6L].

(This can be called with mode call or direct number call. Refer to pages 17 to 20. (Direct call number = "0032"))

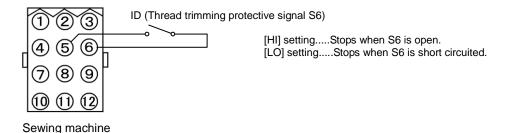
\*Press the [D] key and set to "LO" for the setting value.

(3) Entering the normal mode

For mode call:  $[\ \ ]$  +  $[\ \ ]$ For direct number call: Set with Enter and then press

# Description

- A. The setting value will alternate between [HI] and [LO] with each press of the [D] key.
- B. If the logic changeover [S6L] of the thread trimming protective signal [S6] is set to [HI], the sewing machine will stop when the signal (S6) opens (S6 turns off). This includes the constant open state. (The speed display on the control switch panel will also stop when the sewing machine stops.)
- C. If the logic changeover [S6L] of the thread trimming protective signal [S6] is set to [LO], the sewing machine will stop when the signal (S6) is short circuited (S6 turns on). This includes the constant short circuit state. (The speed display on the control switch panel will also when the sewing machine stops.)
- D. Connection example



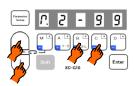
E. The simple setting value is [LO] during function settings [BR1], [RM1], [SRB1] and [JMH]. During the other function setting [YU2] ~ [YU5], [NO1] ~ [NO8],[NOC], [KA1] ~ [KA4], [UN1], [UN2], and [UN3] is [HI].

# 12 To save the setting data

1. How to use the program mode [I]

To save the setting data ............ Function setting [SAVE\*] (Two types of data, [SAVE1] and [SAVE2] can be saved. The [SAVE1] data can be read out with [LOAD1], and the [SAVE2] data with [LOAD2].)

(1)



\* Enter program mode [I] ([↓] + [↑] + [B] + [C] key)

(3)



\* When the [D] key is held down, [SAVE1.] will flicker, and the save process will be executed.



\* Program mode [I] will be entered.



\* Press [D] key over 2 seconds or more, and then the normal mode will be returned to. (Process is completed)

# Description

- A. The current setting data can be saved as simple settings. Saving the data is completed when the [D] key is held down for two or more seconds while [SAVE\*] is displayed and the display returns to the normal mode.
- B. To return to the normal mode from the [SAVE\*] display without saving the data, press the [ $\uparrow$ ] key while holding down the [ $\downarrow$ ] key. The set data will not be saved.
- C. The saved setting data is saved in the program mode {1} simple setting [LOAD1] or [LOAD2], and can be read out by selecting [LOAD1] or [LOAD2] with program mode [1].

  (As the factory setting, the [412B] data is saved in the simple settings [LOAD1] and the [280M] data is saved in the simple

settings [LOAD2].)

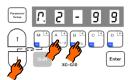
#### Caution

When this function setting [SAVE\*] is used, the settings saved in the program mode [1] simple setting [LOAD\*] before the new data was set will all be cleared. The current setting data will be newly saved in the simple setting [LOAD\*]. Check the current setting data before starting operation.

D. Reading the setting data saved with the [SAVE\*] function

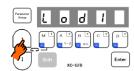
The setting data saved with the [SAVE\*] function above can be read out with the following procedure (program mode [1]).

(1)



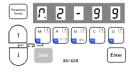
\* Enter program mode [1] ([↓]+[A]+[B] key)

(3)

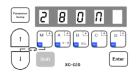


Press the [1] key and set the function to [LOAD1].

(5)

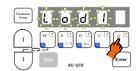


\* Press [D] key (2 seconds or more) to return to the normal mode. (Process is completed) (2)



\* Program mode [1] will be entered.

(4)



\* When the [D] key is held down, [LOAD1] will flicker, and the loading process will be executed.

1. How to use the program mode [2]

No.1 To set the functions for chain stitch sewing machine in simple setting

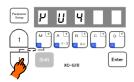
(Ex. to set for the VC2800, VC3800 class, "YAMATO").......Function setting [YU4]

(1)



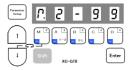
\*Enter the program mode [2].  $([\downarrow] + [C] + [D] \text{ keys})$ 

(3)

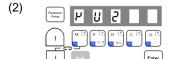


\*Press the  $[\downarrow]$  key or  $[\uparrow]$  key to change the function to [YU4].

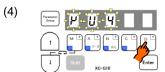
(5)



\*The mode will return to the normal mode when the [D] key is held down over two seconds or more. (This completes the settings.)



\*The mode will change to the program mode [2].



\*When the [D] key is held down, [YU4] will flicker, and the changes to the setting will be set.

### Description

- A. Select the function that corresponds to the sewing machine model for "Simple setting table for chain stitch sewing machine" on the page 43. Holds down the [D] key over 2 seconds or more, and functions will be carried out automatically for that model.(Refer to the simple setting table for "YAMATO" on page 43.)B. To return to the normal mode from the [YU4] display, press the [↑] key while holding down [↓]. In this case, [YU4] will not be set, and the last settings will be used.
- C. Each time the [ ↓ ] key is pressed in step 3, the function will change in order from [YU2], [YU3], [YU4].....[JMH].
- D. Refer to Fig.1 (page 46) for the connector input/output signals.
- E. Refer to Fig.5 (page 60) for the junction wiring.
- F. Set the solenoid voltage to 30V. Refer to page 14. (The factory setting is 24V.)
- G. Set the option A connector 5/12V setting to 12V. Refer to page 14. (The factory setting is 12V.)
- H. The thread trimming protection signal S6 will stop the sewing machine when the switch is turned OFF.

2. Simple sett													_			_		
End condensed speed V	1400	1400	1400	1400	1400	1400		1400	1400	1400	1400	1400		1400	1400		1400	1400
Start condensed speed N	1400	1400	1400	1400	1400	1400		1400	1400	1400	1400	1400		1400	1400		1400	1400
Trimming speed T	200	200	200	200	200	200		200	200	200	200	200		200	200		200	200
Low Low	200	200	200	200	200	200		200	200	200	200	200		200	200		200	200
High Speed H	6000	0009	0009	0009	0009	0009		4500	4500	4000	0009	0009		0009	0009		0009	0009
1/2 pos	2	2	2	2	1	_		7	1	1	1	~		~	~		7	1
Note 4 Setting of switch to increase solenoid return speed				*Note 6							*Note 6			0 1 1 1	o anone		*Note 6	
Note 3 Logic of thread trimming protection signal S6			9	machine	switch:open					Sewing	stops when switch:open			Sewing machine	stops when switch:open		Sewing machine stops when switch:open	
Note 2 DC5V or 12V setting in option A	12V	12V	12V	12V	5V	5V		20	5V	20	5V	5V		5V	5V		5V	5V
Note 1 solenoid voltage	30V	30V	30V	30V	24V	24V		24V	24V	24V	24V	24V		24V	24V		24V	24V
Junction wiring	Fig.50	Fig.50	Fig.50	Fig.50	Fig.51	Fig.51		Fig.51	Fig.51	Fig.52	Fig.51	Fig.51		Fig.51	Fig.51			
I/O signals of connectors	Fig.1	Fig.1	Fig.1	Fig.1	Fig.2	Fig.2		Fig.2	Fig.2	Fig.2	Fig.3	Fig.3		Fig.4	Fig.4		Fig.5	Fig.6
a)	VC2600, VC2700 class Solenoid-operated under thread trimmer	VC2600, VC2700 class Air-operated under thread trimmer with air wiper	VC3845P,2845P,2840P class Air-operated under thread trimmer with air wiper	Solenoid-operated under thread trimmer with solenoid wiper	W(T) series /UT device Pneumatic under thread trimmer with pneumatic top cover thread trimmer electric under thread trimmer	W(T) series /UT device Pneumatic under thread trimmer with pneumatic top cover thread trimmer	Do not use !!	FW series /UT device electric under thread trimmer	FW series /UT device Pneumatic under thread trimmer	W674/UT device Super tack	W(T)562-82/UT device Angled stitch electric under thread trimmer with pneumatic top cover thread trimmer	W(T)562-82/UT device Angled stitch Pneumatic under thread trimmer with pneumatic top cover thread trimmer	Do not use !!	W(T)600,200 series /UT/MS device Condensed stitch electric under thread trimmer with pneumatic top cover thread trimmer	W(T)600,200 series /UT device condensed stitch Pneumatic under thread trimmer with pneumatic top cover thread trimmer	Do not use !!	W(T)600 series /UT device Stitch lock pneumatic under thread trimmer with pneumatic top cover theread trimmer	EX/BL500,600 series
Sewing machine maker	YAMATO	YAMATO	YAMATO	YAMATO	PEGASUS	PEGASUS	PEGASUS	PEGASUS	PEGASUS	PEGASUS	PEGASUS	PEGASUS	PEGASUS	PEGASUS	PEGASUS	PEGASUS	PEGASUS	PEGASUS
Function	YU2	YU3	YU4	YU5	NO1	NO1A	NO2	NO3	NO3A	NO4	NO5	NO5A	90N	NO7	NO7A	NO8	NOD	NOF

pagu ped ped	00	90	00	00	66	66	66									00	00	00	00
End condensed speed V	1400	1400	1400	1400	2999	2999	2999									1400	1400	1700	1900
Start condensed speed N	1400	1400	1400	1400	1400	1400	1400									1400	1400	1700	1700
Trimming speed T	250	250	250	250	200	200	200									200	200	200	200
Low Speed L	250	250	250	250	200	200	200									200	200	200	200
High speed H	0009	0009	0009	0009	4000	2500	4000									0009	0009	0009	5500
1/2 pos	2	2	2	2	2	2	2									2	1	2	2
Note 4 Setting of switch to increase solenoid return speed		() () () ()	o alon		O. Con V	Set Set JP6:	2										9 O+O N*	o e e o	
Note 3 Logic of thread trimming protection signal S6		Sewing machine	stops when switch:short			machine stops when	switch.									Sewing	machine	stops when	SWITCH:SHORT
Note 2 DC5V or 12V setting in option A	12V	12V	12V	12V	12V	12V	12V									5V	5V	5V	5V
Note 1 solenoid voltage	708	30V	708	30V	Λ0ε	300	300									247	24V	24V	24V
Junction wiring	Fig.53	Fig.53	Fig.53	Fig.53	Fig.54	Fig.54	Fig.55												
I/O signals of connectors	Fig.7	Fig.7	Fig.8	Fig.7	Fig.9	Fig.10	Fig.10									Fig.11	Fig.12	Fig.13	Fig.14
Model name of sewing machine and device	M, RX series Automatic thread trimmer with solenoid wiper	D series Automatic thread trimmer with air wiper	F series Air-operated under thread trimmer with air wiper	DX series Air-operated under thread trimmer with air wiper	33700, 34500 class Solenoid-operated under thread trimmer	34800skcc class Solenoid-operated under thread trimmer	34700 class Push and Pull air-operated under thread trimmer with air wiper	Do not use !!	FD3, FD4 series			MH-481-4-4, MH-484-4-4 class							
Sewing machine maker	KANSAI	KANSAI	KANSAI	KANSAI	UNION	UNION	UNION									BROTHER	RIMOLDI	SIRUBA	JUKI
Function	KA1	KA2	KA3	KA4	UN1	UN2	NN3	U345	U346	U348	U347	U160	U16	U362	UFCW	BR1	RM1	SRB1	JMH
		l		1		<u> </u>	<u> </u>		- 44	L	l	l	1	1	l				

Note: The function name will display in the order of [YU2], [YU3], [YU4].....[NO1].....[KA1].....[UN1].....[JUN1].....[JUN1].....[JUN1].....[NU2] with each press of the [D] key. The function name will display in the order of [YU2], [JMH].....[KA1].....[KA1].....[NO1].....[YU2] with each press of the [D] key.

<sup>1.</sup> Refer to page 14 for how to change the solenoid voltage. The factory setting is 24V. 2. Refer to page 14 for how to change the option A connector DC5V/12V. The factory setting is 12V.

3. Refer to page 40 for how to change the logic of the thread trimming protection signal S6.

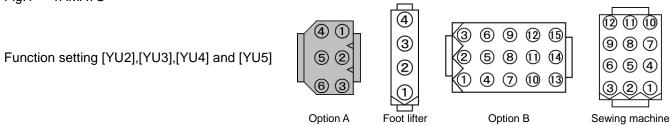
The factory setting is sewing machine stop at switch: short. (The operation of the thread trimming protection device and thread trimming protection sensor switch ON and OFF will not always match. Consult with your dealer on any unclear points.) 4. Refer to page 15 for how to set the switch to increase the solenoid return speed. Always set JP6 to FAST when [UN1], [UN2] and [UN3] are set.

The factory settings is JP6 : SLOW.

5. The chain stitch sewing machine specifications may be changes in part by the sewing machine maker. Consult with your dealer before selecting the functions from the above table. 6. If the electromagnetic solenoid is connected to the trimming output, the JP6 switch should be set to "FAST",

# 3. I/O signals of connectors

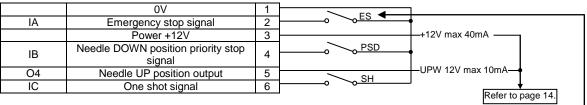
Fig.1 "YAMATO"

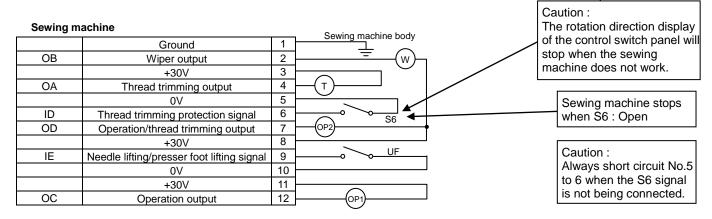


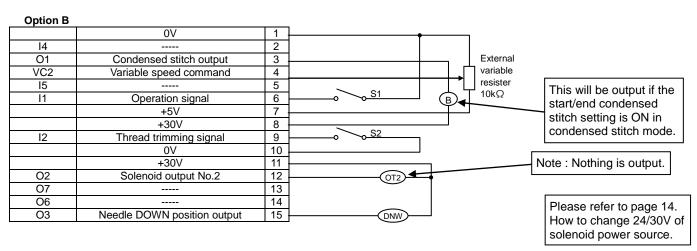
#### Presser foot lifter

	0V	1	
IF	Presser foot lifting signal	2	
OF	Presser foot lifting output +	3	(FU)————
OF OF	Presser foot lifting output -	4	

# Option A (Black connector)



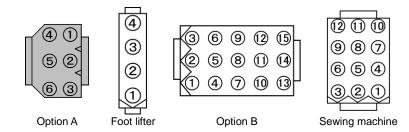




Note) The thread trimming (operation) will differ from the [YU2] to [YU5] simple settings, so select the setting value according to the sewing machine being used.

Fig.2 "PEGASUS"

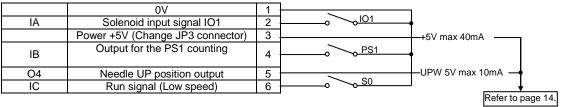
Function setting [NO1], [NO1A], [NO3], [NO3A] and [NO4]

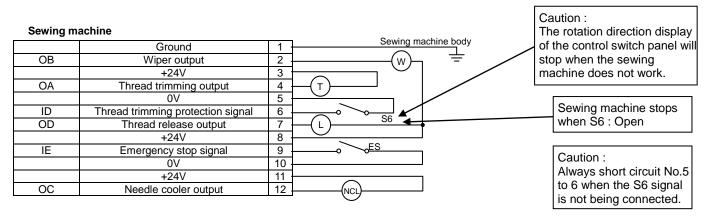


#### Presser foot lifter

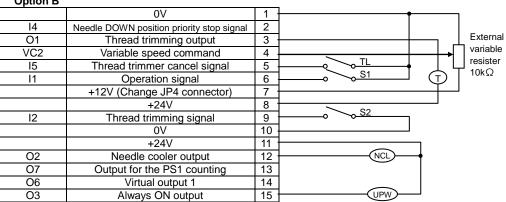
	0V	1	
IF	Presser foot lifting signal	2	
OF	Presser foot lifting output +	3	(FU)
OF	Presser foot lifting output -	4	

# Option A (Black connector)

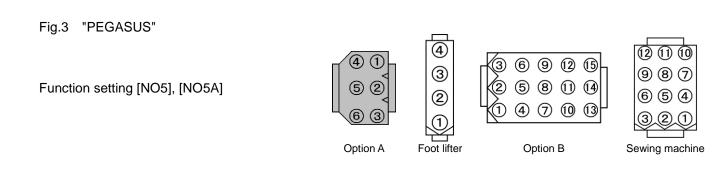




# Option B



Note) The thread trimming (operation) will differ from the [NO1] to [NO4] simple settings, so select the setting value according to the sewing machine being used.

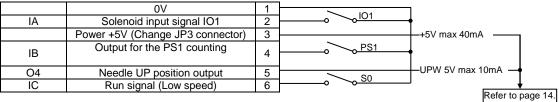


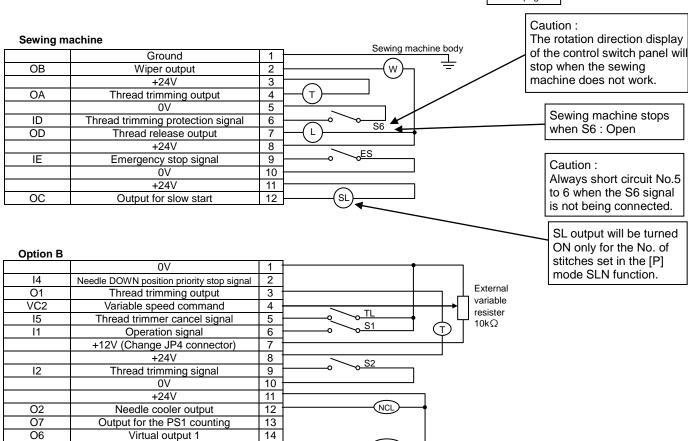
#### Presser foot lifter

О3

	21.4	4	
	0V	1	
IF	Needle lift, presser foot signal	2	
OF	Presser foot lifting output +	3	(FU)———
	Presser foot lifting output -	4	ļ

# Option A (Black connector)



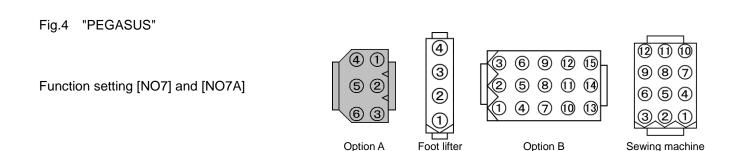


Note) The thread trimming (operation) will differ from the [NO5], [NO5A] simple settings, so select the setting value according to the sewing machine being used.

15

Always ON output

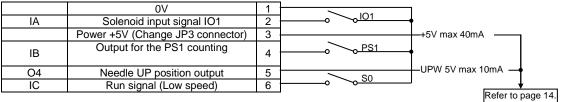
(UPW)

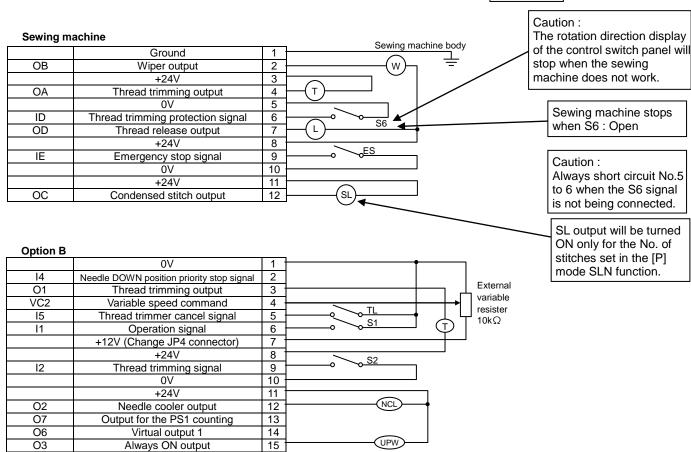


#### Presser foot lifter

	,		1
	0V	1	
IF	Presser foot lifting signal	2	
OF	Presser foot lifting output +	3	(FU)———
Oi	Presser foot lifting output -	4	

# Option A (Black connector)

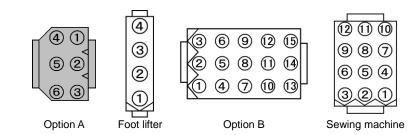




Note) The thread trimming (operation) will differ from the [NO7], [NO7A] simple settings, so select the setting value according to the sewing machine being used.

Fig.5 "PEGASUS"

Function setting [NOD]

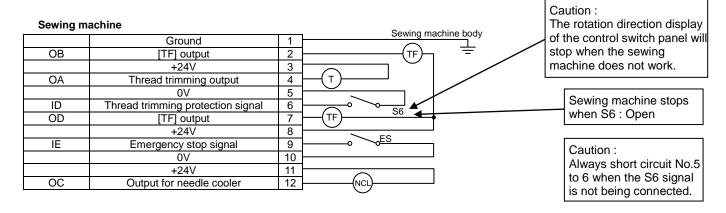


#### Presser foot lifter

	01/		7
	UV	1	
IF	Presser foot lifting signal	2	
OF	Presser foot lifting output +	3	(FU)
OF	Presser foot lifting output -	4	

#### Option A (Black connector)

	0V	1	
IA	Solenoid input signal IO1	2	0 lO1
	Power +5V (Change JP3 connector)	3	+5V max 40mA
IB	Output for the PS1 counting	4	o PS1
04	Needle UP position output	5	UPW 5V max 10mA
IC	Run signal (Low speed)	6	
			Refer to page 14.

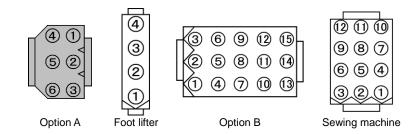


### Option B

Option B			
	0V	1	<del>                                     </del>
14		2	]
01	Thread trimming output	3	External   Control   Contr
VC2	Variable speed command	4	variable resister
15	Thread trimmer cancel signal	5	TL 10kΩ
I1	Operation signal	6	
	+12V (Change JP4 connector)	7	
	+24V	8	22
12	Thread trimming signal	9	\$2
	0V	10	
	+24V	11	
02	Output for needle cooler	12	NCL
07	Output for the PS1 counting	13	
06	Virtual output 1	14	
O3	Always ON output	15	UPW UPW

Fig.6 "PEGASUS"

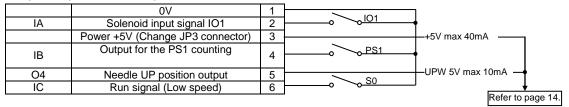
Function setting [NOF]

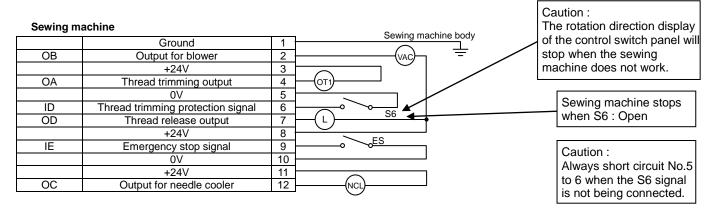


#### Presser foot lifter

	01/		1
	UV	1	
IF	Presser foot lifting signal	2	
OF	Presser foot lifting output +	3	(FU)
OF	Presser foot lifting output -	4	

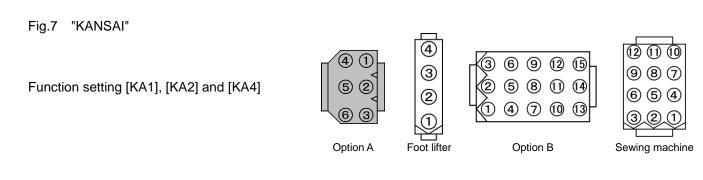
#### Option A (Black connector)





### Option B

Орион в			
	0V	1	+
14		2	]
01	Thread trimming output	3	External
VC2	Variable speed command	4	variable
15	Thread trimmer cancel signal	5	$\frac{TL}{S1}$
I1	Operation signal	6	
	+12V (Change JP4 connector)	7	
	+24V	8	00
12	Thread trimming signal	9	\$2
	0V	10	
	+24V	11	
02	Output for needle cooler	12	NCL
07	Output for the PS1 counting	13	
O6	Virtual output 1	14	
O3	Always ON output	15	UPW



### Presser foot lifter

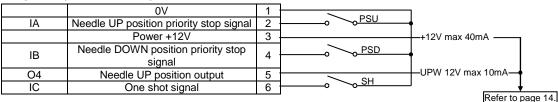
07

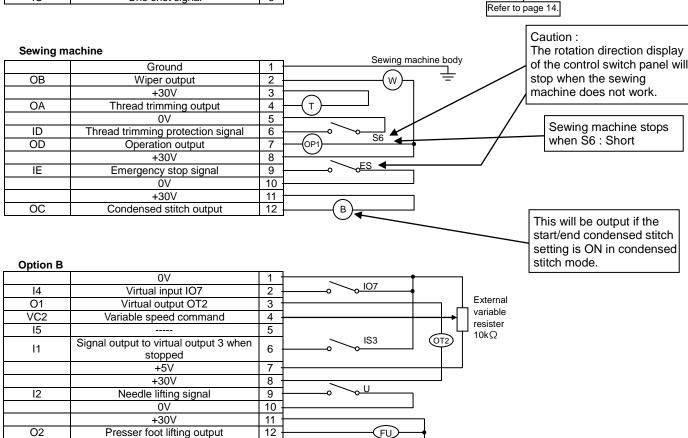
06

О3

	01/	4	]
	UV	1	\ -
IF	Presser foot lifting signal	2	F F
OF	Puller output +	3	(PUL)————
OF	Puller output -	4	

#### Option A (Black connector)





Note) The thread trimming (operation) will differ from the [KA1], [KA2] and [KA4] simple settings, so select the setting value according to the sewing machine being used.

13

14

15

Thread tension output

(TF)

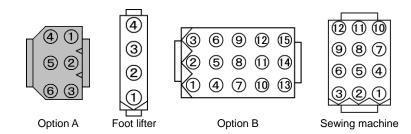
Please refer to page 14.

solenoid power source.

How to change 24/30V of

Fig.8 "KANSAI"

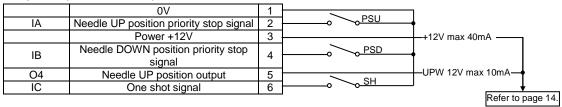
Function setting [KA3]

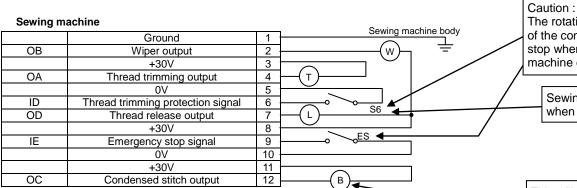


#### Presser foot lifter

	0V	1	
IF	Presser foot lifting signal	2	F F
OF	Puller output +	3	(PUL)
UF	Puller output -	4	

#### Option A (Black connector)





The rotation direction display of the control switch panel will stop when the sewing machine does not work.

> Sewing machine stops when Š6: Short

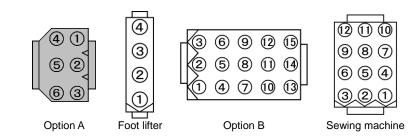
This will be output if the start/end condensed stitch setting is ON in condensed stitch mode.

Option B				
	0V	1	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	
14	Virtual input IO7	2	007	_
01	Virtual output OT2	3	<del>                                     </del>	Externa
VC2	Variable speed command	4	<del>                                     </del>	variable
15		5	]	resister 10kΩ
I1	Signal output to virtual output 3 when stopped	6	IS3 OT2	101(32
	+5V	7		
	+30V	8	<del>                                     </del>	
l2	Needle lifting signal	9		
	0V	10		
	+30V	11		
O2	Presser foot lifting output	12	FU	
07		13		
O6		14	_	
O3	Thread tension output	15	TF-	

Please refer to page 14. How to change 24/30V of solenoid power source.

Fig.9 "UNION SPECIAL"

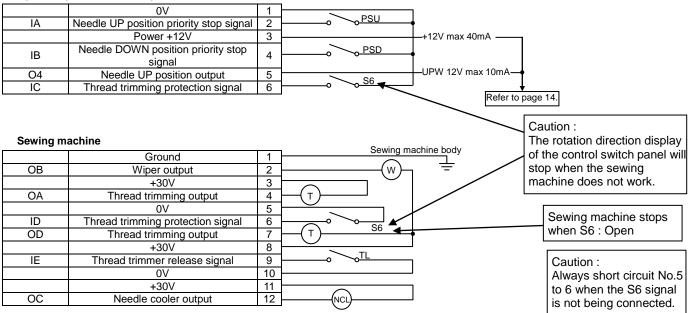
Function setting [UN1]



#### Presser foot lifter

	0V	1	<del></del>
IF	Presser foot lifting signal	2	F F
OF	Presser foot lifting output +	3	(FU)
OF	Presser foot lifting output -	4	

#### Option A (Black connector)



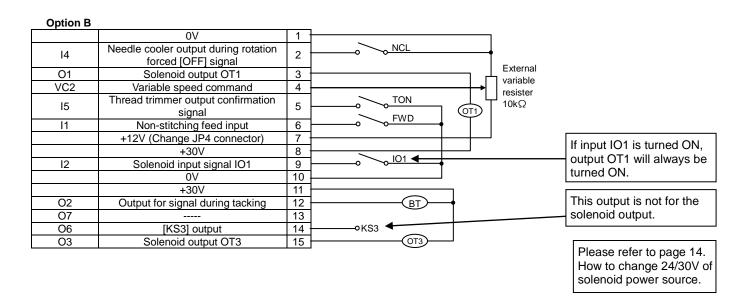
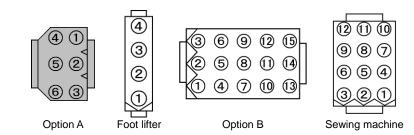


Fig.10 "UNION SPECIAL"

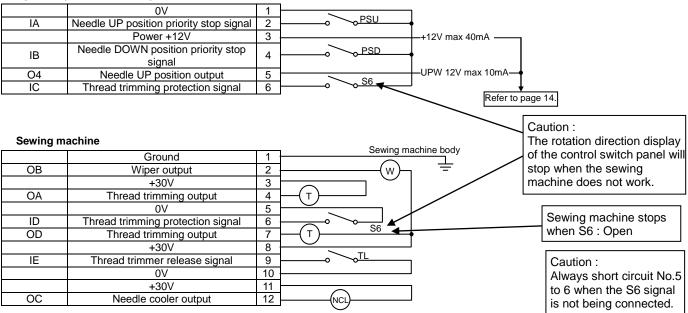
Function setting [UN2], [UN3]



#### Presser foot lifter

	0\/	1	
	UV	ı	_
IF	Presser foot lifting signal	2	
OF	Presser foot lifting output +	3	(FU)
Oi	Presser foot lifting output -	4	

#### Option A (Black connector)



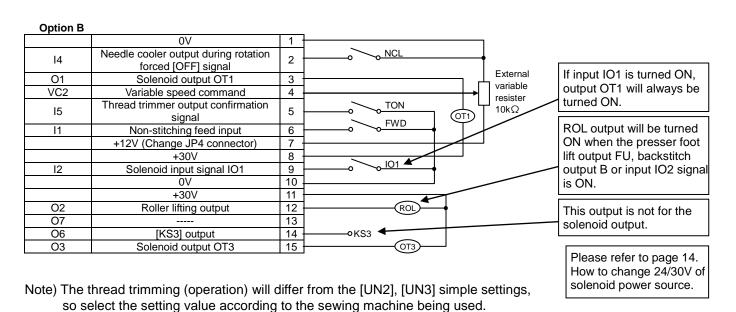
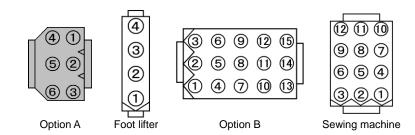


Fig.11 "BROTHER"

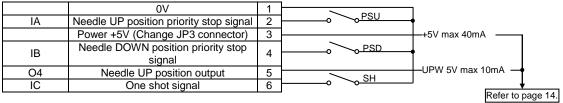
Function setting [BR1]

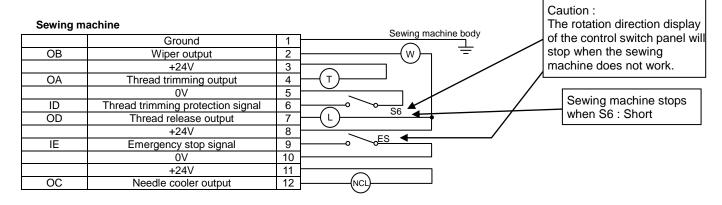


#### Presser foot lifter

	0\/	1	
	UV		
IF	Presser foot lifting signal	2	
OF	Presser foot lifting output +	3	(FU)———
OF .	Presser foot lifting output -	4	

# Option A (Black connector)





#### Option B

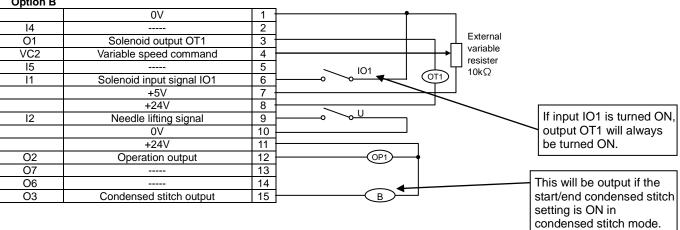
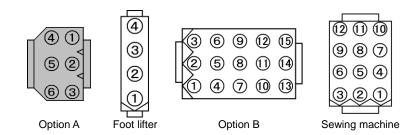


Fig.12 "RIMOLDI"

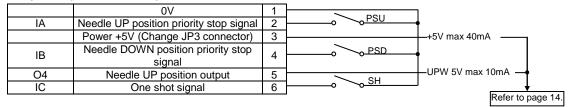
Function setting [RM1]

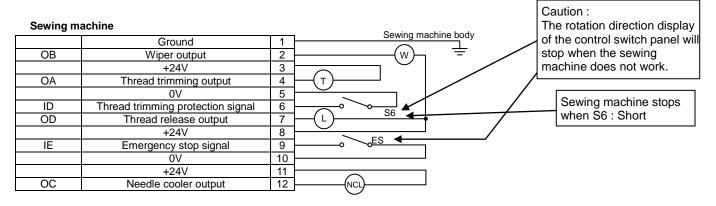


#### Presser foot lifter

	0V	1	<del></del>
IF	Presser foot lifting signal	2	F F
OF	Presser foot lifting output +	3	(FU)
OF	Presser foot lifting output -	4	

#### Option A (Black connector)





#### Option B

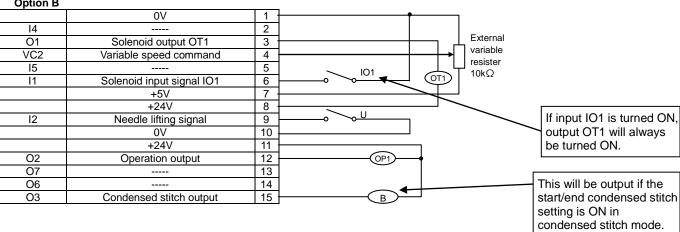
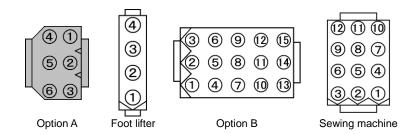


Fig.13 "SIRUBA"

Function setting [SRB1]



#### Presser foot lifter

	0) /		1
	0V	1	
IF	Presser foot lifting signal	2	
OF	Presser foot lifting output +	3	(FU)
OF .	Presser foot lifting output -	4	

#### Option A (Black connector)

	0V	1	NO.
IA	Needle UP position priority stop signal	2	PSU
	Power +5V (Change JP3 connector)	3	+5V max 40mA
IB	Needle DOWN position priority stop signal	4	PSD
O4	Needle UP position output	5	UPW 5V max 10mA
IC	Low speed run signal	6	
			Refer to page 14.

#### Sewing machine Sewing machine body Ground 1 W OB Wiper output 2 3 +24V T OA 4 Thread trimming output 5 6 7 0V ID Thread trimmer cancel signal OD Thread release output 8 +24V ΙE Backstitching during run signal 9 10 ٥V +24V 11 OC Condensed stitch output 12 В

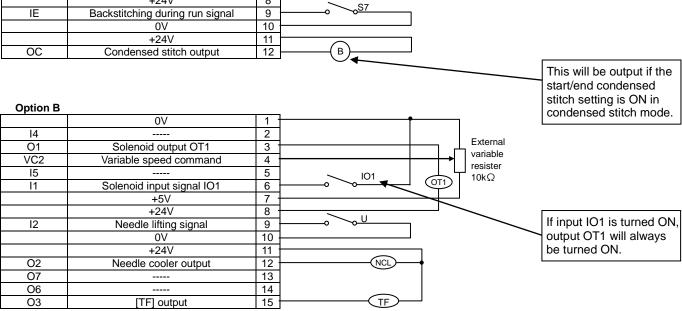
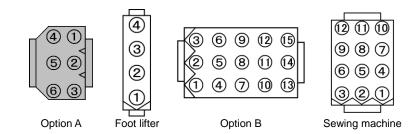


Fig.14 "JUKI"

Function setting [JMH]

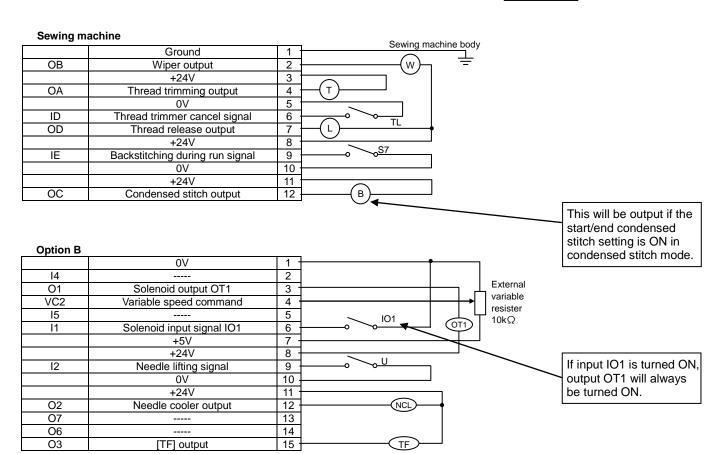


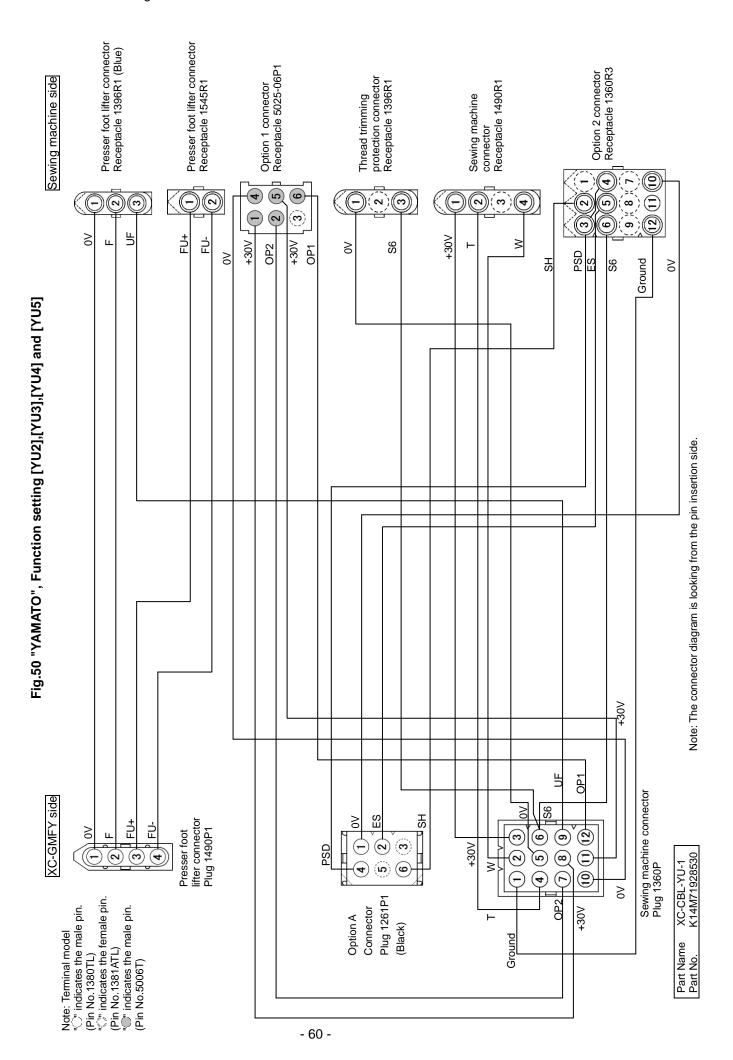
#### Presser foot lifter

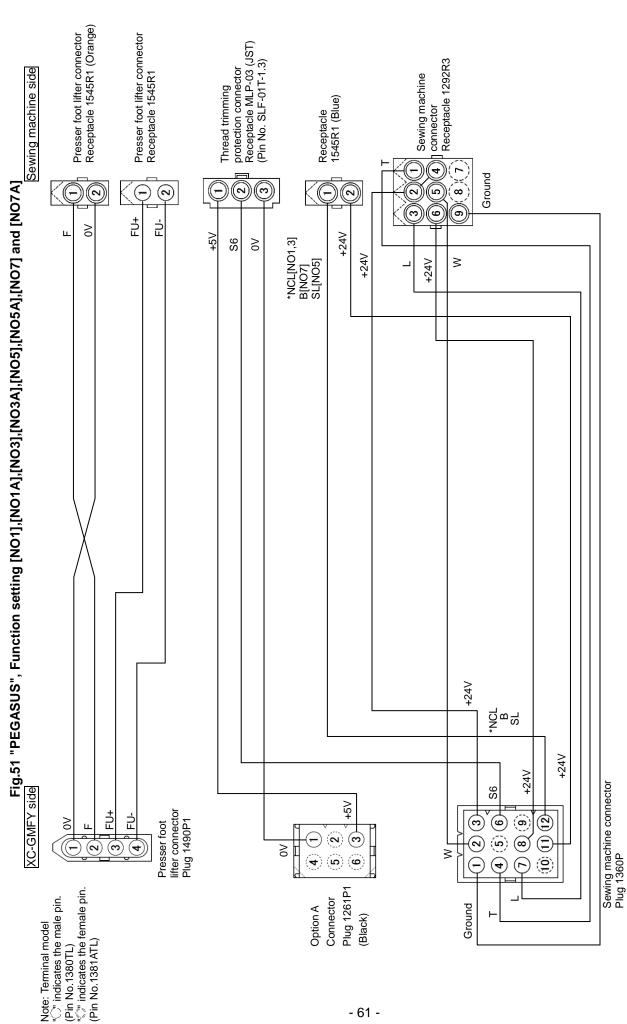
	0)/		1
	UV	1	
IF	Presser foot lifting signal	2	
OF	Presser foot lifting output +	3	(FU)———
UF	Presser foot lifting output -	4	

#### Option A (Black connector)

	0V	1	POLL
IA	Needle UP position priority stop signal	2	PSU
	Power +5V (Change JP3 connector)	3	+5V max 40mA
IB	Needle DOWN position priority stop signal	4	PSD
04	Needle UP position output	5	UPW 5V max 10mA
IC	Low speed run signal	6	
	·		Refer to page 14.







Note: 1.The connector diagram is looking from the pin insertion side.

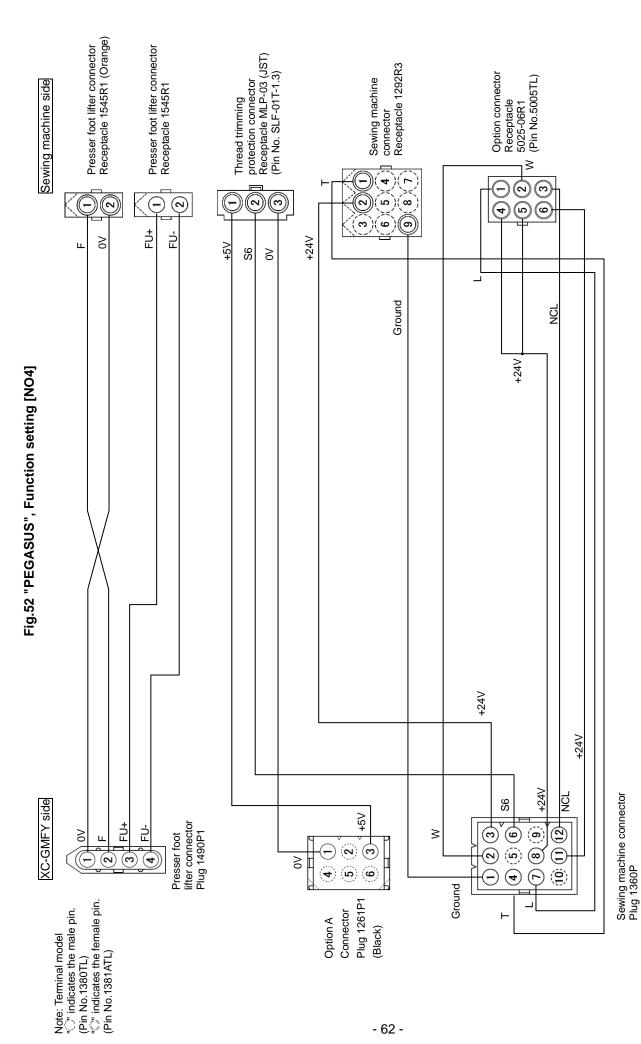
2. \* The NCL output will be applied for function settings [NO1], [NO3].

The B output will be applied for function settings [NO7].

The SL output will be applied for function settings [NO5].

XC-CBL-PP-1 K14M71928730

Part Name Part No.



Note: The connector diagram is looking from the pin insertion side.

XC-CBL-PP-2 K14M71928830

Part Name Part No.

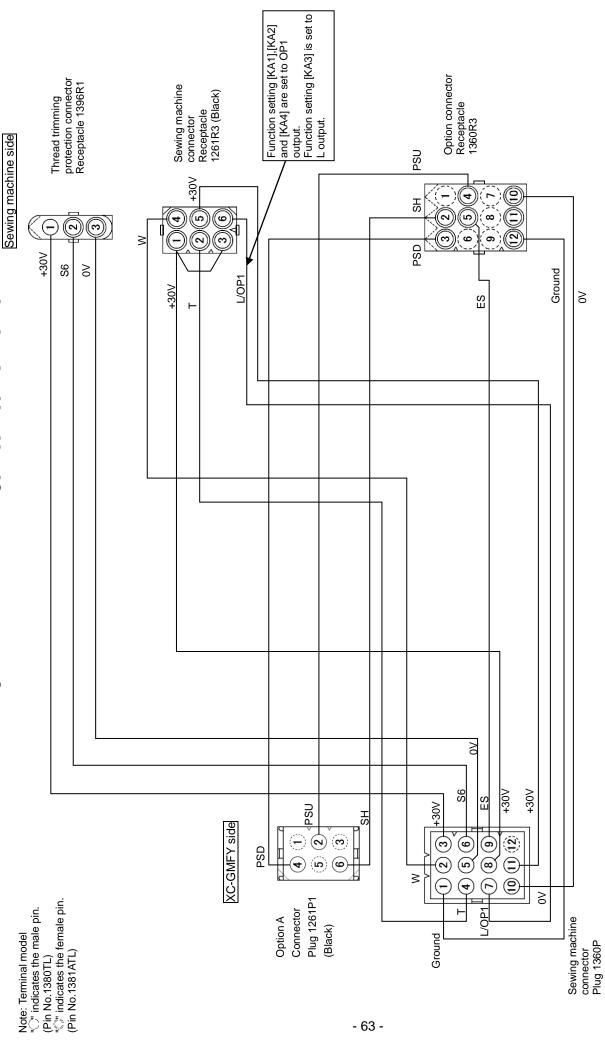
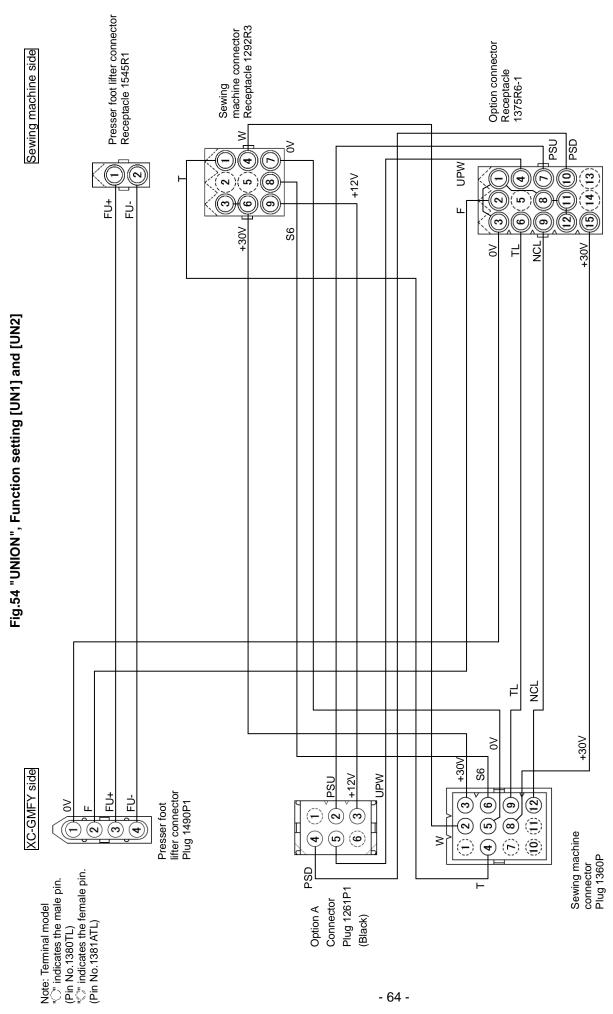


Fig.53 "KANSAI", Function setting [KA1],[KA2],[KA3] and [KA4]

Note: The connector diagram is looking from the pin insertion side.

XC-CBL-KA-1 K14M71928931

Part Name Part No.

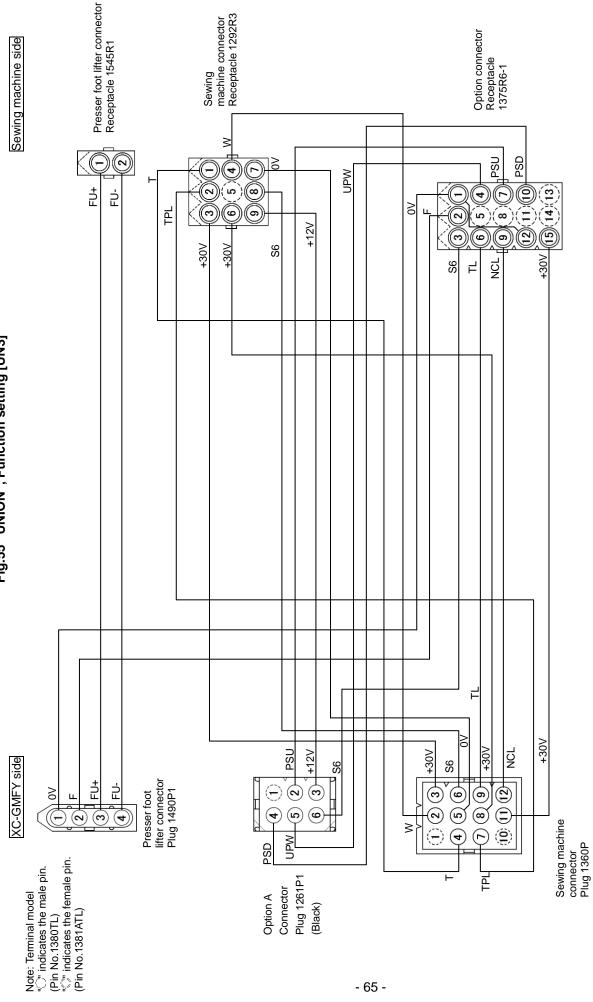


Note: The connector diagram is looking from the pin insertion side.

XC-CBL-UN-1 K14M71925030 Part Name Part No.

- 64 -

Sewing machine side Fig.55 "UNION", Function setting [UN3] XC-GMFY side

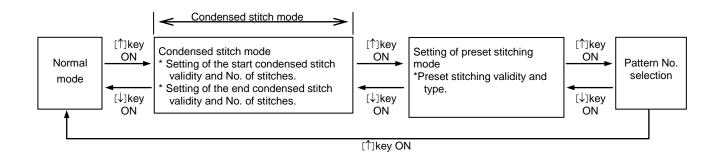


Note: The connector diagram is looking from the pin insertion side.

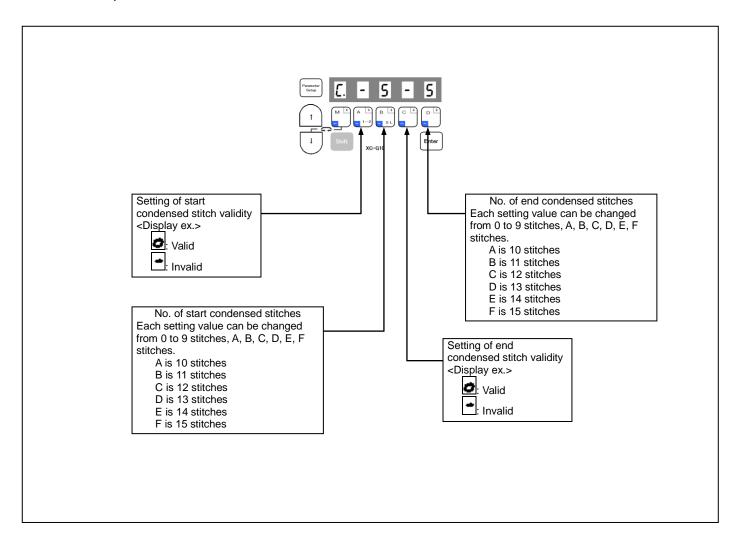
Part Name XC-CBL-UN-2 Part No. K14M71925130

- 65 -

# 5. Displays and function of each key in the condensed stitch mode



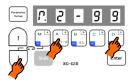
When the [↑] key is turned ON, will display above the [M] key, and the condensed stitch mode will be entered. The validity and No. of stitches of start and end condensed stitch can be set here.



1.How to use Simple setting of Program Mode [3] (for lock stitch trimming machine)

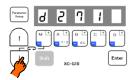
To set the functions for the DÜRKOPP ADLER thread trimming sewing machine in one step
(For example, to set for the 271 class, "DÜRKOPP ADLER").......Function setting [D271]

(1)



\*Enter the program mode [3].  $([\downarrow] + [A] + [D] \text{ keys})$ 

(3)

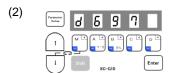


\*Press the  $[\downarrow]$  key or  $[\uparrow]$  key to change the function to [D271].

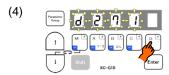
(5)



\*The mode will return to the normal mode when the [D] key is held down over two seconds or more. (This completes the settings.)



\*The mode will change to the program mode [3].



\*When the [D] key is held down, [D271] will flicker, and the changes to the setting will be set.

# Description

- A. Select the model name that corresponds to the sewing machine model for the simple setting values for the DÜRKOPP ADLER thread trimming sewing machine on the "Technical manual". After selecting the function name, holds down the [D] key over 2 seconds or more. The function name's set speed and function will be set automatically.
- B. To return to the normal mode from the [D271] display, press the [↑] key while holding down [↓]. In this case, [D271] will not be set, and the last settings will be used.
- C. Each time the [↓] key is pressed in step 3, the function will change in order from [D697], [D271], [D273]....[750].

#### Caution

To use this mode, please ask your dealer or look at "TECHNICAL INFORMATION MANUAL" about simple setting, I/O signal, Junction wiring in detail.

Model name of sewing machine and device
697-15000 class
271-14000,272-14000 class
273-14000,274-14000 class
DB2-B705,DB2-B707,DB2-B715 class
DB2-B716-?,DB2-B716-1,DB2-B716-?,DB2-B716-5 class
DB2-B737-1,DB2-B737-3,DB2-B737-5 class
DB2-B746-5,DB2-B746-7,DB2-B746-8,DB2-B747-5,DB2-B748 5,DB2-B748-7 class
DB2-B757 class
DB2-B772,DB2-B774,DB2-B7740,DB2-B778 class
DB2-B790,DB2-B791-3,DB2-B791-5,DB2-B7910-3,DB2-B7910 -5,DB2-B792,DB2-B793-403,DB2-B798 class
DB2-B837,DB2-B838 class
LT2-B841-1,LT2-B841-3,LT2-B841-5,LT2-B842-1,LT2-B842-3,L T2-B842-5,LT2-B845,LT2-B8450,LT2-B8480,LT2-B847,LT2-B8 48,LT2-B872,LT2-B875,LT2-B8750 class
LZ2-B852,LZ2-B853,LZ2-B854,LZ2-B856,LZ2-B857 class
DDL-500,DMN-5420NFA-6-WB class
DDL-505, DDL-505A, DDL-506, DDL-506A, DDL-506E, DDL-560- 5, DDL-5600, DLU-5494NBB-6-WB, PLW-1245-6, PLW-1246-6, P LW-1257-6, PLW-1264-6, PLW-1266-6 class
DDL-555-2-2B,DDL-555-2-4B,DDL-555ON,DDL-5570,DDL-557 1,DDL-5580 class
DLD-432-5,DLD-436-5,DLM-5400N-6,DLM-5400-6,DLN-415-5,DLN-5410N-6,DLN-5410N-6,DLN-5410-6,DLU-480-5,DLU-491-5,DLU-5490BB-6-OB,DLU-5490BB-6-WB,DLU-5490N-6,DMN-530-5,DMN-531-5 class
DNU-241H-5, DNU-241H-6, DSC-244-6, DSC-244V-6, DSC-245-6, 5, DSC-245-6, DSC-246V-6, DSU-142-6, DSU-144-6, DSU-145-6, DSU-145-6, DU-141H-4, DU-141H-5, DU-141H-6, DU-161H-6, Class
LH-1172,LH-1180-5,LH-1182-5,LH-1150,LH-1152,LH-1160,LH-1 162 class
DDL-5560NL-6,LU-1114-5,LU-1114-6,LZH-1290-6 class
LU-2210-6-0B class

End condensed speed V	1700	1700	1700	1700	1700	1700	1500	1500	1500	1000	1000	1500	1500	1500	1500	1500	1500
Start condensed speed N	1700	1700	1700	1700	1700	1700	1500	1500	1500	1000	1000	1500	1500	1500	1500	1500	1500
Trimming speed T	200	200	200	200	180	100	160	160	200	180	180	180	180	200	200	200	215
Low Low	200	200	200	200	250	100	250	250	250	200	200	250	250	250	250	250	250
High speed H	3500	4000	3500	1900	4000	220	4000	4000	4000	2300	3500	4000	4500	4000	4000	4000	4500
1/2 pos	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2
Note 2 DC5V or 12V setting in option A connector	12V	12V	12V	12V	12V	12V	12V	12V	12V	12V	12V	12V	12V	12V	12V	12V	12V
Note 1 solenoid voltage	300	300	30V	30V	300	24V	24V	24V	24V	24V	24V	24V	24V	24V	24V	24V	24V
Junction wiring	Refer CONN N	NEC		YOTA	1	;	Fig.60	Fig.60	Fig.60	Fig.60	Fig.60	Fig.60	Fig.60	Fig.60	Fig.60	Fig.60	Fig.60
I/O signals of connectors	!	1			Fig.23		Fig.24	Fig.24	Fig.24	Fig.24	Fig.24	Fig.24	Fig.24	Fig.24	Fig.24	Fig.24	Fig.24
Model name of sewing machine and device	AD1012,AD1012B,AD1012G,AD1013,AD1013A,AD1013G,AD1 020,AD1102,AD1102B,AD1102G,AD1103,AD1103A,AD1202,A D1203,AD1204S,AD1205,AD1205S,AD1212G,AD1213,AD220 0,AD5010S class	AD157,AD157G class	AD158,AD158-2,AD158-22,AD1584-3,AD158A-32,AD158B-2, AD158B-22,AD158G-2,AD158G-22,AD158-3,AD158-32 class	AD3110,AD3110P,AD320-2,AD320-22,AD320-202,AD331,AD3 310,AD3310P,AD332,AD340-2,AD340-22,AD340-202,AD340B- 2,AD340B-22,AD340B-202,AD341-2,AD341-22,AD341-202,AD 345-2,AD345-22,AD345-202,AD352 class	Class 63900 Solenoid-operated needle feed under trimmer	SLH-2B	457 Wiper	457 Thread pull	591, 1591	211A	212A	411U	412U	591V	1691D250	1691D210, 1691D200	750
Sewing machine maker	TOYOTA	TOYOTA	тоуота	ТОУОТА	UNION SPECIAL	SEIKO	SINGER	SINGER	SINGER	SINGER	SINGER	SINGER	SINGER	SINGER	SINGER	SINGER	SINGER
Digital display	r 100	151	l 158	r 300	8638	2H75	4595	_ ժՆՏԻ	59 !	B! ! 2	2 12B	11 1 h	በ2!	59 10	69 <i>IR</i>	69 16	05b
Function	T100	T157	T158	T300	6E9N	SLH2	457G	457F	591	211A	212A	411U	412U	591V	691A	691B	750

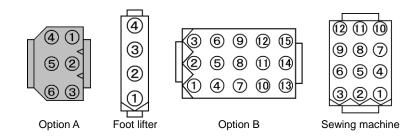
Note: 1. Refer to page 14 for how to change the solenoid voltage. The factory setting is 24V.

2. Refer to page 14 for how to change the option A connector DC5V/12V. The factory setting is 12V.

# 3. I/O signals of connectors

Fig.20 "DÜRKOPP ADLER"

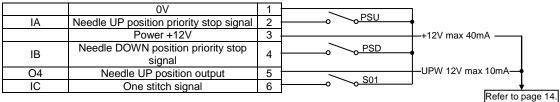


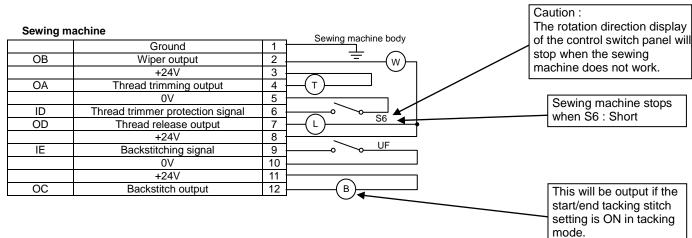


#### Presser foot lifter

	0) /	-	
	UV	1	
IF	Presser foot lifting signal	2	
OF	Presser foot lifting output +	3	(FU)————
OF .	Presser foot lifting output -	4	

# Option A (Black connector)

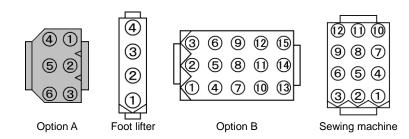




Option B 0V 14 Backstitching signal 2 Presser foot lifting output + 3 External 01 variable VC2 Variable speed command 4 S01 One stitch signal resister 5 15 (FU) 10kΩ UD. Half-stitch signal 11 6 When input UD is turned ON, 7 +5V half-stitch sewing will start. +24V 8 BTL ◀ 12 Tacking cancel signal 9 When input BTL is turned ON, start 10 0V and end tacking will be prohibited. +24V 11 Ω2 Needle cooler output 12 (NCL) This output is not for the 07 [KS3] output 13 06 14 solenoid output. О3 TF output 15 -Refer to page 93.

Fig.21 "DÜRKOPP ADLER"

Function setting [D271]



#### Presser foot lifter

	0V	1	_
IF	Presser foot lifting signal	2	F F
OF	Presser foot lifting output +	3	(FU)
l OF	Presser foot lifting output -	4	

#### Option A (Black connector)

	0V	1	<u> </u>
IA	Needle UP position priority stop signal	2	PSU
	Power +12V	3	+12V max 40mA
IB	Needle DOWN position priority stop signal	4	PSD
04	Needle UP position output	5	UPW 12V max 10mA
IC	One stitch signal	6	<u>S01</u>
			Refer to page 14.

Sewing machine

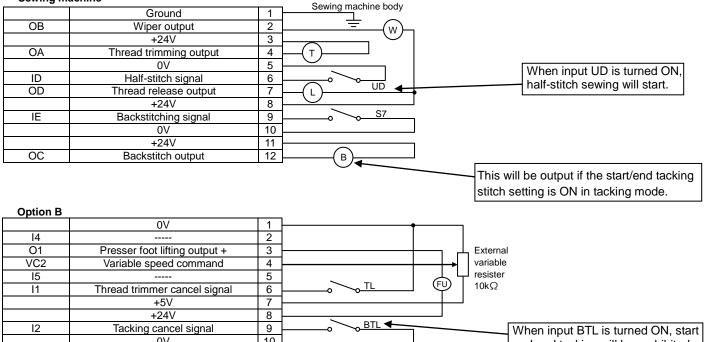
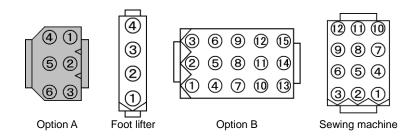


Fig.22 "DÜRKOPP ADLER"

Function setting [D273]



#### Presser foot lifter

	٥V	1	
IE	Presser foot lifting signal	2	<u></u>
II.	<u> </u>		
OF	Presser foot lifting output +	3	(FU)
٠.	Presser foot lifting output -	4	

#### Option A (Black connector)

	0V	1	
IA	Needle UP position priority stop signal	2	PSU
	Power +12V	3	+12V max 40mA
IB	Needle DOWN position priority stop signal	4	PSD
04	Needle UP position output	5	UPW 12V max 10mA
IC	One stitch signal	6	S01 V
			Refer to page 14.

Sewing machine

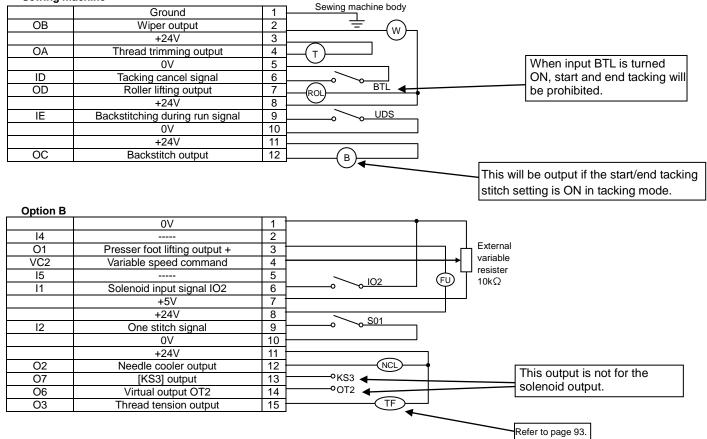
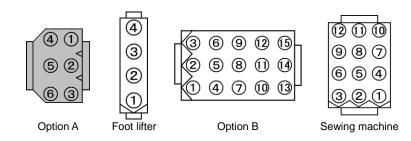


Fig.23 "UNION SPECIAL"

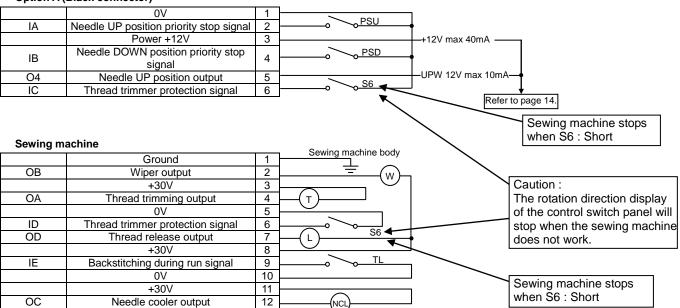
Function setting [U639]

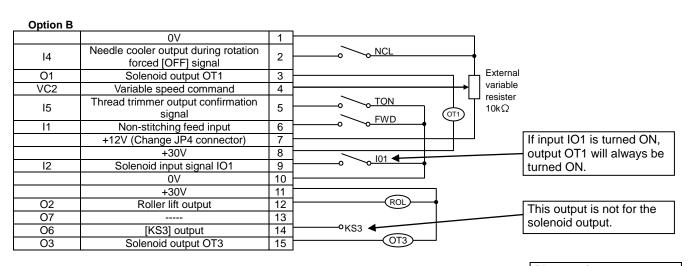


#### Presser foot lifter

	0V	1	
IF	Presser foot lifting signal	2	
OF	Presser foot lifting output +	3	(FU)
OF	Presser foot lifting output -	4	

#### Option A (Black connector)



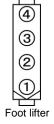


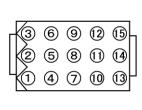
Please refer to page 14. How to change 24/30V of solenoid power source.

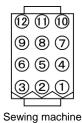
Fig.24 "SINGER"

Function setting [457G], [457F], [591], [211A], [212A], [411U], [412U], [591V], [691A], [691B] and [750]









Option A

Option B

### Presser foot lifter

	0V	 1	
IF	Presser foot lifting signal	 2	
OF	Presser foot lifting output +	 3	[FU]——
OF .	Presser foot lifting output -	 4	

### Option A (Black connector)

	0V		1	0V
	Start tacking cancel signal	Except 750		When this input is turned ON, start tacking will be inhibited while the signal is ON.
IA	Thread trimmer protection signal	750	2	When input S6 is turned ON while the sewing machine is running, the sewing machine will stop. When input S6 is turned ON during thread trimming, the operation will be completed, and operation will not be possible until input S6 is turned OFF.
	Power +12V		3	DC12V (max 40mA) is output.
IB	End tacking cancel signal		4	When this input is turned ON, end tacking will be inhibited while the signal is ON.
04	Needle UP position output		5	The needle UP position signal is output. The output voltage is DC12V.
IC	Thread trimmer cancel signal		6	When pedal full heeling is turned ON while this input is ON, the thread will not trimmed. After the thread trimmer interlock time passes, the presser foot lifting operation will start.

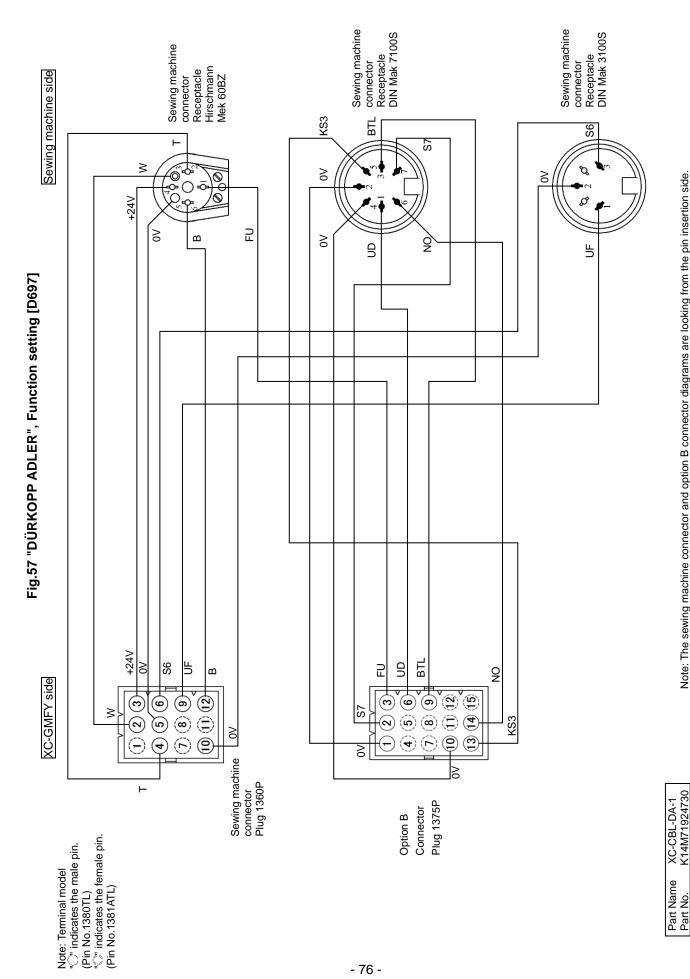
#### Sewing machine

	Ground		1	Ground
	Wiper solenoid output	457G, 457F,750		It will be for wiper solenoid output.
	Thread release solenoid output	691A,691B	_	It will be for thread release solenoid output.
OB	Option solenoid output	411U,412U, 591,211A, 212A,591V	2	This output is always turned ON when option solenoid input signal is ON.
	+24V		3	+24V
OA	Thread trimming output		4	It will be for thread trimming solenoid output.
	0V		5	0V
ID	Needle up input		6	When this input is turned ON, the needle up input will function.
	Thread release solenoid output	457G, 457F,750		It will be for thread release solenoid output.
OD	Wiper solenoid output	Except 457G, 457F,750	7	It will be for wiper solenoid output.
	+24V		8	+24V
ΙE	Manual backtacking signal		9	When this input is turned ON, the backtacking operation will start.
•	0V		10	0V
•	+24V		11	+24V
OC	Backstitch output		12	It will be for Backstitch solenoid output.

Option B

0V		1	0V
		2	
	Except 691A,691B, 750	3	Not output.
ADD.BT solenoid output	691A,691B		It will be for ADD.BT solenoid output.
Thread trimmer output	750		Thread trimming starts.
Variable speed command		4	This input is for external speed command. (If voltage is applied to this input, sewing machine will start.)
		5	
Needle UP position priority stop signal		6	When input PSU is turned ON while the sewing machine is running, the needle will stop at the UP position after swing PSU stitches and thread trimming.
+5V		7	DC5V (max 10mA) is output.
+24V		8	+24V
Emergency stop signal	457G,457F, 691A,691B, 750	a	When this input is turned ON while the sewing machine is running, all running states will be canceled, and the sewing machine will stop with the brakes.
Option solenoid input signal	591,211A, 212A,411U, 412U,591V		When this input is turned ON, the option solenoid output will start.
0V		10	0V
+24V		11	+24V
	Except 691A,750		Not output.
Air blow output	691A	12	It will be for the air blow output.
Wiper solenoid output			It will be for wiper solenoid output.
		13	
		14	
Thread pull output	691A	15	It will be for the thread pull output.
	Except 691A	15	Not output.
	ADD.BT solenoid output Thread trimmer output Variable speed command Needle UP position priority stop signal +5V +24V Emergency stop signal Option solenoid input signal  0V +24V Air blow output Wiper solenoid output Thread pull output	Company	2  Except 691A,691B, 750  ADD.BT solenoid output 691A,691B Thread trimmer output 750  Variable speed command 5  Needle UP position priority stop signal 5  Needle UP position priority stop signal 6  +5V 7 +24V 8  Emergency stop signal 457G,457F, 691A,691B, 750  Option solenoid input signal 212A,411U, 412U,591V  OV 10 +24V 11  Except 691A,750 Air blow output 691A Wiper solenoid output 750  13 13 14 Thread pull output 691A 15

Note) The thread trimming (operation) will differ with the [457G], [457F], [591], [211A], [212A],[411U], [412U], [591V], [691A], [691B] and [750] simple setting, so select the setting value according to the sewing machine being used.



Note: The sewing machine connector and option B connector diagrams are looking from the pin insertion side.

Sewing machine connector Receptacle Hirschmann Mek 100

Sewing machine connector Receptacle Hirschmann DIN Mak 3100S

S7

 $\geq$ 

Note: The sewing machine connector and option B connector diagrams are looking from the pin insertion side.

XC-CBL-DA-2 K14M71924830 Part Name Part No.

XC-GMFY side

Sewing machine connector Receptacle DIN Mak 7100S Sewing machine connector Receptacle Hirschmann Mek 100 Sewing machine side KS3 801 9 +24V  $\mathbb{F}$ NCL <del>P</del> > OT2 ROL 8 ≥ 02 +24V NDS BTL В (0) (1) (2)8 0 ROL Sewing machine connector Plug 1360P Plug 1375P Connector Option B Note: Teminal model
"(" indicates the male pin.
(Pin No.1380TL)
"(")" indicates the female pin.
(Pin No.1381ATL)

Note: The sewing machine connector and option B connector diagrams are looking from the pin insertion side.

Sewing machine connector Receptacle DIN Mak 3100S

BTL

/ SON

OT2

KS3

XC-CBL-DA-3 K14M71924930 Part Name Part No.

- 78 -

Thread trimmer connector Receptacle 1490R1 Thread release connector Receptacle 1261R2 Thread pull connector Receptacle 1396R1 lifter connector Receptacle 1490R1 Receptacle 1292R Option connector Presser foot Sewing machine side 8 BSL (1) +24V 8 9 (<u>-</u>) 2 <u></u> (N) (P) (S)  $\bigcirc$ +24V FU+ +24V В ш 폇 8 +24V +24V 0 W [457G,457F,750] OT1 [591,211A,212A,411U,412U,591V] KS3 [691A] W [750] Not output [Except 691A,750] TB [691A,691B] | T [750] | Not output [Except 691A,691B,750] TF [691A] Not output [Except 691A] - [691A,691B] SB [Except 750] S6 [750] +24V +24V XC-GMFY side 8 Ę 금 4 5 6 7 8 9 1 789 8 4 5 ш (5) (2) 2 +24V 9 Sewing machine\_ lifter connector XC-CBL-SG-1 K14M72022131 Plug 1261P1 Plug 1490P1 Plug 1375P Presser foot connector Plug 1360P Connector Connector Option B Option A (Black) L [457G,457F,750] W [Except 457G,457F,750] · (Pin No.1380TL)

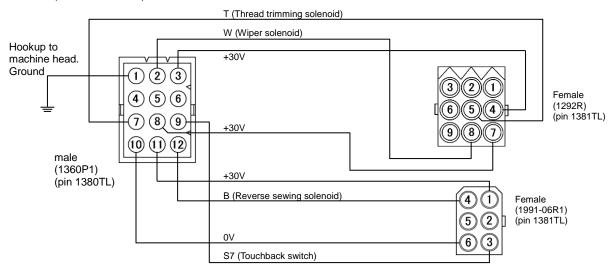
indicates the female pin.
(Pin No.1381ATL) "C" indicates the male pin. Note: Terminal model Part Name Part No.

Fig.60 "SINGER", Function setting [457G],[457F],[591],[211A],[212A],[411U],[412U],[591V],[691A],[691B] and [750]

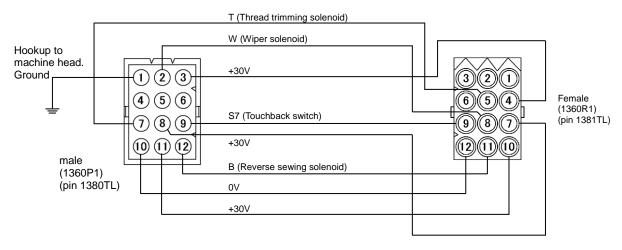
#### 5. How to connect BROTHER machine

#### 5.1 Junction wiring

### (1)DB2-715 (XC-CBL-BR-1)

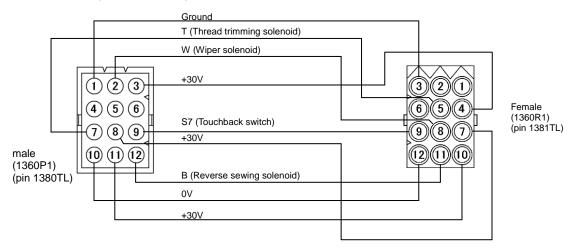


### (2)DB2-716 (XC-CBL-BR-2)



(3)DB2-B737, B737 MARK II, B748, B791, B7910, B793, B795, B798, LT2-B842, B845, B847, B848, B872, B875,

LZ2-B852, B853, B854 (XC-CBL-BR-3)



#### 5.2 How to use BROTHER'S built-in detector by LIMI-SERVO X

#### (1). MODEL

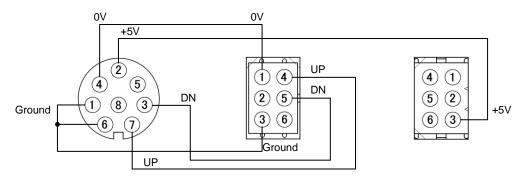
- (a) Applicable brother built-in type detector brother control box: MODEL MD-803, MD-813
- (b) MITSUBISHI LIMI-SERVO MOTOR LIMI-SERVO X MODEL XC-GMFY control box

#### (2). How to connect

(a) Set up for over-change connector

First, turn off the power. After 10 min. of turning off, screw down and remove the front cover. Power for brother's built-in detector is +5v, so open the cover of MITSUBISHI LIMI-SERVO control box, and change from +12v to +5v inside connector (JP3).

(b) Connect by relay cable (XC-CBL-BR-4)



TO BROTHER BUILT-IN DETECTOR CONNECTOR 8 PIN DIN TYPE HOSIDEN CONNECTOR TCS8086-01-5201 TO LIMI-SERVO
DETECTOR
CONNECTOR
MOLEX CONNECTOR
CONNECTOR 1991-06P1
TERMINAL 1380TL
OR AMP CONNECTOR
CONNECTOR 770361-1
TERMINAL 770147-1

TO LIMI-SERVO
OPTION A
CONNECTOR
MOLEX CONNECTOR
CONNECTOR 1261P1
TERMINAL 1380TL
OR AMP CONNECTOR
CONNECTOR 770090-1
TERMINAL 770147-1

#### 5.3 How to connect BROTHER'S built-in volume type push button switch

(1). Applicable brother push bottom switch built-in volume type push bottom switch

# OFF ON LOW \_\_\_\_\_\_\_HIGH

#### (2). MITSUBISHI LIMI-SERVO MOTOR

(a) 100V, 1-phase use.

CONTROL BOX : XC-GMFY-10-05 MOTOR : XL-G554-10Y

(b) 200V, 3-phase use.

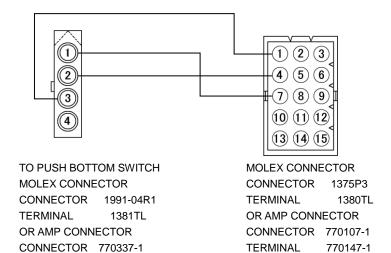
CONTROL BOX : XC-GMFY-20-05 MOTOR : XL-G554-20Y

**TERMINAL** 

#### (3). How to connect

(a) Connect push bottom switch with LIMI-SERVO (XC-CBL-BR-6)
Using the junction wire of following indication, connect the control box and volume of push bottom switch.

(b) Turn off the power. After 10 min. of turning off, screw down and remove the front cover. Power for brother's variable speed command is 12v, so open the cover of MITSUBISHI LIMI-SERVO control panel, and change from +5v to +12v inside connector (JP4).



(4). Set up by control panel

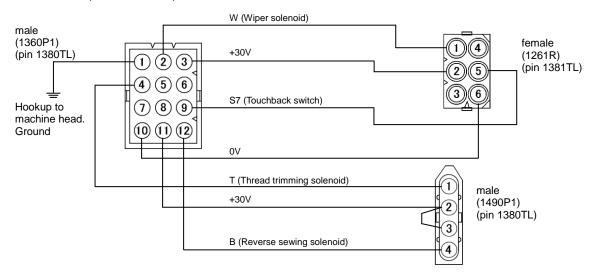
- (a) Press the key [↓], [A] and [C] key simultaneously over 2 seconds at normal mode (indication is rotating) and set "Q" mode. Indicate the thread trimming time like [VCS.OF].
- (b) Press key [↓] few times, and find out VC2 (action mode VC2 for speed instructions). Indication become like [VC2.VC].
- (c) Press the key "D" few times, change the indication for [VC2.VR] (function of speed ordering input VC2 of connector option-b change into the function of speed volume of control panel).
- (d) Press key [↓] few times, and find out V25 (VC2 input 5V/12V changeover mode). Indication become like [V25.ON].
- (e) Press the key "D" once, change the indication for [V25.OF] (function of VC2 maximum input voltage change into 12v).
- (f) Press the key  $[\downarrow]$  and  $[\uparrow]$  simultaneously, return to the normal mode.

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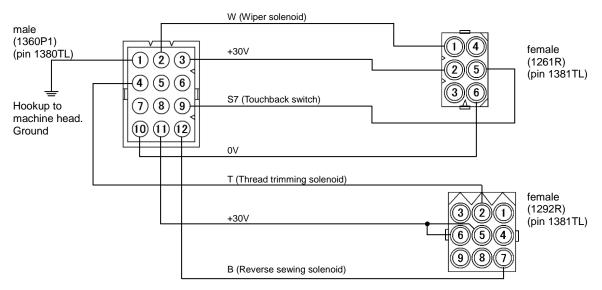
#### 6. How to connect JUKI machine

#### 6.1 Junction wiring

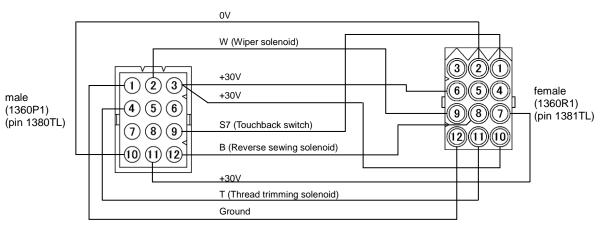
### (1) For DDL-500 (XC-CBL-JK-1)



### (2) For DDL-555-2-2B, 4B (XC-CBL-JK-2)

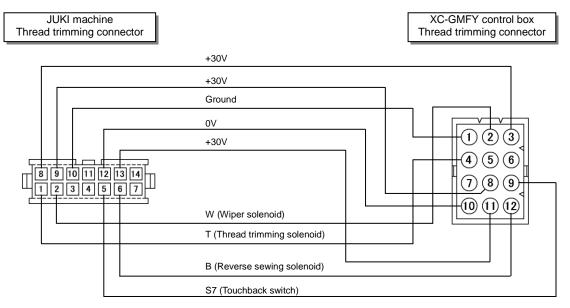


### (3) For DDL-505, 506, 5570, 5580, DLU-5490 (XC-CBL-JK-3)



### (a) For thread trimming

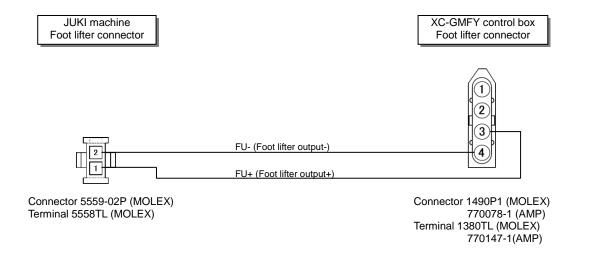
### [Parts Name:XC-CBL-JK-5 (Parts No.:K14M72021130)]



Connector 5559-14P (MOLEX) Terminal 5558TL (MOLEX)

Connector 1360P1 (MOLEX) 770102-1 (AMP) Terminal 1380TL (MOLEX) 770147-1(AMP)

### (b) For foot lifter [Parts Name:XC-CBL-JK-6 (Parts No.:K14M72021230)]



#### 6.2 How to use JUKI'S built-in detector by LIMI-SERVO X

#### (1). MODEL

(a) JUKI'S built-in detector

THE models for JUKI'S control box j1aeas

(b) MITSUBISHI'S SERVO MOTOR

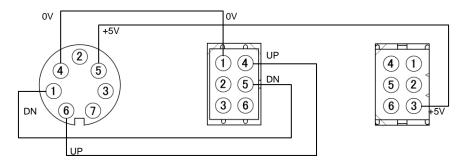
LIMI-SERVO X MODEL XC-FMFY control box

### (2). How to connect

(a) Set up the dc5v/12v changeover switch

First, turn off the power. If turned off the power, the voltage is high, and please wait 10 more minutes after you turned off, please take off the front cover to screw down by plus driver. The power for JUKI'S built-in detector is +5v, open the control panel for MITSUBISHI LIMI-SERVO X, change over the inside connector (JP3) from side +12v to side +5v.

(b) Connection with junction wire (XC-CBL-JK-4)



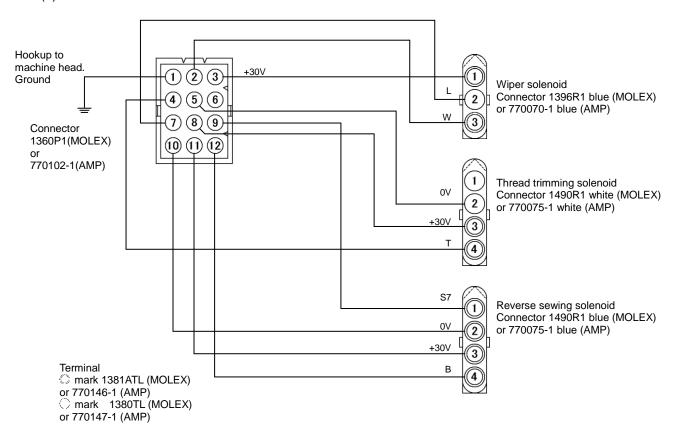
TO JUKI BUILT-IN
DETECTOR
CONNECTOR
7 PIN DIN TYPE
HOSIDEN CONNECTOR
TCS8076-01-5201

TO LIMI-SERVO
DETECTOR
CONNECTOR
MOLEX CONNECTOR
CONNECTOR 1991-06P1
TERMINAL 1380TL
OR AMP CONNECTOR
CONNECTOR 770361-1
TERMINAL 770147-1

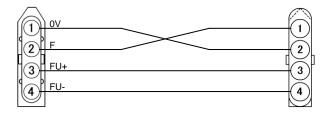
TO LIMI-SERVO
OPTION A
CONNECTOR
MOLEX CONNECTOR
CONNECTOR 1261P1
TERMINAL 1380TL
OR AMP CONNECTOR
CONNECTOR 770090-1
TERMINAL 770147-1

#### 7. How to connect TOYOTA machine

## 7.1 Junction wiring (1)XC-CBL-TY-1



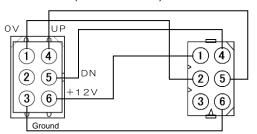
### (2) TOYOTA FOOT LIFTING DEVICE (XC-CBL-TY-2)



To LIMI-SERVO foot lifting connector Connector 1490P1 white (MOLEX) or 770078-1 white (AMP) Terminal 1380TL male (MOLEX) or 770147-1 (AMP) To TOYOTA machine foot lifting Connector 1490R1 black (MOLEX) or 770075-1 black (AMP) Terminal 1380TL male (MOLEX) or 770147-1 (AMP)

#### (3)TOYOTA BUILT-IN SYNCHRONIZER (XC-CBL-TY-3)

To LIMI-SERVO detector connector Connector 1991-06P1 (MOLEX) or 770361-1 (AMP) Terminal 1380TL male (MOLEX) or 770147-1 (AMP)

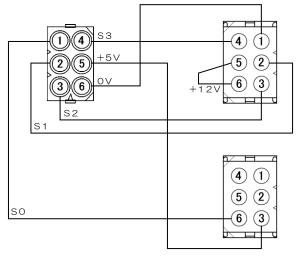


To TOYOTA built-in synchronizer Connector 1261R1 white (MOLEX) or 770086-1 white (AMP) Terminal 1380TL male (MOLEX) or 770147-1 (AMP)

#### (4) TOYOTA FOOT PEDAL MODEL RT-26, RT-27 (XC-CBL-TY-4)

To foot pedal model Connector 1261R1 (MOLEX) or 770086-1 (AMP) Terminal mark 1381ATL (MOLEX) or 770146-1 (AMP) mark 1380TL (MOLEX) or 770147-1 (AMP)

Note: Change the output voltage 5VDC with the jumper JP3. (Refer to page 14.)

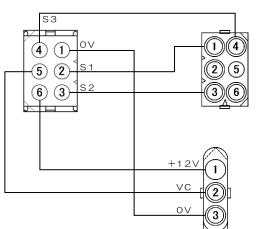


To LIMI-SERVO lever connector Connector 1261P1 white (MOLEX) or 770090-1 white (AMP) Terminal 1380TL male (MOLEX) or 770147-1 (AMP)

To LIMI-SERVO option A connector Connector 1261P1 black (MOLEX) or 770090-1 black (AMP) Terminal 1380TL male (MOLEX) or 770147-1 (AMP)

### (5)TOYOTA VARIABLE SPEED PEDAL (XC-CBL-TY-5)

To LIMI-SERVO lever connector Connector 1261P1 (MOLEX) or 770090-1 (AMP) Terminal mark 1381ATL (MOLEX) or 770146-1 (AMP) mark 1380TL (MOLEX) or 770147-1 (AMP)



To TOYOTA variable speed pedal Connector 1261R1 (MOLEX) or 770086-1 (AMP)

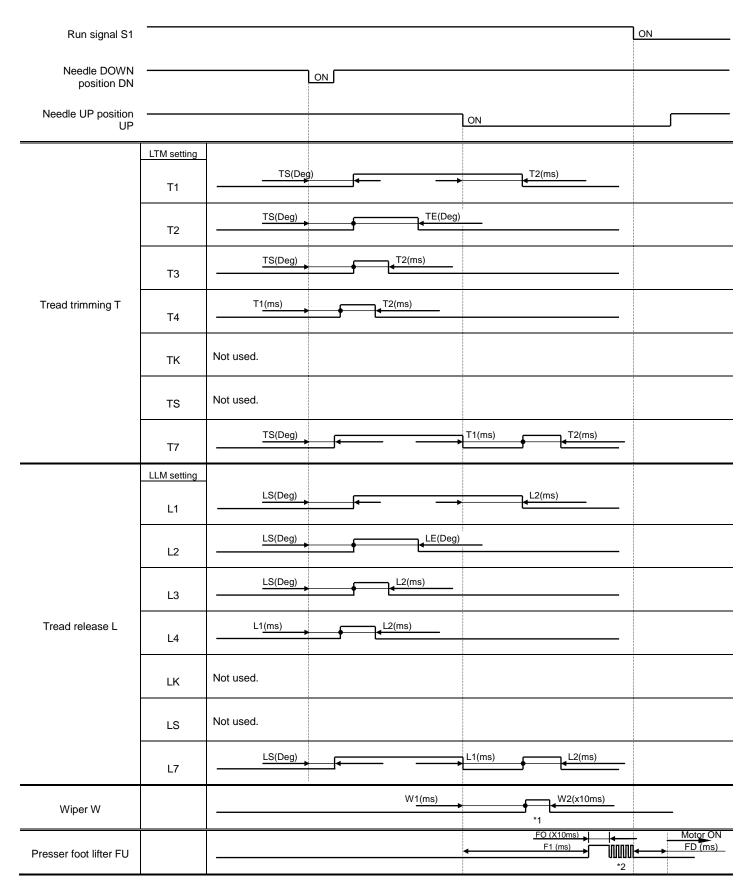
To TOYOTA variable speed pedal Connector 1396R1 black (MOLEX) or 770070-1 black (AMP)

<sup>\*</sup> Turn the program mode [C] function [PDS] ON. Refer to the page 210.

<sup>\*</sup> Turn the program mode [C] function [PDS] ON. Refer to the page 210.

### 15 Setting in the thread trimming mode TR

1. Thread trimming timing when thread trimming mode TR setting is PRG

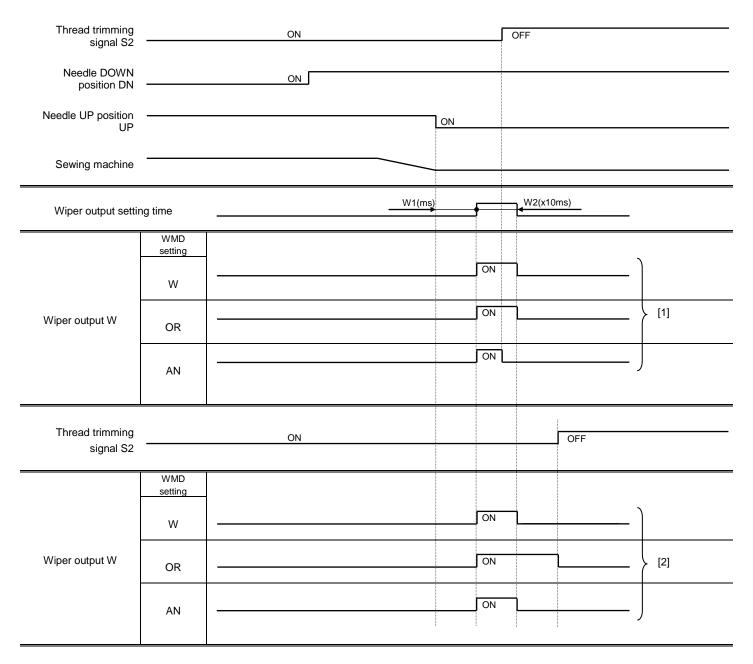


Notes: \*1.The wiper output [W] becomes special operation according to the [G] mode WMD setting, as shown on page 89.

<sup>\*2.</sup>The presser foot lifter [FU] chopping duty can be set with FUD in the [P] and [C] mode.

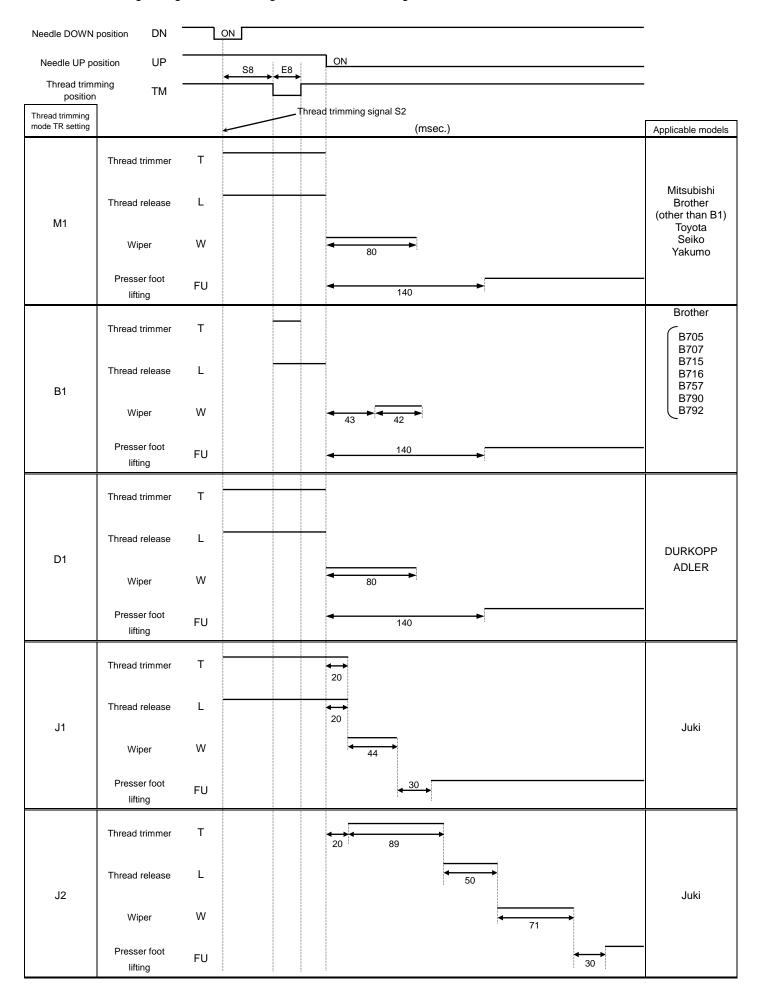
### 2. Wiper output timing

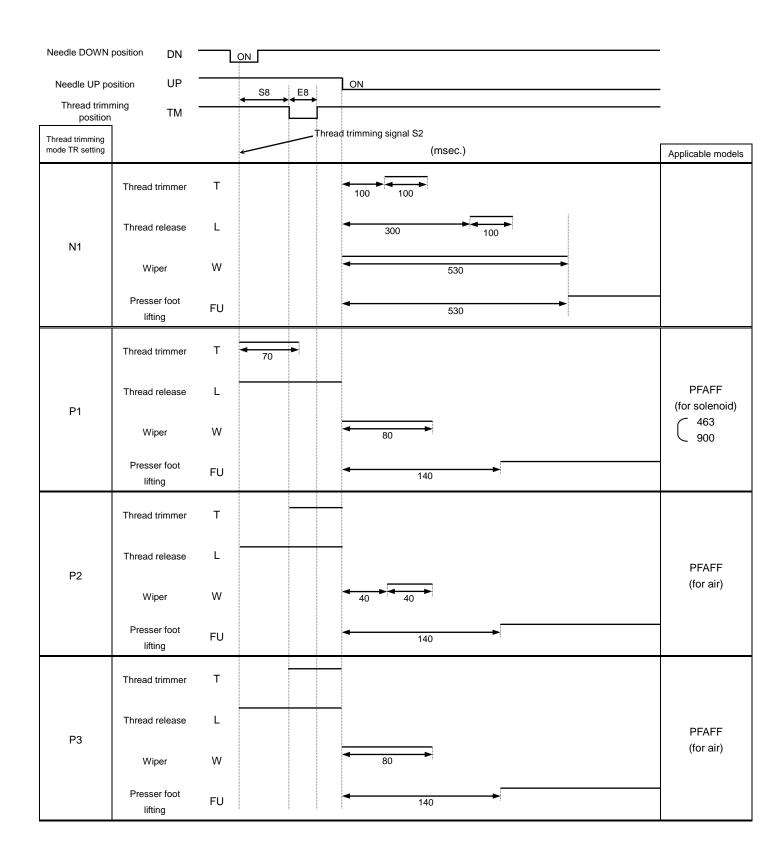
Wiper output OFF timing with (S2) signal by using WMD setting (in program mode G)

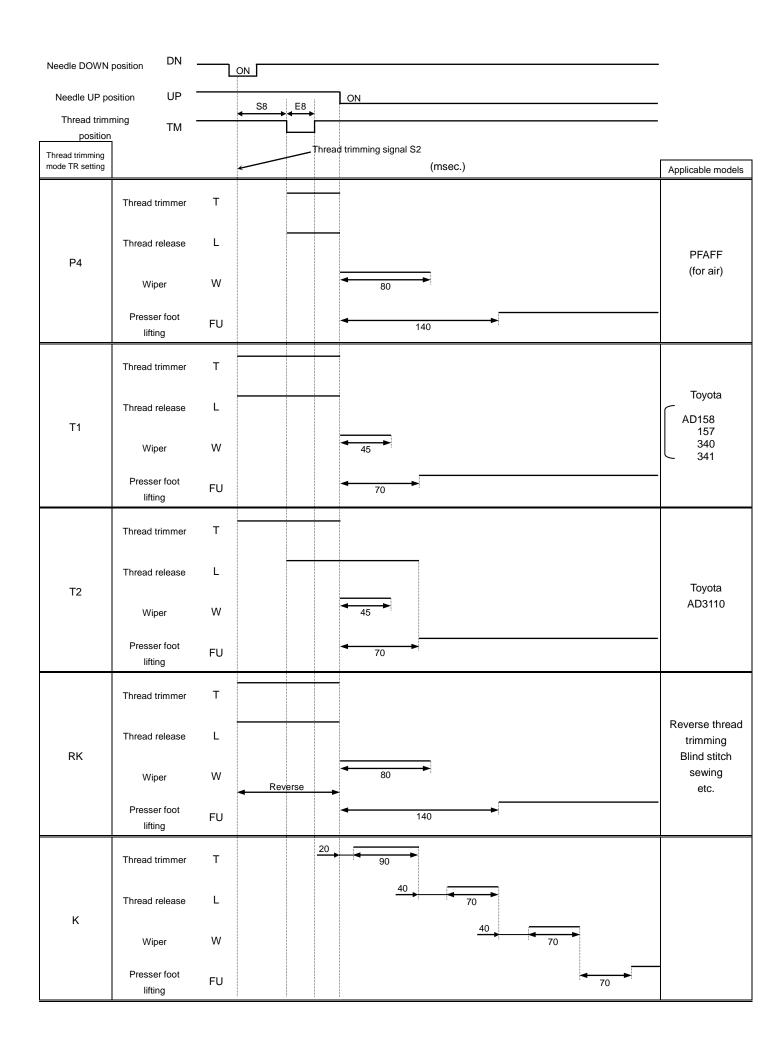


<sup>\*</sup> Wiper output OFF timing is changed by S2 signal OFF timing like above chart [1] and [2].

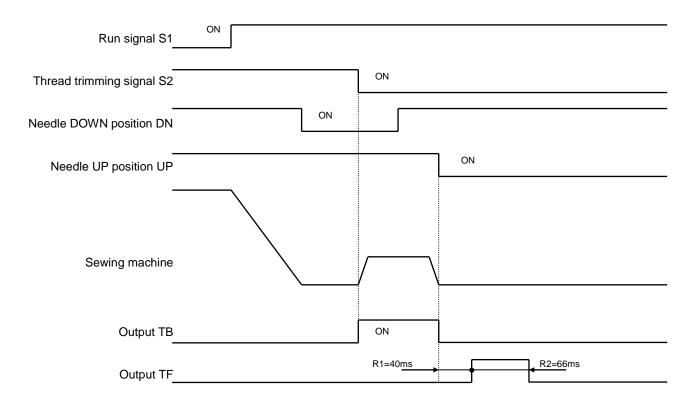
### 3. Thread trimming timing for each setting in the thread trimming mode TR



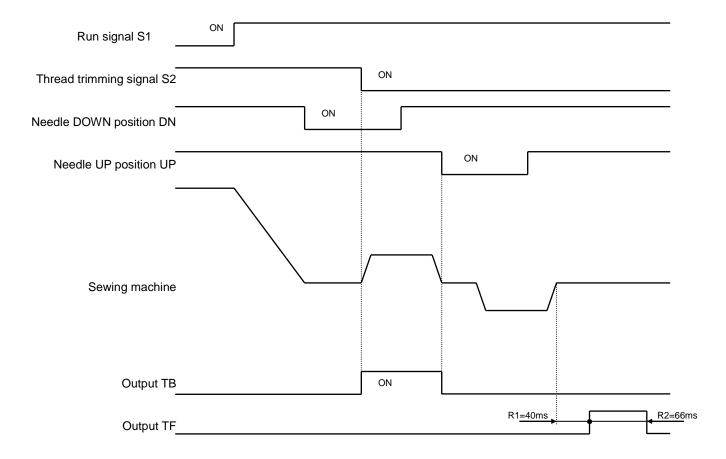




### (1) Output normal timing



### (2) Function setting [RU [ON]] in program mode [P]

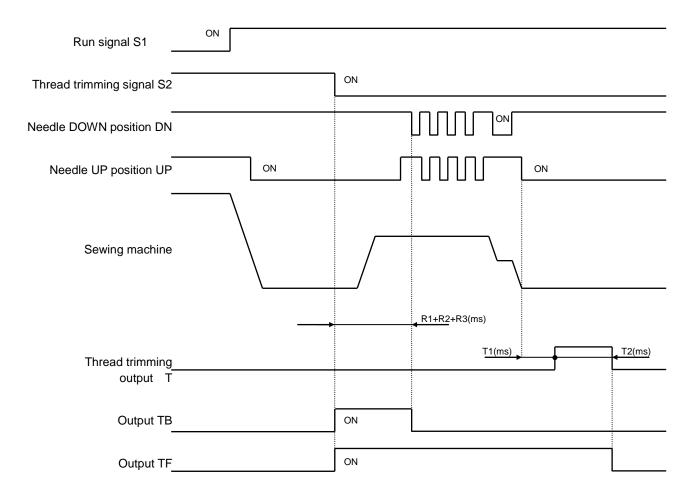


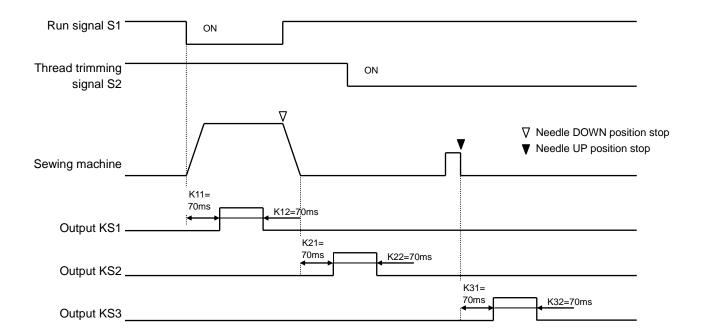
Note 1. The TF output start time can be set with R1 in the  $\left[G\right]$  mode.

The TF output time can be set with R2 in the [G] mode.

2. The above-mentioned timing is function setting [TRM [LK]] in program mode [G].

(3) Chain stitch sewing machine (Condensed stitch is valid.)





Note. The KS1 to KS3 output start time and output time can be set with K11 to K32 in the [S] mode.

#### Caution

This timing chart (sequence) is only available when [SQS] is set to [NO]. When [SQS] is not set to [NO], please refer to "[18] Simple sequence".

### 18 Simple Sequence

The function outputs [KS1], [KS2], [KS3] and [KS4] can be set as simple sequence outputs. To set the simple sequence output, the starting conditions [IN] [T][R][S][TR][SB][GO] are set in the simple sequence starting condition setting function [SQS] of the [S] mode. With this, function outputs [KS1], [KS2], [KS3] and [KS4] will be simple sequence outputs. (The default setting is the [NO] setting.)

#### 1. Simple sequence starting conditions

The simple sequence starting condition setting function [SQS] is as follows.

[NO] : The simple sequence is not started. (The default setting is the [NO] setting.)

(Refer to "[17] Output KS1, KS2, KS3 timings".)

[IN] : When virtual input IO4 is turned ON.[T] : When thread trimming is completed.

[R] : When operation is starting.

[S] : When motor is stopped. (This also includes when single-stitch operation is stopped.)

[TR] : When starting stitching after thread trimming.

[SB] : When start tacking is completed. (If the start tacking setting is "NO", it is when starting stitching after thread trimming.)

[GO] : Always start.

#### 2. Simple sequence forced end conditions

The simple sequence forced end conditions can be set.

[NO] : The simple sequence will not forced end. (The default setting is the [NO] setting.)

[LV] : When virtual input IO5 is ON level.[IN] : When virtual input IO5 is turned ON.[T] : When thread trimming is completed.

[R] : When operation is starting.

[S] : When motor is stopped. (This also includes when single-stitch operation is stopped.)

[TR] : When starting stitching after thread trimming.

[SB] : When start tacking is completed. (If the start tacking setting is "NO", it is when starting stitching after thread trimming.)

#### 3. Simple sequence output starting point setting

The simple sequence output starting point setting [S1S], [S2S], [S3S] and [S4S] can be set.

[KS] : Linked output. (ON edge of the front output)

[IN] : Virtual input ON point. (KS1:IO6, KS2:IO7, KS3:IO8, KS4:IO9)

 $\label{eq:thm:model} [T] \qquad \vdots \qquad \text{When thread trimming is completed.}$ 

[R] : When operation is starting.

[S] : When motor is stopped. (This also includes when single-stitch operation is stopped.)

[TR] : When starting stitching after thread trimming.

[SB] : When start tacking is completed. (If the start tacking setting is "NO", it is when starting stitching after thread trimming.)

#### 4. Simple sequence output end point setting

The simple sequence output end point setting [S1E], [S2E], [S3E] and [S4E] can be set.

[KS] : Linked output. (Each output starting point)

[OF] : Virtual input OFF point. (KS1:IO6, KS2:IO7, KS3:IO8, KS4:IO9)
[IN] : Virtual input ON point. (KS1:IOA, KS2:IOB, KS3:IOC, KS4:IOD)

[T] : When thread trimming is completed.

[R] : When operation is starting.

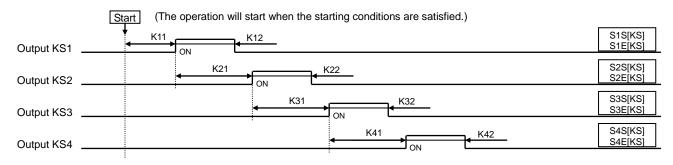
[S] : When motor is stopped. (This also includes when single-stitch operation is stopped.)

[TR] : When starting stitching after thread trimming.

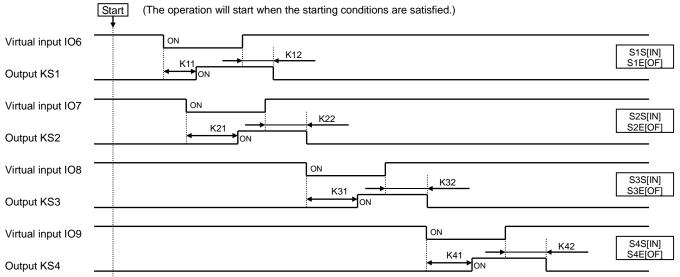
[SB] : When start tacking is completed. (If the start tacking setting is "NO", it is when starting stitching after thread trimming.)

#### 5. Simple sequence output timing chart

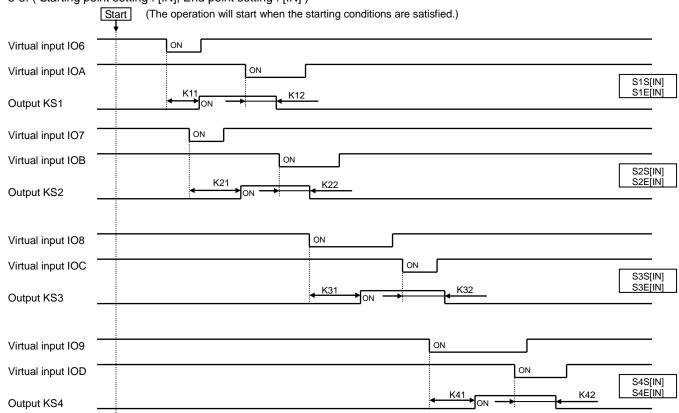
### 5-1. ( Starting point setting : [KS], End point setting : [KS] )



#### 5-2. (Starting point setting: [IN], End point setting: [OF])



#### 5-3. (Starting point setting: [IN], End point setting: [IN])



#### Explanation of setting functions

(a) Sequence output [KS1] [KS2] [KS3] [KS4] output start time/No. of stitch setting changeover [NS1] [NS2] [NS3] [NS4]

[OF] setting : Time setting ([K11] [K21] [K31] [K41] : 10 msec unit)

[ON] setting: No. of stitch setting ([K11] [K21] [K31] [K41])

(b) Sequence output [KS1] [KS2] [KS3] [KS4] output time/No. of stitch setting changeover [NE1] [NE2] [NE3] [NE4]

[OF] setting : Time setting ([K12] [K22] [K32] [K42] : 10 msec unit)

[ON] setting: No. of stitch setting ([K12] [K22] [K32] [K42])

(c) Sequence output [KS1] [KS2] [KS3] [KS4] time setting/No. of stitch setting each by ten times setting [KL1] [KL2] [KL3] [KL4]

[OF] setting: Time setting/No. of stitch setting ([K11][K12], [K21][K22], [K31][K32], [K41][K42])

[ON] setting: Time setting/No. of stitch setting by ten times ([K11][K12]x10, [K21][K22]x10, [K31][K32]x10, [K41][K42]x10)

(d) Sequence output [KS1] [KS2] [KS3] [KS4] time setting by ten times setting [KSL]

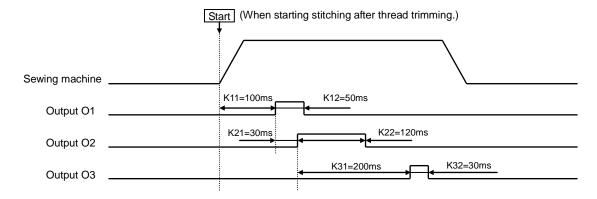
[OF] setting: Time setting ([K11][K12][K21][K22][K31][K32][K41][K42])

[ON] setting: Time setting by ten times ([K11][K12][K21][K22][K31][K32][K41][K42]x10)

Note 1. When using the simple sequence, make each simple sequence related setting shown above, and assign the function output [KS1] [KS2] [KS3] [KS4] to the output setting of the output pin being used by setting the [C] mode output function.

2. If the starting conditions are not set in the simple sequence setting starting condition setting [SQS] above (when [NO] is set), the function output [KS1] [KS2] [KS3] will have the output timing shown on the next page.

When the following timing output is to be output to the option B connector's No.3 pin, No.12 pin and No.15 pin. ([O1],[O2],[O3])



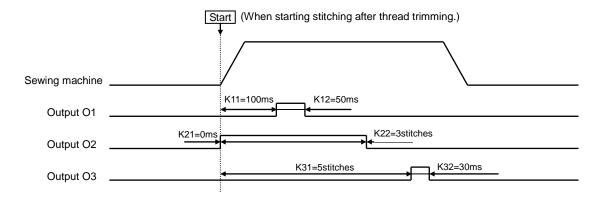
### [ Setting ]

C Mode ([ $\downarrow$ ]+[C] key)

Function	Standard	Setting	Description
O1	OT1	KS1	Selection of output signal function
O2	NCL	KS2	Selection of output signal function
O3	TF	KS3	Selection of output signal function

	• /		
Function	Standard	Setting	Description
SQS	NO	TR	Simple sequence start condition (When starting stitching after thread trimming)
SQE	NO	T	Simple sequence forced end condition (When thread trimming is completed)
S1S	KS	KS	KS1 output starting point setting (Linked output. (ON edge of the front output))
S1E	KS	KS	KS1 output end point setting (Linked output. (Each output starting point))
S2S	KS	KS	KS2 output starting point setting (Linked output. (ON edge of the front output))
S2E	KS	KS	KS2 output end point setting (Linked output. (Each output starting point))
S3S	KS	KS	KS3 output starting point setting (Linked output. (ON edge of the front output))
S3E	KS	KS	KS3 output end point setting (Linked output. (Each output starting point))
K11	7	10	KS1 output start [Time] setting (10x10ms=100ms)
K12	7	5	KS1 output [Time] setting (5x10ms=50ms)
K21	7	3	KS2 output start [Time] setting (3x10ms=30ms)
K22	7	12	KS2 output [Time] setting (12x10ms=120ms)
K31	7	20	KS3 output start [Time] setting (20x10ms=200ms)
K32	7	3	KS3 output [Time] setting (3x10ms=30ms)

2.Example 2 When the following timing output is to be output to the option B connector's No.3 pin, No.12 pin and No.15 pin. ([O1],[O2],[O3])



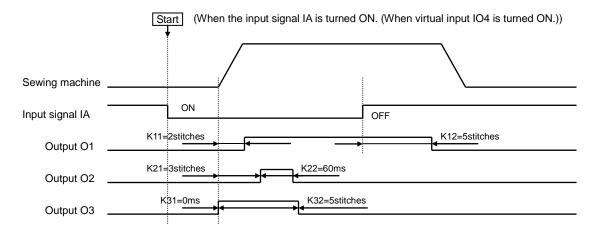
### [ Setting ]

C Mode ( $[\downarrow]+[C]$ key)
----------------------------------

Function	Standard	Setting	Description
O1	OT1	KS1	Selection of output signal function
O2	NCL	KS2	Selection of output signal function
O3	TF	KS3	Selection of output signal function

Function	Standard	Setting	Description
SQS	NO	TR	Simple sequence start condition (When starting stitching after thread trimming)
SQE	NO	T	Simple sequence forced end condition (When thread trimming is completed)
NS1	OF	OF	KS1 output start time/No. of stitch setting changeover (Time count setting)
NE1	OF	OF	KS1 output time/No. of stitch setting changeover (Time count setting)
S1S	KS	TR	KS1 output starting point setting (Linked output. (ON edge of the front output))
S1E	KS	KS	KS1 output end point setting (Linked output. (Each output starting point))
NS2	OF	OF	KS2 output start time/No. of stitch setting changeover (Time count setting)
NE2	OF	ON	KS2 output time/No. of stitch setting changeover (Stitch count setting)
S2S	KS	TR	KS2 output starting point setting (Linked output. (ON edge of the front output))
S2E	KS	KS	KS2 output end point setting (Linked output. (Each output starting point))
NS3	OF	ON	KS3 output start time/No. of stitch setting changeover (Stitch count setting)
NE3	OF	OF	KS3 output time/No. of stitch setting changeover (Time count setting)
S3S	KS	TR	KS3 output starting point setting (Linked output. (ON edge of the front output))
S3E	KS	KS	KS3 output end point setting (Linked output. (Each output starting point))
K11	7	10	KS1 output start [Time] setting (10x10ms=100ms)
K12	7	5	KS1 output [Time] setting (5x10ms=50ms)
K21	7	0	KS2 output start [Time] setting (0ms)
K22	7	3	KS2 output [No. of stitches] setting (3stitches)
K31	7	5	KS3 output start [No. of stitches] setting (5stitches)
K32	7	3	KS3 output [Time] setting (3x10ms=30ms)

By input signal of the option A connector's No.2 pin ([IA]), When the following timing output is to be output to the option B connector's No.3 pin, No.12 pin and No.15 pin. ([O1],[O2],[O3])



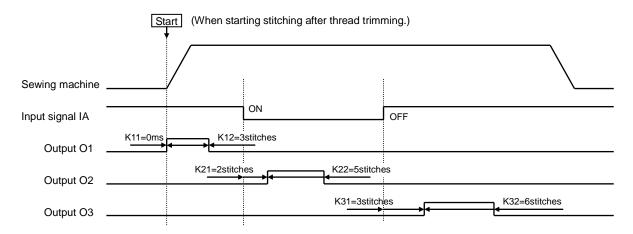
### [ Setting ]

C Mode (	$(\Gamma \cup 1 \cup \Gamma \cap 1)$	kov)
C MOULE		VE A1

Function	Standard	Setting	Description
IA	PSU	104	Selection of input signal function
IM	NO	106	Selection of input signal function
01	OT1	KS1	Selection of output signal function
O2	NCL	KS2	Selection of output signal function
O3	TF	KS3	Selection of output signal function
OM	NO	OT4	Selection of output signal function

Function	Standard	Setting	Description
SQS	NO	IN	Simple sequence start condition (When virtual input IO4 is turned ON.)
SQE	NO	Т	Simple sequence forced end condition (When thread trimming is completed)
NS1	OF	ON	KS1 output start time/No. of stitch setting changeover (Stitch count setting)
NE1	OF	ON	KS1 output time/No. of stitch setting changeover (Stitch count setting)
S1S	KS	TR	KS1 output starting point setting (When starting stitching after thread trimming)
S1E	KS	OF	KS1 output end point setting (Virtual input OFF point. (KS1:IO6))
NS2	OF	ON	KS2 output start time/No. of stitch setting changeover (Stitch count setting)
NE2	OF	OF	KS2 output time/No. of stitch setting changeover (Time count setting)
S2S	KS	TR	KS2 output starting point setting (When starting stitching after thread trimming)
S2E	KS	KS	KS2 output end point setting (Linked output. (Each output starting point))
NS3	OF	OF	KS3 output start time/No. of stitch setting changeover (Time count setting)
NE3	OF	ON	KS3 output time/No. of stitch setting changeover (Stitch count setting)
S3S	KS	TR	KS3 output starting point setting (When starting stitching after thread trimming)
S3E	KS	KS	KS3 output end point setting (Linked output. (Each output starting point))
K11	7	2	KS1 output start [No. of stitches] setting (2stitches)
K12	7	5	KS1 output [No. of stitches] setting (5stitches)
K21	7	3	KS2 output start [No. of stitches] setting (3stitches)
K22	7	6	KS2 output [Time] setting (6x10ms=60ms)
K31	7	0	KS3 output start [Time] setting (0ms)
K32	7	5	KS3 output [No. of stitches] setting (5stitches)

By input signal of the option A connector's No.2 pin ([IA]), When the following timing output is to be output to the option B connector's No.3 pin, No.12 pin and No.15 pin. ([O1],[O2],[O3])



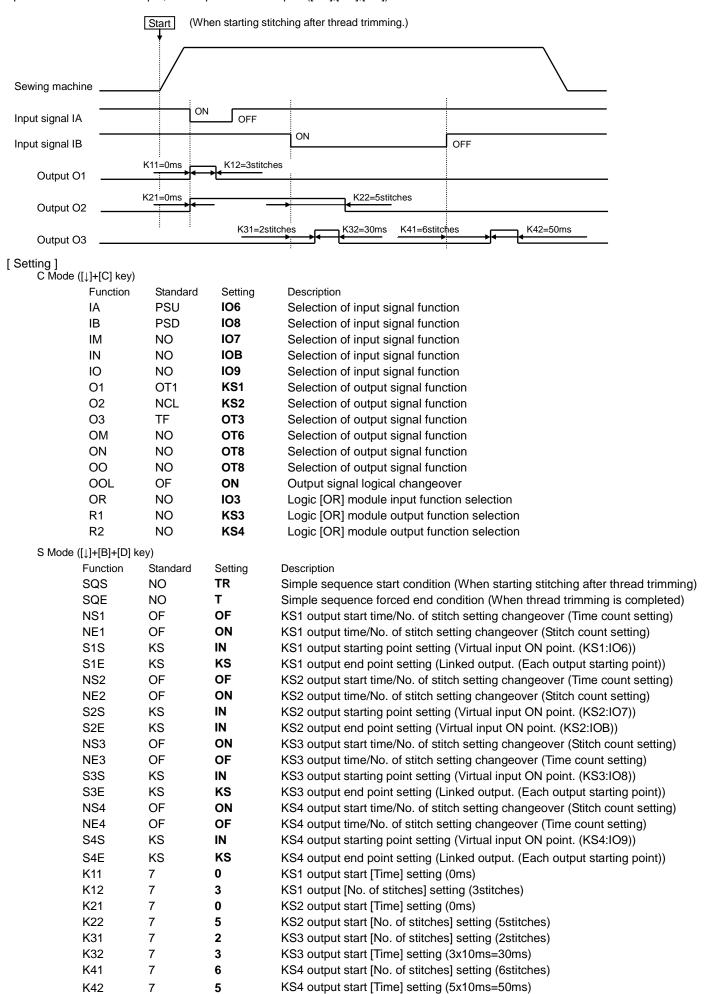
### [ Setting ]

	([⊥]+[C] kev)
CIVIOUE	ULITICI NEVI

Function	Standard	Setting	Description
IA	PSU	107	Selection of input signal function
IM	NO	108	Selection of input signal function
01	OT1	KS1	Selection of output signal function
O2	NCL	KS2	Selection of output signal function
O3	TF	KS3	Selection of output signal function
OM	NO	OT7	Selection of output signal function
OML	OF	ON	Output signal logical changeover

Standard	Setting	Description
NO	TR	Simple sequence start condition (When starting stitching after thread trimming)
NO	Т	Simple sequence forced end condition (When thread trimming is completed)
OF	OF	KS1 output start time/No. of stitch setting changeover (Time count setting)
OF	ON	KS1 output time/No. of stitch setting changeover (Stitch count setting)
KS	TR	KS1 output starting point setting (When starting stitching after thread trimming)
KS	KS	KS1 output end point setting (Linked output. (Each output starting point))
OF	ON	KS2 output start time/No. of stitch setting changeover (Stitch count setting)
OF	ON	KS2 output time/No. of stitch setting changeover (Stitch count setting)
KS	IN	KS2 output starting point setting (Virtual input ON point. (KS2:IO7))
KS	KS	KS2 output end point setting (Linked output. (Each output starting point))
OF	ON	KS3 output start time/No. of stitch setting changeover (Stitch count setting)
OF	ON	KS3 output time/No. of stitch setting changeover (Stitch count setting)
KS	IN	KS3 output starting point setting (Virtual input ON point. (KS3:IO8))
KS	KS	KS3 output end point setting (Linked output. (Each output starting point))
7	0	KS1 output start [Time] setting (0ms)
7	3	KS1 output [No. of stitches] setting (3stitches)
7	2	KS2 output start [No. of stitches] setting (2stitches)
7	5	KS2 output [No. of stitches] setting (5stitches)
7	3	KS3 output start [No. of stitches] setting (3stitches)
7	6	KS3 output [No. of stitches] setting (6stitches)
	NO NO OF OF KS KS OF OF KS KS 7 7 7	NO         TR           NO         T           OF         OF           OF         ON           KS         KS           OF         ON           KS         IN           KS         KS           OF         ON           OF         ON           KS         IN           KS         KS           7         O           7         3           7         5           7         3           7         5           7         3

By input signal of the option A connector's No.2 pin ([IA]) and No.4pin ([IB]), When the following timing output is to be output to the option B connector's No.3 pin, No.12 pin and No.15 pin. ([O1],[O2],[O3])



### 20 How to set Thread break detector

#### 1. Setting Thread break detector function

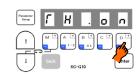
### Call out the program mode [Q] function [TH].

(This can be called with mode call or direct number call. Refer to pages 17 to 20.

(Direct call number = "1416"))

\* Enter program mode [Q]

 $([\downarrow] + [A] + [C] keys)$ 



(2)

(7)

\* Press the [D] key and set the value to "ON".

#### (3)Set the function [TH].

For mode call:  $[\downarrow] + [\uparrow]$ 

Enter For direct number call: Set with

(4) Call out the program mode [C] function [I1].

> (This can be called with mode call or direct number call. Refer to pages 17 to 20.

(Direct call number = "357"))



\* Press the [D] key and set the value to "THI".

#### (6)Call out the program mode [C] function [O1].

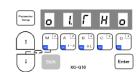
For mode call:  $[\downarrow]$ 

For direct number call: Set with select number [416], and Enter then press

(8) Entering the normal mode

For mode call: [↓] + [↑]

For direct number call: Set with and then press



\* Press the [D] key and set the value to "THO".

### Description

Selection the function on program mode [Q].

[TH.ON]: To use upper thread break detector function, set to "ON"

[TH.OF]: Upper thread break detector function is invalid.

Selection the function on program mode [Q].

[TST.]: Setting the action, after thread was broken.

[NO]: "THO" output function become on and continue to sew.

[TR]: "THO" output function become on and trimming thread.

[ST]: "THO" output function become on and sewing machine will be stooped.

\* When the sewing machine run again, "THO" output will be clear.

[B.]: To set the speed neglect thread break function.

When sewing machine rotation speed become under this speed, it neglect thread break function.

[THS.]: To set the stitch numbers to neglect thread break function, after sewing machine speed becomes over "B" speed.

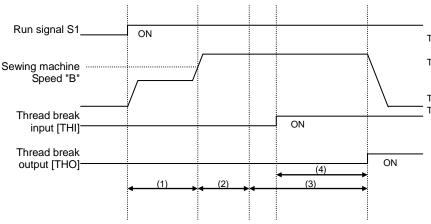
[THF.]: Setting the judgment stitch amount of thread break.

Selection the function on program mode [C].

[I1.THI]: No. 6 pin of option connector B will be set to thread break input function.

[O1.THO]: No. 3 pin of option connector B will be set to thread break output function.

#### 2. Timing chart of thread break input and output.



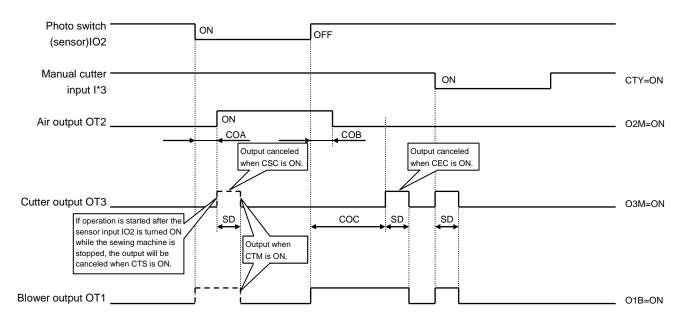
Term (1): Sewing machine speed is under "B" speed, so it neglect thread break function.

Term (2): After sewing machine speed become over "B" speed, still under "THS" stitch amount, so it neglect thread break function.

Term (3): Thread break function is valid.

Term (4): The judgment stitch amount "THF" of thread break. after this stitch amount, thread break function move to "TST" function.

#### 1. Cutter output function



(Note) Use of the I\*1 input is prohibited when using the blower output.

F mode setting

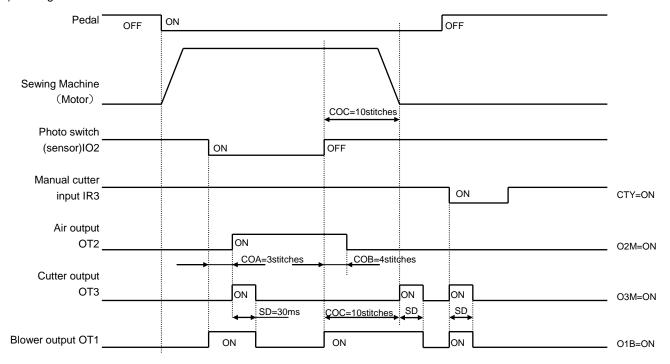
Function name	Specification
O1B	Set OT1 output to blower output.
O2M	Set OT2 output to air output.
O3M	Set OT3 output to cutter output.
I2M	Add mesh judgment control to IO2 input. (If output stays ON or OFF for longer than the mesh judgment time set with ED, the IO2 input will not be fixed.)
CTY	Set I*3 input to manual cutter input.
CTM	Set OT3 cutter output to both OFF→ON and ON→OFF of IO2 photo switch.
COA	No. of stitches A
COB	No. of stitches B
COC	No. of stitches C
SD	Cutter ON time
ED	Mesh judgment time
CSC	The output of the automatic cutter output is prohibited while the sensor is ON.
CEC	The output of the automatic cutter output is prohibited while the sensor is OFF.
CTS	The output of the automatic cutter output is prohibited when the sensor input is ON while the sewing machine is stopped.

Note 1.Always set O2M to ON even when not using the air output.

2. Customize the option connectors I1, I2 and O1 to O3 to the required functions using the program mode beforehand.

### 2. Setting example of the Cutter output function

### 1). Timing



### 2). Setting

C Mode ([↓]+[C] k	.ey)	
-------------------	------	--

Function	Standard	Setting	Description
IA	PSU	IO2	Input signal select (Sensor signal)
<b>I</b> 1	IO1	IR3	Input signal select (Manual cutter input)
O1	OT1	OT1	Output signal select (Blower output)
O2	NCL	OT2	Output signal select (Air output)
O3	TF	OT3	Output signal select (Cutter output)

30

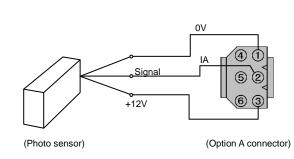
### F Mode ([ $\downarrow$ ]+[ $\uparrow$ ]+[B] key)

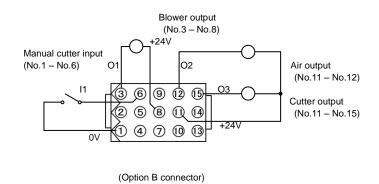
Function	Standard	Setting	Description
O1B	OF	ON	Set OT1 output to blower output.
O2M	OF	ON	Set OT2 output to air output.
ОЗМ	OF	ON	Set OT3 output to cutter output.
CTY	OF	ON	Set I*3 input to manual cutter input.
CTM	OF	ON	Set OT3 cutter output to both OFF→ON and ON→OFF of IO2 photo switch.
CTS	OF	ON	Cutter output prohibit when sensor is ON while stopped
CAT	OF	ON	Automatic thread trim setting after cutter sensor is turned off
COA	0	3	No. of stitches (0~99 stitches)
COB	0	4	No. of stitches (0~99 stitches)
COC	0	10	No. of stitches (0~99 stitches)

Cutter ON time (0~508msec)

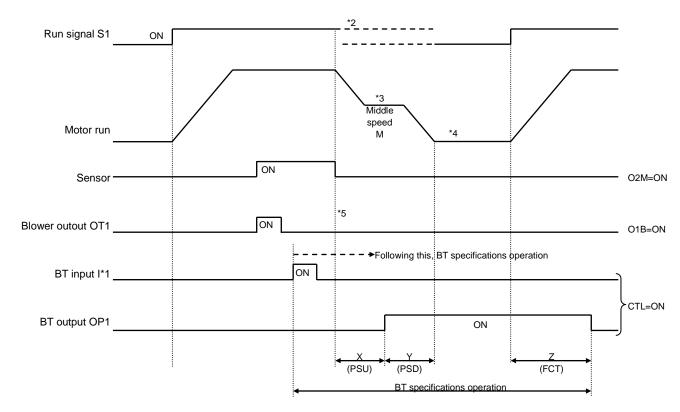
#### 3). Wiring example

SD





### 3. BT specifications (\*1) operation chart and required settings

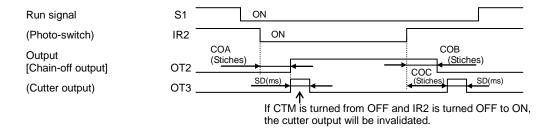


- \*1 : When CTL is set to ON, the BT specifications operation will be applied after the I\*1 input turns ON. (If the BT output is turned OFF after I\*1 turns OFF, the BT specifications will be canceled.)
- \*2 : S1 is invalidated after the photo sensor detection. Operation will restart after stopping and then turning S1 OFF and ON.
- \*3: Medium speed preset stitching when photo sensor turns OFF after BT input.
- \*4 : Up position stop after thread trimming.
- \*5 : Not output when photo sensor is OFF after BT input.

### Note 1.Always set O2M to ON even when not using the air output.

- 2.Customize the option connectors I1, I2 and O1 to O3 to the required functions using the program mode beforehand.
- 3. The No. of stitch settings PSU, PSD and FCT are common with the other settings. Thus, when using as the BT specifications, the PSU/PSD input and the function that automatically lowers the presser with a timer cannot be used.

#### 4. How to set the tape cutter operation 1



(1) Function setting of the program mode [C]
Ex. function setting [I1. IR2] + [O1. OT2] + [O2. OT3]

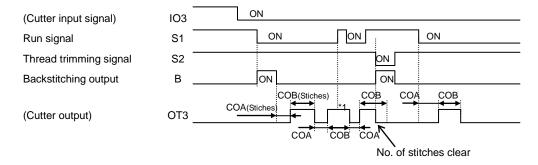
(2) Function setting of the program mode [F]

1) Function setting [CTM. ON] : Cutter output mode

2) Function setting [O2M. ON] : Operation mode of output OT2
3) Function setting [O3M. ON] : Operation mode of output OT3
4) Function setting [COA. \*\*] : No. of stitches COA setting
5) Function setting [COB. \*\*] : No. of stitches COB setting
6) Function setting [COC. \*\*] : No. of stitches COC setting
7) Function setting [SD. \*\*\*] : Cutter output time SD setting

Note 1. Always set the F mode function CTR to OFF when using this operation.

#### 5. How to set the tape cutter operation 2



(1) Function setting of the program mode [C] Ex. function setting [I1. IO3] + [O1. OT3]

(2) Function setting of the program mode [F]

Function setting [CTR. ON]
 Cutter output mode
 Function setting [COA. \*\*]
 No. of stitches COA setting
 Function setting [COB. \*\*]
 No. of stitches COB setting

Note 1. Function setting [IO3]: When the cutter input signal is set to IO3, the cutter output will not turn OFF even if the sewing machine is stopped during No. of stitches [COB] counting. (\*1)

- 2. Function setting [IR3]: When the cutter input signal is set to IR3, the cutter output will turn OFF when the sewing machine is stopped during No. of stitches [COB] counting.
- 3. Always set the F mode functions CTY, CTM, O2M, O3M to OFF when using this operation.

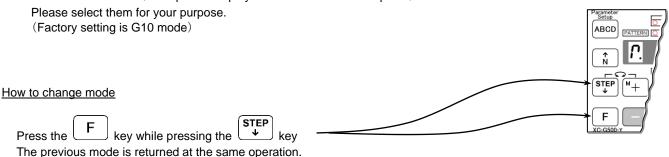
Control switch panel applications

1. Examples of using control switch panel

## SELECTION OF MODE

There are 2 kinds of modes in the control panel

- 1) G10 mode : Display of setting data for control box like sewing machine direction, sewing machine speed and so on. (The same display as the XC-G10 control panel)
- 2) Control panel mode : Display of back tacking data, program input data, teaching input data and so on. (The specific display of the XC-G500 control panel)



Note: Mode is not changed while the is lighted on control panel mode.

Press the tweeters will be the two the two that the tweeters is the light, it is possible to change mode.

## Settings Data Copy Function

The control panel can be used to read the machine control box settings data and write to another control box.

Reading Settings Data (Control Box → Control Panel)

- (1) Turn ON the power while pressing the ABCD key. The display will indicate
- (2) Turn the key ON to copy the settings data from the control box to the control panel.
- (3) Copying is completed successfully if the normal display appears after several tens of seconds. If M5 (15) displays, an error has occurred. Use the following procedure to perform the operation again.
  - 1) Turn the power OFF.  $\rightarrow$  2) Turn OFF the M5 display.
    - $\rightarrow$  3) Inspect the connector connection.  $\rightarrow$  4) Repeat the operation from step 1.

Writing Settings Data (Control Panel → Control Box)

- (1) Turn ON the power while pressing the key. The display will indicate
- (2) Turn the key ON to copy the settings data from the control panel to the control box.
- (3) Copying is completed successfully if the normal display appears after ten seconds. If M5 (15) displays, an error has occurred. Use the following procedure to perform the operation again.
  - 1) Turn the power OFF.  $\rightarrow$  2) Turn OFF the M5 display.  $\rightarrow$  3) Check the control box voltage/model.
    - $\rightarrow$  4) Inspect the connector connection.  $\rightarrow$  5) Repeat the operation from step 1.

Notes: 1. The settings data cannot be written if the voltage and model (control box model name) do not match. (M5 ( , , , ) displays.)

2. Never disconnect the control panel while reading or writing settings data. Control box operation after disconnection cannot be guaranteed.

Speed limit limiter changeover

### 2. Changing the speed limit limiter for the maximum speed using the switches

• Applicable control box : XC-GMF

• Working specifications : The high-speed speed limit limiter is changed with the switch.

(Variable-speed operation is carried out with the variable-speed pedal XC-CVS-2.)

[Setting] (For example, to change the high-speed speed limit between 2000 rotations and 600 rotations.)

(1). For example, set the Mitsubishi sewing machine simple setting (Direct call number = "1423") LU2-4410 or LU2-4430 for the model setting.

(2) Q mode ([ $\downarrow$ ] + [A] + [C] key)

Function [LIM. OF]  $\rightarrow$  [LIM.ON]

(Set the speed limit during OT1 output ON to medium speed M.)

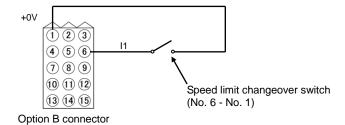
(3) P mode ( $[\downarrow]$  +  $[\uparrow]$  key)

Set the medium speed setting to 600 rotations.

[M. 800]

[M. 600] (Direct call number = "0005")

[Connection]



Caution 1: When the switch is OFF, the normal speed limit (2000 rotations) will be applied. When the switch is ON, the speed will be limited to the medium speed M setting value (600 rotations).

Caution 2: Do not use the 01 (OT1) output. (Do not connect.)

Caution 3: When using only 2 pin with the option B connector, the connector could dislocate easily with vibration. Thus, insert an empty pin into the pins that are not being used.

Variable-speed pedal + separate switch operation

3. Special operation using option B connector variable-speed command VC2 (The speed can be adjusted with the digital potentiometer on the setting panel.)

• Applicable control box : XC-GMF

• Working specifications : High-speed operation using variable-speed pedal (XC-CVS-2) and separate switch

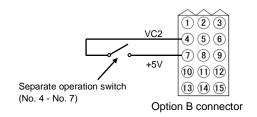
(Digital keys C and D on the control panel is valid)

[Setting]

Q mode setting (  $[\downarrow]$  + [A] + [C] keys)

- VC2=VC  $\rightarrow$  VC2=VS
(Direct call number = "1405")

[Connection]



### 4. Example of down counter function application settings

### Operation

Number of count stitches: 900 stitches.

The number of stitches is displayed on the control box or control switch panel.

Thread trimming (pedal heeling operation) is carried out while stitching (while counting).

After 900 stitches are counted, the needle stops at the DOWN position, and further stitching is prohibited. The thread is trimmed with pedal heeling, and then the automatic counter is cleared.

### [Setting]

```
B mode ([\downarrow]+[B] key)
                          (Direct call number = "0201")
  N=900
  D=900
                          (Direct call number = "0202")
  CDN=ST
                          (Direct call number = "0210")
  DSC=ST
                          (Direct call number = "0211")
  DNC=ON
                          (Direct call number = "0213")
  CNU=1
                          (Direct call number = "0217")
C mode ([\downarrow]+[C] key)
  CNF=DN (For XC-G500Y type control box display)
                                                                    (Direct call number = "0529")
  IM=PSD
                         (Direct call number = "0339")
  IN=CCD
                         (Direct call number = "0342")
  OM=CDE
                         (Direct call number = "0449")
  ON=OT2
                          (Direct call number = "0453")
  A1=IO2
                          (Direct call number = "0477")
  N1=CDE
                         (Direct call number = "0480")
  N2=T(or, N2 = KS3:
                            when counter clearing is mistaken with pedal heeling)
                                                                                         (Direct call number = "0482")
P mode ([\downarrow] + [\uparrow] key)
  PSD = 0 stitches (default value)
```

Note that when stitching at a high speed, the needle will stop at the DOWN position after stitching the number of stitches instead of following the counter setting value. (After the set number of stitches are counted, PSD stop will take place with the count end signal, so the needle will not stop immediately.) Thus, set the number of stitches for the down counter setting value as a value obtained by subtracting several stitches (number of stitches exceeded to the DOWN position) in respect to the number of stitches to be actually stitched. (In this case, the excessive number of stitches will be displayed as a minus value.)

Add the following setting when a minus count is not to be displayed.

```
B mode ([\downarrow]+[B] key)

NXD = ON (Direct call number = "0214")
```

Note that in this case, the display will stop at "0". However, the down counter setting value and the number of excessive stitches during actual stitching will differ in the same manner as above.

```
In the above setting example,
```

```
B mode ([↓]+[B] key)

If the B mode is set to CNU = 10 (stitches), set N = 90 and D = 90 (For 900 stitches)

B mode ([↓]+[B] key)

In this case, the B mode NXD = ON does not need to be set. (Set NXD to OFF)
```

One count will consist of 10 stitches, and 90 will be counted (900 stitches to 909 stitches). In other words, the actual number of stitches will be between 900 stitches and 909 stitches.

(The number of excessive stitches when stopping at the DOWN position (PSD stop) will be within these ten stitches.)

- 5. Example of using the counter function (turning on a lamp using a relay when the count is completed)
- Use the down counter as a bobbin thread level counter (end count at 10,000 stitches), and after ending count turn on lamp using a relay.

#### [Setting]

# C Mode ([ $\downarrow$ ]+[C] key)

Eunction

runctio	лі	Stariuaru	Setting	Description
14	(Direct call number = "0378")	NO	CCD	Input signal function selection
O3	(Direct call number = "0426")	TF	CDE	Output signal function selection

Ctondord

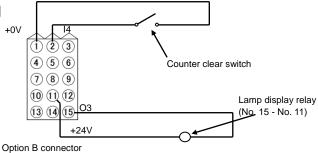
# B mode ([↓]+[B] key)

mode (	[♥]Ŧ[D] KGy)			
Functi	on	Standard	Setting	Description
Ν	(Direct call number = "0201")	99	1000	Down counter value setting
CDN	(Direct call number = "0210")	CU	ST	Count by number of stitches setting
DSC	(Direct call number = "0211")	ST	ST	Operation at end of down counter count selection
DNC	(Direct call number = "0213")	OF	ON	Down counter validity setting
CNU	(Direct call number = "0217")	1	10	Number of stitches per counter setting

Sotting

Description

# [Connection example]



- Cautions) 1: Prepare the lamp (display lamp) and lamp power supply separately. (Power (current capacity) sufficient to turn the lamp on cannot be supplied from the control box.)
  - 2: Use a 24V compatible relay. Contact Mitsubishi when using a 12V relay.
  - 3: When using the control box (XC-G500-Y), a buzzer will sound with the above setting. (In addition, the counter can be displayed on the control box, and the counter can be cleared with the P key on the control box, etc.)

Counter function applications 3

(Option B connector pin No. 9)

6. Example of setting two counters (Using the up counter and down counter simultaneously)

[Setting example] 1) Down counter setting (Example: Count 10,000 stitches)

# B mode ([↓]+[B] key)

Funct	tion	Standard	Setting	Description
N	(Direct call number = "0201")	99	1000	Down counter setting
D	(Direct call number = "0202")	99	1000	Current down counter value
CDN	(Direct call number = "0210")	CU	ST	Down counter count conditions
				(Count with number of stitches)
DSC	(Direct call number = "0211")	ST	ST	Operation at end of down counter count selection
DNC	(Direct call number = "0213")	OF	ON	Down counter validity
CNU	(Direct call number = "0217")	1	10	Number of stitches per count setting
C Mode (	[↓]+[C] key)			
Funct	tion	Standard	Setting	Description
I1	(Direct call number = "0357")	IO1	CCD	Input signal selection (down counter clear signal) (Option B connector pin No. 6)

# [Setting example] 2) Up counter setting (Example: Count 12,000 stitches)

# B mode ([↓]+[B] key)

B mode ([	√]+[B] key)			
Funct	ion	Standard	Setting	Description
Р	(Direct call number = "0203")	99	1200	Up counter setting
U	(Direct call number = "0204")	0	0	Current up counter value
CUP	(Direct call number = "0205")	CU	ST	Up counter count conditions
				(Count with number of stitches)
USC	(Direct call number = "0206")	ST	ST	Operation at end of up counter count selection
UPC	(Direct call number = "0208")	OF	ON	Up counter validity
C Mode ([	[↓]+[C] key)			
Funct	ion	Standard	Setting	Description
12	(Direct call number = "0370")	U	CCU	Input signal selection (up counter clear signal)

- 7. Setting points for post-type sewing machine
- 1. Sewing machine model : Post-type sewing machine
- 2. Applicable control box : XC-GMF type
- 3. Details of fault : Stop position inconsistency, overrunning, etc.
- 4. Setting points (In respect to standard setting value or ultra-thick material setting value)
  - (1) If the sewing machine has a belt longer than a normal sewing machine, the [GA. LL] setting is valid for the gain setting [GA.]. If the belt is not long, or if the sewing machine pulley is not large, the [GA.L] or [GA.H] setting is more effective. If the torque or power at the start of stitching is a problem, the [GA.H] setting is more effective.
  - (2) When using the sewing machine for ultra-thick material or the post-type sewing machine, the pulley may be larger than the normal sewing machine. Set the size of the pulley on the sewing machine being used, and the size of the pulley on the motor.

A mode : [PL.ON] (Direct call number = "0109") (Pulley ratio manual setting)

[MR.\*\*\*] (Direct call number = "0110") (Motor side pulley diameter setting)

[SR.\*\*\*] (Direct call number = "0111") (Sewing machine side pulley diameter setting)

(3) Speed setting

If the stop position is inconsistent or if overrunning occurs when stopping from high-speed operation, lower the high-speed setting value.

P mode : **[H.2000]** (Direct call number = "0000") (For example, even if the sewing machine specification is 3000 rotations, lower the setting value.)

If the stop position is inconsistent when stopping from low-speed operation or inching, lower the low-speed setting value.

P mode : **[L. 150]** (Direct call number = "0001") (For example, 150 rotations, etc.)

If the stop position is inconsistent when stopping with pedal healing needle lift (thread trimming), lower the needle lifting speed setting.

P mode : **[T. 150]** (Direct call number = "0002") (For example, 150 rotations, etc.)

(4) Set the deceleration time for stopping to a large value. (Note that this will delay the time for stopping.) Set the deceleration time in [DC.-]. Set the deceleration time to a value larger than the [DCT.16] setting value.

A mode : [DC. -] (Direct call number = "0104")

[DCT. 30] (Direct call number = "0105") (For example, 30, etc.)

(5) Braking time at sewing machine stop (Use the original setting value if this does not need to be improved.)
In addition to changing the deceleration time in item (4) above, increase the braking time setting value for stopping the

In addition to changing the deceleration time in item (4) above, increase the braking time setting value for stopping the sewing machine.

A mode : **[BKT. 30]** (Direct call number = "0115") (For example, 30 (30 x 10msec = 300msec), etc.)

(6)When the stop position deviates during DOWN position stop (2-position) Do not set the needle DOWN stop position angle (coasting angle) setting [D8.] to less than the default setting [28].

### Set [D8.] to a value larger than [28].

(This is effective when the sewing machine does not stop at the DOWN position.)

P mode : **[D8. 50]** (Direct call number = "0054") (For example, 50 degrees, etc.)

(7)When the stop position deviates during UP position stop (1-position or needle lifting (thread trimming)) Do not set the needle UP stop position angle (coasting angle) setting [U8.] to less than the default value [14].

#### Set [U8.] to a value larger than [14].

(This is effective when the sewing machine does not stop at the UP position.)

P mode : **[U8. 50]** (Direct call number = "0055") (For example, 50 degrees, etc.)

#### Caution) Adjust the DOWN and UP stop positions with the detector.

(When changing the [U8.] setting value, always adjust the detector's coupler.)

(When changing the [D8.] setting value, always adjust the detector's DOWN position disk.)

(8) If the A mode speed loop stop setting [STM.] does not pose a problem with normal starting or stopping, set [STM. OF]. (This may be effective for ultra-thick material sewing machines, but is not very effective for the post-type sewing machine.)

(9) The effectiveness of the following settings for the post-type sewing machine is not cleared, but can be tried.

(9-1) K mode function setting [NAN. ON] (Deceleration immediately when operation signal turns OFF.)

(9-2) K mode function setting [HWG. ON] (Large inertia sewing machine operation gain valid)

( K mode : ( $[\ \downarrow\ ] + [\ \uparrow\ ] + [\ A] + [\ C]$  key ) )

(10)When degree of pedal pressing does not feel correct during 1-stitch sewing with pedal or inching

A mode : **[SC. ON]** (Direct call number = "0106") (S-pattern cushion valid at start)

[SCT. 7] (Direct call number = "0107") (S-pattern cushion time setting. Increase this value slightly

as required.)

Set and adjust the sewing machine referring to the above points.

<sup>\*</sup> For 1-stitch sewing, the K mode function setting [NAN.ON] in item (9-1) above is also effective.

### Methods of fixing needle stop position to left and right sides using zigzag sewing machine

## Setting example 1. Using the K mode function [ZNC.]

With the zigzag sewing machine, the number of zigzag stitches (shifting width) can be set.

- (1) K mode: Press the four keys  $[\downarrow] + [\uparrow] + [A] + [C]$ , and enter the K mode.
- (2) Next, press the  $[\uparrow]$  or  $[\downarrow]$  key several times, and display the function [ZNC.]. (Direct call number = "1240") The following display will appear.

E n C. 0

(3) Press the [D] key, and set the number of zigzag stitches (shifting width). For example, to stop at either the left or right side after zigzagging for four points, set the number of stitches to 3. The following display will appear.



(4) To always stop at the left side or at the right side, set the number of stitches to 6. The following display will appear.



Caution: With the K mode function [ZNC.], the sewing machine will stop at each of the set number of stitches.

When using the zigzag sewing machine with automatic thread trimmer, or when using 2-position setting (needle DOWN stop setting) etc, the stop position could deviate and may not stop at the end depending on the stitching start position. In this case, carry out the settings given in example 2 below.

## Setting example 2. Using the back tacking function

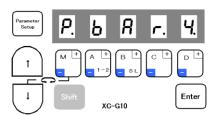
(Note that when using the back tacking function, start/end tacking (automatic repeat sewing) cannot be used.) An example for 4-point zigzag sewing is given below. For other cases, change the number of stitches. (Note: When setting example 1 above has been set, always return the function [ZNC.] setting to [ZNC.0].)

1 Using the control box (without control switch panel)

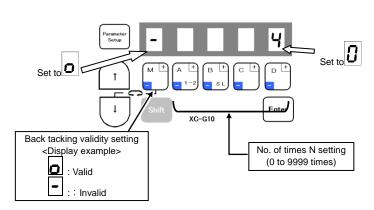
(1) Select the pattern sewing mode with the setting panel on the control box.

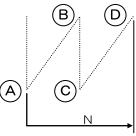
Key operation	Display
<b>(</b>	* The pattern No. selection mode will appear.
Press key four times from normal mode.	P. 5 F r. I.

(2) In the pattern sewing mode, set the back tacking mode (pattern 4). Press the [D] key and set the pattern No. to 4. (Back tacking mode) The following display will appear.



- (3) Next, press the  $[\downarrow]$  key, and set the back tacking validity and the number of times.
  - Set the back tacking validity setting to [Valid].
  - Set the number of back tacking times N to "0".



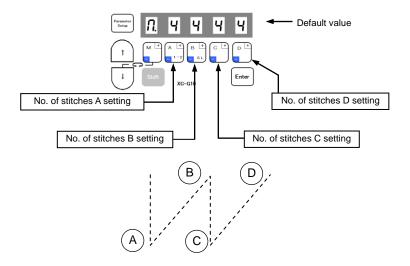


If the number of times N is set to 3, stitching will take place in the order of A, B, C.

If N is set to 5, the order will be A, B, C, D, C.

If N is set to 6 or higher, the order will be A, B, C, D, C, D... (When N is set to 0, the tacking operation will be continued in the order of A, B, C, D, C, D ... while the pedal is pressed down.

(4) Next, press the [↓] key, and enter the number of back tacking stitch setting mode, and set the number of stitches for A, B, C and D.



With this setting, the following can be determined:

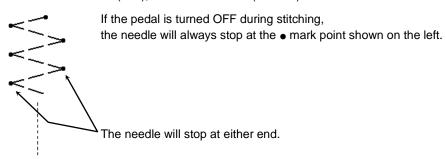
A: Stop needle at either left end or right end.

B: Fix needle stop position to left end or right end.

the following can be determined:

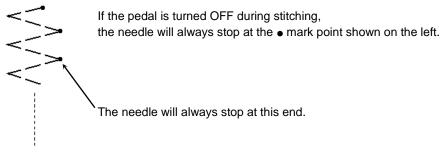
(4-1) A: Stop needle at left end or right end.

Set the number of stitches to A = 2 (or 3), and B = C = D = 3 (stitches).



(4-2) B: Fix needle stop position to left end or right end.

Set the number of stitches to A = 5 (or 6), and B = C = D = 6 (stitches).



Caution: 1. N is set to 0, so while the pedal is pressed down,

the stitches will be repeatedly stitched in the order of A, B, C, D, C, D, C, D ....

C and D are repeated.

To eliminate the A and B stitches, set A and B to 0 stitches.

- 2. This explanation is for 4-point zigzag, so change the number of stitches for other types of zigzag.
- 3. The back tacking mode is used, so the automatic tacking (start/end tacking) and touch back output cannot be used.
- 2 Using the control switch panel (XC-G500-Y)

When using the control switch panel, refer to the respective manual, and set the number of times and stitches in the same manner in the back tacking settings.

Zigzag sewing machine applications

3 Set the various settings for the program mode.

(1) Set the stitching speed for back tacking to variable-speed.

- In the normal mode, hold down the [↓] key, and press the [D] key for two or more seconds to enter the program D mode.
- When in the D mode, press the [D] key several times, and display the function [D1.D]. (Direct call number = "0600") The following display will appear.

d 1. d

- Next, press the [↓] several times, and display the tacking alignment function [BM]. (Direct call number = "0603") Press the [D] key, and set the function [BM.ON]. The following display will appear.



- After making the above setting, press the [↓] and [↑] keys simultaneously to return to the normal mode.
- (2) Change the speed setting limiter for the back tacking speed.
  - In the normal mode, hold down the [↓] key, and press the [D] key for two or more seconds to enter the program H mode.
  - Next, press the [↓] key several times, and display the tacking speed limiter function [LNH.]. (Direct call number = "1006") Press the [C] key several times, and set [LNH.90]. The following display will appear.

L n H 9 0

- After making the above setting, press the [1] and [1] keys simultaneously to return to the normal mode.
- (3) Change the backtacking speed.
  - In the normal mode, hold down the [↓] key, and press the [↑] key for two or more seconds to enter the program P mode.
  - First, confirm the maximum speed setting [H.]. (Direct call number = "0000") (If the value must be changed, press the key below the value, and set the required speed.)
  - Next, press the [↓] key several times, and display the start tacking speed setting [N.]. (Direct call number = "0003") Press the [A] key and [B] key to set the same value as that set for the maximum speed above.
  - Next, press the [↓] key, and display the end tacking speed setting [V.]. (Direct call number = "0004")
     In the same manner, press the [A] and [B] keys to set the same value as that set for the maximum speed above.
     (Set the start tacking speed and end tacking speed values to the same value.)
  - After making the above setting, press the [1] and [1] keys simultaneously to return to the normal mode.
- (4) To trim thread at an angle when heeling while sewing with a zigzag machine with thread trimmer.
  - In the normal mode, hold down the  $[\downarrow]$  key, and press the  $[\uparrow]$  + [A] + [C] key for two or more seconds to enter the program K mode.
  - Next, press the [↓] key several times, and display the special setting function [CDR. ON]. (Direct call number = "1239") Press the [D] key, and set the function [CDR. ON]. The following display will appear.



- After making the above setting, press the [↓] and [↑] keys simultaneously to return to the normal mode.
- (5) To carry out manual touch back when using a zigzag machine with touch back switch.

(Note that automatic repeat sewing such as start/end tacking cannot be used.)

- Connect the touch back switch between the sewing machine connectors No. 9 and No. 10. Connect the repeat sewing output solenoid between the sewing machine connectors No. 11 and No. 12.
- In the normal mode, hold down the [↓] key, and press the [C] key for two or more seconds to enter the program C mode.
- Next, press the  $[\downarrow]$  key several times and display the input signal selection function [IE.]. (Direct call number = "0312") Press the [D] key several times, and set either [IE.IO3] or [IE.IR3].

The following display will appear.



When [IE.IO3] is set, the touch back solenoid can be driven even when the sewing machine is stopped.



When [IE.IR3] is set, the touch back solenoid can be driven only when the sewing machine is running.

- Next, press the [↓] key several times, and set the output signal selection function [OC.]. (Direct call number = "0400") Press the [D] key several times, and set [OC.OT3].
- After making the above setting, press the [↓] and [↑] keys simultaneously to return to the normal mode.

Order of signal priority

## 9. Order of signal priority

(1) Order of lever unit's (lever connector) S1 (run), S2 (thread trimmer) and S3 (presser foot lifter) signals

#### S1 (run) > S2 (thread trimmer) > S3 (presser foot lifter)

- (Note 1) : For the (run) signal, an interlock is applied when the power is turned ON, thus, this will be invalid even if the S signal is ON when the power is turned ON. (The signal must be turned ON again.) \* If the pedal is not at the neutral position or if the S1 signal is ON when the power is turned ON, the error message "MA" will appear.
- (Note 2) : The S2 (thread trimmer) signal will be validated only after operation has been carried out once. (This signal is validated when the S1 signals turns OFF after operating once.)
- (Note 3) : The S3 (presser foot lifter) signal is valid only when the S1 and S2 signals are invalid (when the motor is stopped.) (In other words, the S3 signal is invalid when the motor is running, including when the thread trimmer is operating.)

### (2) Order of speed command signal priority

The order of priority for the S1 (variable-speed run signal), S0 (low-speed run signal), S4 (high-speed run signal), S5 (medium-speed run signal), SPL (speed low-speed signal), SPM (speed medium-speed signal) and SPH (speed high-speed signal) is as follows.

$$egin{pmatrix} {
m S0} \\ {
m SPL} \end{pmatrix} > egin{pmatrix} {
m S5} \\ {
m SPM} \end{pmatrix} > egin{pmatrix} {
m S4} \\ {
m SPH} \end{pmatrix} > egin{pmatrix} {
m S1+AT} \end{pmatrix} > egin{pmatrix} {
m S1 only} \\ {
m S1-AT} \end{pmatrix}$$

Note 1) S1 + AT: Indicates the S1 signal and P mode automatic operation function [AT.ON]

(3) Supplements (Operation in S2 signal and S3 signal short-circuit state)

For example, operation when only the S1 (run) signal is turned ON and OFF while the S2 (thread trimmer) and S3 (presser foot lifter) signals are always ON in the normal setting state. (Lever connector pins No. 5 and 6 are short-circuited.)

#### [Operation]

When the power is turned ON, the presser foot lifter will turn ON, when the S1 signal turns ON, the presser foot lifter will turn OFF.

Operation (high-speed operation) will start.

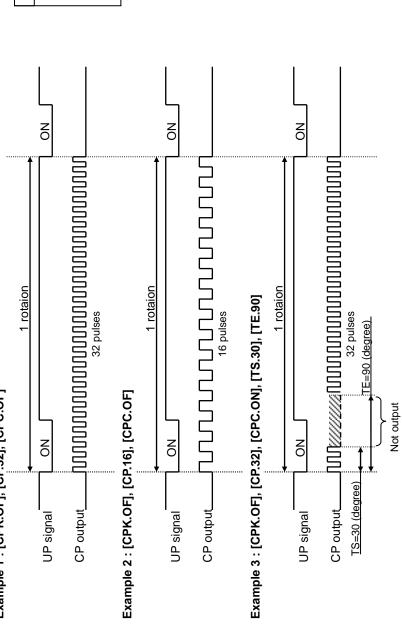
→ When the S1 signal is then turned OFF, the thread trimmer will operate, the machine will stop, and then the presser foot lifter will operate.

10. CP output

	Specification		Feed pulse [CP] is invalid.  When feed pulse will be used, set this function to "OF" This signal output is from the same pin of "O6".	Setting the number of pulse [CP]. After changing this number, turn on power switch again.	The prohibited angle section of pulse generated can be set from UP position. The start prohibited angle can be set with [TS] (G mode). The end prohibited angle can be set with [TE] (G mode).		
ing			S P	*	N P		
Setting	isplay		ქ0 0	* *	ქo		
Function name	Setting range Digital display		[PŁ	[P.	[P[.		
				1~99	ı		
	Unit			ı			
Factory	ractory setting GMFY		NO	32	OF		
0	perab	oility	0	0	0		
	Direct call number				0250	0521	0522
	Function name		Feed pulse output (CP) CPK. cancel function	Setting CP pulse amount CP.	Prohibited angle of output CPC.		
	Mode	<u>a</u>	C mode	<b>→</b>	+ 0		

[CP output] (CP output: No. 14 pin of Option B connector. (Note: CP output is not for solenoid output.))

Example 1 : [CPK.OF], [CP.32], [CPC.OF]

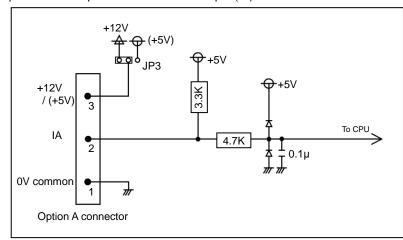


Note)

Input/output circuits

## 11. Main input/output circuits

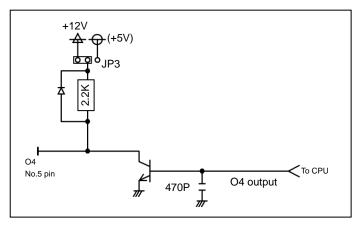
## (1) Input circuit for option A connector No. 2 pin (IA)



## Caution)

The input circuit for the option A connector's No. 4 pin (IB) and No. 6 pin (IC) is the same as that shown on the left.

## (2) Output circuit for option A connector No. 5 pin (O4)



#### Caution)

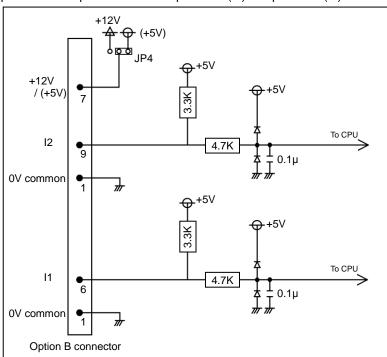
As the default, the O4 output is set to the needle UP position output (UPW).

The needle UP position signal is output.

The output will be 12V output (default).

The output can be selected with the C mode settings.

## (3) Input circuit for option B connector pin No. 6 (I1) and pin No. 9 (I2)

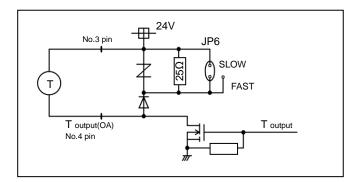


### Caution)

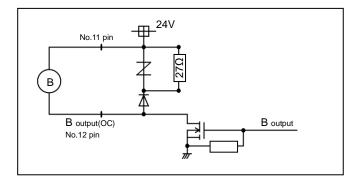
The input circuit for the option B connector No. 2 pin (I4) and No. 5 pin (I5) is the same as that shown on the left.

Input/output circuits

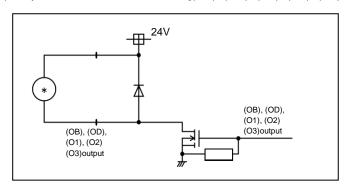
## (4) Output circuit for sewing machine connector T output (OA)



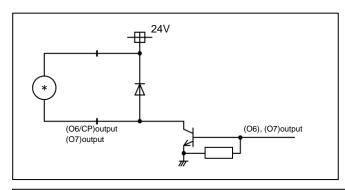
### (5) Output circuit for sewing machine connector B output (OC)



## (6) Output circuit for other solenoids [(OB), (OD), (O1), (O2), (O3) outputs]



## (7) Output circuit for option B connector No. 13 pin (O7), pin No. 14 (O6/CP)



Caution 1)

The option B connector pin No. 13 (O7) and pin No. 14 (O6) are output terminals for the solenoid valve. The solenoid cannot be driven.

## Caution 2)

When using the option B connector pin No. 14 (O6/CP) as the pulse output (CP), several settings are required including the CPK function and CP function (cycle division ratio) in the C mode. These are not set as the default.

12. Detector compatibility <Matrix list>

Con		×	×		tector ×			×	_ 120		×			achine  ××		iwə2 i	_	stiM I××	
Control box series	Control box type Detector type	XC-KE-01P	XC-KB-12P	XC-KB-12	XC-KB-22	XC-K-12P	XC-K-22	XC-K-12	LA-K-22	LA-K-12	XC-K-2000	XC-K-1002	XC-K-1000 XC-K-1001	XC-K-230-E XC-K-230-F	XC-K-180	XC-K-230-C XC-K-230-D	_A-K-180	XA-K-230-C XA-K-230-D	LA-K-190
XC-G Series	XC-GMF	0	0	0	×	0	×	0	×	0	0	0	0	0	0	0	0	0	0
XC-F Series	XC-FMF	0	0	0	×	0	×	0	×	0	0	0	0	0	0	0	0	0	0
XC-E Series	XC-EMF XC-EN	0	0	0	×	0	×	0	×	0	0	0	0	0	0	0	0	0	0
XC-B Series	XC-BMF XC-BMBL XC-BFL XC-BN	O Note1	0	0	×	0	×	0	×	0	0	0	0	0	0	O Note4	0	O Note4	0
XC-A	XC-AFL XC-AN	×	0	0	0	0	0	0	0	0	0	0	0	0	0	×	0	×	0
Series	XC-AMF XC-AM	×	X Note2	△ Note3	0	X Note2	0	△ Note3	0	△ Note3	X Note2	× Note2	0	0	0	×	0	×	0
XC §	XC-M XC-FL XC-N	×	0	0	0	0	0	0	0	0	0	0	0	0	0	×	0	×	0
XC Series	XC-MF	×	X Note2	△ Note3	0	X Note2	0	△ Note3	0	△ Note3	X Note2	X Note2	0	0	0	×	0	×	0
ZK-A Series	ZK-AMBL	×	0	0	0	0	0	0	0	0	×	0	0	0	0	×	0	×	0
LF-A Series	LF-AMDF LF-AM	×	X Note2	△ Note3	0	X Note2	0	△ Note3	0	△ Note3	×	X Note2	0	0	0	×	0	×	0
ZK Series	ZK-MBL ZK-FL ZK	×	0	0	0	0	0	0	0	0	×	0	0	0	0	×	0	×	0
	LF-M	×	0	0	0	0	0	0	0	0	×	0	0	0	0	×	0	×	0
LF Series	LF-MDF (DIP switch 32P side)	×	X Note2	△ Note3	0	X Note2	0	△ Note3	0	△ Note3	×	X Note2	0	0	0	×	0	×	С
	LF-MDF (DIP switch 64P side)	×	×	×	×	×	×	×	×	×	×	×	×	×	×	0	×	0	×

Note1: The detector does not have a PG signal, so when using a pulse output (CP output) with the XC-BFL or XC-BMF, the pulse output cannot be output. Note2: The ground from the sewing machine is connected to the control box's TM signal (thread trimming position), so this cannot be connected.

However, this can be used if the detector's ground wire is cut off (pin removed), etc., and the ground is not connected.

Note3: The detector does not have a TM signal (thread trimming position), so this cannot be used with a sewing machine that uses the thread trimming position TM signal. Note4: When using the pulse output (CP output) with the XC-BFL or XC-BMF, the pulse output will be double at 64 pulses. Refer to " $\overline{24}$  Table of Program Mode Function" for details on each function. The numbers in the table are used with the direct number call function.

	name	Function	No.
	H.	Maximum speed	0000
	L.	Low speed	0001
	Т.	Thread trimming speed	0002
	N.	Start tacking speed	0003
	٧.	End tacking speed	0004
	М.	Medium speed	0005
	S.	Slow start speed	0006
	SLN.	No. of slow start stitches	0007
_	SLM.	Slow start operation mode	0008
e)	SLP.	Slow start when power is turned ON	0009
<u> </u>	SH.	One shot	0010
Ļ	SHM.	One shot operation mode	0011
ı	PSU.	No. of stitches after PSU input	0012
<u> </u>	PSD.	No. of stitches after PSD input	0013
(e)	PS1.	Sensor input signal PS1 operation mode	0014
.⊆	1.	No. of stitches after PS1 input	0015
등	PS2.	Sensor input signal PS2 operation mode	0016
ğ	2.	No. of stitches after PS2 input	0017
∟	PSN.	Restart after PSD,SEN input PSN	0018
βl	SEN.	Input sensor function valid / invalid	0019
Ĭ÷	SE.	Setting stitch amount to stop by "SEN"	0020
é	FUM.	Presser foot lift momentary	0021
S	FU.	FUM operation mode	0022
٦ؚٙ	FCT.	Time setting for FUM operation mode	0023
P mode (For sewing machine): [↓]+[↑] key	FD.	Time to motor drive after presser foot lifter bring down	0024
ğ	FO.	Full wave time of presser foot lifter output	0025
lμ	S3D.	Delay time of presser foot signal S3 input	0026
٦	FUD.	Presser foot lifting output chopping duty	0027
"	PFU.	Presser foot lifting output when power is turned ON	0028
	FL.	Cancel the presser foot lifting with full heeling	0029
	S3L.	Cancel presser foot lifting with light heeling	0030
	S2L.	Cancel of thread trimming operation	0031
	S6L.	Thread trimming protection signal (S6) logical	
	30L.	changeover	0032
	AT.	Automatic operation	0033
	TL.	Thread trimmer cancel	0034
	TLS.	Auto-stop of preset stitch sewing before trim	0035
	RU.	Reverse run needle lifting after thread trimming	0036
	R8.	RU reverse run angle	0037
	TB.	Thread trimming with reverse feed	0038
	TBJ.	Not used.	0039
	S2R.	Full heeling, S2 signal operation mode	0040
	IL.	Cancel of interlock after full pedal heeling	0041
	TR.	Thread trimming mode	0042
	POS.	Thread trimming validity at neutral pedal	0043
	P1P.	Operation when power is turned ON during 1 position setting.	0044
	P2P.	Operation when power is turned ON during 2 position setting.	0045
	C8.	Needle stop position before fabric	0046
	K8.	Reverse run angle from DOWN position to UP position	0047
	E8.	On angle of virtual "TM"	0048
	S8.	On start angle of virtual "TM"	0048
	SNM.	Setting sensor "SEN" input function	0050
	KD.	Virtual down setting	0050
	KDU.	Virtual width of up and down signal	0051
	PSJ.	Not used.	0052
	D8.	Needle DOWN position stop angle	0053
	U8.	Needle UP position stop angle	0055
			0000

	name	Function	No.
	GA.	Gain high/low selection	0100
	PDC.	Pedal curve	0101
>	AC.	Acceleration time simple setting	0102
(e)	ACT.	Acceleration time	0103
A mode (For servo motor) : [↓]+[A] key	DC.	Deceleration time simple setting	0104
Ę.	DCT.	Deceleration time	0105
Ļ	SC.	S-character cushion	0106
	SCT.	S-character cushion time setting	0107
(	S2M.	Full heeling S2 signal operation mode when	0108
ţ		power is turned on or after thread trimming	
DO.	PL.	Sewing machine shaft/motor shaft speed setting selection	0109
n c	MR.	Setting motor pulley diameter	0110
Ņ	SR.	Setting sewing machine pulley diameter	0111
er		Random stop is available without thread	
r s	NOS.	trimming.	0112
-0	STM.	First priority stop => speed control	0114
1)	BKT.	Brake time	0115
qe	B8.	Weak brake angle	0116
Ŏ	BNR.	Reduction of weak brake sound	0117
'n	BKS.	Weak brake force	0118
A	BKM.	Weak brake mode	0119
	BK.	Weak brake	0120
Ş	S.	Display sewing speed	0200
ke	N.	Down counter setting count amount	0201
3	D.	Down counter display count amount	0202
크	P.	Up counter setting count amount	0203
<u>-</u>	U.	Up counter display count amount	0204
] :	CUP.	Up counter the selection of setting mode	0205
У)	USC.	Up counter the selection of counter operation	0206
pla	UCM.	Up counter changing sewing pattern	0207
dis	UPC.	Up counter valid / invalid	0208
þ	NXU.	Up counter operation after counting over	0209
bee	CDN.	Down counter the selection of setting mode	0210
mode (For counter/speed display) : [ $\downarrow ]+[B]$ key	DSC.	Down counter the selection of counter operation	0211
unt	DCM.	Down counter changing sewing pattern	0212
8	DNC.	Down counter valid / invalid	0213
ō	NXD.	Down counter operation after counting over	0214
(F	PCM.	Counter condition turning on power switch	0215
qe	PRN.	Setting Thread trimming times "N"	0216
Ŏ	CNU.	Setting Number of stitches "N"	0217
ī	CCI.	Count modification (to use IO1, IO2)	0218
В	PMD.	Display condition turning on power switch	0219
	CCM.	Reset for Up / Down counter during operation	0220
Prog	gram mode	e [I] (Save mode of the setting data ): $[\downarrow]+[\uparrow]+[B]$ -	+[C] key
	name	Function	No.
	SAVE1	Save mode of the setting data 1	ı
	SAVE2	Save mode of the setting data 2	-
	CCR	Copy of the current data	-
	CU1	Copy of user's 1 data	,
	CU2	Copy of user's 2 data	-
Prod	gram mode	e [R] (Reset): [↓]+[B]+[C] key	_
	name	Function	No.
	RESET.	Reset	-
Prod		e [1] (Mitsubishi sewing machine): [↓]+[A]+[B] ke	v
	name	Function	No.
	280M	LS2-1280-M1T(W)	-
	:	:	-
	LOAD1	Load of the saved setting data1	-
Prod		e [2] (Chain stitch sewing machine): [\]+[C]+[D] I	(ev
0(	name	Function	No.
	YU2	YAMATO VC2600,VC2700 class	- 110.
	:	:	-
	JMH	JUKI	<del>-</del>
			D1 1
Prog		e [3] (other lock stitch sewing machine): [\]+[A]+	
	name	Function	No.
	D697	DÜRKOPP ADLER 697-15000 class	-
		· -	

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SINGER

	nomo	Function	No
-	name	Function	No.
	IA.	IA input function selection	0300
	IAL.	IA input logic changeover	0301
	IAA.	IA input alternating operation	0302
	IB.	IB input function selection	0303
	IBL.	IB input logic changeover	0304
	IBA.	IB input alternating operation	0305
	IC.	IC input function selection	0306
	ICL.	IC input logic changeover	0307
	ICA.	IC input alternating operation	0308
	ID.	ID input function selection	0309
	IDL.	ID input logic changeover	0310
	IDA.	ID input alternating operation	0311
	IE.	IE input function selection	0312
	IEL.	IE input logic changeover	
	IEA.		0313
		IE input alternating operation	0314
	IF.	IF input function selection	0315
	IFL.	IF input logic changeover	0316
	IFM.	Setting the function for IF	0317
	RFS.	Set condition of RS F/F for IF	0318
	RFR.	Reset condition of RS F/F for IF	0319
_	RFN.	RS F/F reset stitch amount for IF	0320
(e)	IG.	IG input function selection	0321
ž	IGL.	IG input logic changeover	0322
$\Box$	IGA.	IG input alternating operation	0323
宁	IH.	IH input function selection	0324
$\rightarrow$	IHL.	IH input logic changeover	0325
ب ا	IHA.	IH input alternating operation	0325
<u>ج</u> ا	II.	Il input function selection	0327
ō	IIL.		
tting input/output signal to function): [↓]+[C] key	IIA.	Il input logic changeover	0328
I≚		Il input alternating operation	0329
₽	IJ.	Not used.	0330
0	IJL.	Not used.	0331
<u> </u>	IJA.	Not used.	0332
2	IK.	Not used.	0333
<u>.</u>	IKL.	Not used.	0334
S	IKA.	Not used.	0335
ΙĦ	IL.	Not used.	0336
ф	ILL.	Not used.	0337
ΙZ	ILA.	Not used.	0338
ζ(	IM.	IM input function selection	0339
$\Box$	IML.	IM input logic changeover	0340
ī	IMA.	IM input alternating operation	0341
	IN.	IN input function selection	0342
Ĭ.	INL.	IN input logic changeover	0343
Ħ	INA.	IN input alternating operation	0344
Se	10.	IO input function selection	
Ä	IOL.		0345
l <sub>i</sub> o	IOL.	IO input logic changeover	0346
		IO input alternating operation	0347
l e	IP.	IP input function selection	0348
ŏ	IPL.	IP input logic changeover	0349
C mode (For se	IPA.	IP input alternating operation	0350
$\circ$	IQ.	IQ input function selection	0351
	IQL.	IQ input logic changeover	0352
	IQA.	IQ input alternating operation	0353
	IR.	IR input function selection	0354
	IRL.	IR input logic changeover	0355
	IRA.	IR input alternating operation	0356
	I1.	I1 input function selection	0357
	I1L.	I1 input logic changeover	0358
	IIM.	Setting the function for I1	0359
	110	Special setting for input signal "I1"	0360
	I1F	Special setting for input signal "I1" is ON	0361
	I1C	RS F/F clear setting	0362
	1CT	LRS E/E delay time cetting	USES
1	1CT F1D	RS F/F delay time setting	0363
	F1P	Input signal I1 virtual F/F circuit operation 1	0364
	F1P F1C	Input signal I1 virtual F/F circuit operation 1 Input signal I1 virtual F/F circuit operation 2	0364 0365
	F1P F1C F1S	Input signal I1 virtual F/F circuit operation 1 Input signal I1 virtual F/F circuit operation 2 Input signal I1 virtual F/F circuit operation 3	0364 0365 0366
	F1P F1C F1S R1S	Input signal I1 virtual F/F circuit operation 1 Input signal I1 virtual F/F circuit operation 2 Input signal I1 virtual F/F circuit operation 3 Set condition of RS F/F for I1	0364 0365 0366 0367
	F1P F1C F1S R1S R1R	Input signal I1 virtual F/F circuit operation 1 Input signal I1 virtual F/F circuit operation 2 Input signal I1 virtual F/F circuit operation 3 Set condition of RS F/F for I1 Reset condition of RS F/F for I1	0364 0365 0366
	F1P F1C F1S R1S R1R R1N	Input signal I1 virtual F/F circuit operation 1 Input signal I1 virtual F/F circuit operation 2 Input signal I1 virtual F/F circuit operation 3 Set condition of RS F/F for I1 Reset condition of RS F/F for I1 RS F/F reset stitch amount for I1	0364 0365 0366 0367 0368 0369
	F1P F1C F1S R1S R1R R1N I2.	Input signal I1 virtual F/F circuit operation 1 Input signal I1 virtual F/F circuit operation 2 Input signal I1 virtual F/F circuit operation 3 Set condition of RS F/F for I1 Reset condition of RS F/F for I1 RS F/F reset stitch amount for I1 I2 input function selection	0364 0365 0366 0367 0368 0369 0370
	F1P F1C F1S R1S R1R R1N I2.	Input signal I1 virtual F/F circuit operation 1 Input signal I1 virtual F/F circuit operation 2 Input signal I1 virtual F/F circuit operation 3 Set condition of RS F/F for I1 Reset condition of RS F/F for I1 RS F/F reset stitch amount for I1 I2 input function selection I2 input logic changeover	0364 0365 0366 0367 0368 0369
	F1P F1C F1S R1S R1R R1N I2. I2L. I2M.	Input signal I1 virtual F/F circuit operation 1 Input signal I1 virtual F/F circuit operation 2 Input signal I1 virtual F/F circuit operation 3 Set condition of RS F/F for I1 Reset condition of RS F/F for I1 RS F/F reset stitch amount for I1 I2 input function selection I2 input logic changeover Setting the function for I2	0364 0365 0366 0367 0368 0369 0370
	F1P F1C F1S R1S R1R R1N I2.	Input signal I1 virtual F/F circuit operation 1 Input signal I1 virtual F/F circuit operation 2 Input signal I1 virtual F/F circuit operation 3 Set condition of RS F/F for I1 Reset condition of RS F/F for I1 RS F/F reset stitch amount for I1 I2 input function selection I2 input logic changeover Setting the function for I2 RS F/F clear setting	0364 0365 0366 0367 0368 0369 0370 0371
	F1P F1C F1S R1S R1R R1N I2. I2L. I2M.	Input signal I1 virtual F/F circuit operation 1 Input signal I1 virtual F/F circuit operation 2 Input signal I1 virtual F/F circuit operation 3 Set condition of RS F/F for I1 Reset condition of RS F/F for I1 RS F/F reset stitch amount for I1 I2 input function selection I2 input logic changeover Setting the function for I2 RS F/F clear setting	0364 0365 0366 0367 0368 0369 0370 0371 0372
	F1P F1C F1S R1S R1R R1N I2. I2L. I2M. I2C	Input signal I1 virtual F/F circuit operation 1 Input signal I1 virtual F/F circuit operation 2 Input signal I1 virtual F/F circuit operation 3 Set condition of RS F/F for I1 Reset condition of RS F/F for I1 RS F/F reset stitch amount for I1 I2 input function selection I2 input logic changeover Setting the function for I2 RS F/F clear setting RS F/F delay time setting	0364 0365 0366 0367 0368 0369 0370 0371 0372 0373
	F1P F1C F1S R1S R1R R1N I2. I2L. I2M. I2C 2CT R2S	Input signal I1 virtual F/F circuit operation 1 Input signal I1 virtual F/F circuit operation 2 Input signal I1 virtual F/F circuit operation 3 Set condition of RS F/F for I1 Reset condition of RS F/F for I1 RS F/F reset stitch amount for I1 I2 input function selection I2 input logic changeover Setting the function for I2 RS F/F clear setting RS F/F delay time setting Set condition of RS F/F for I2	0364 0365 0366 0367 0368 0369 0370 0371 0372 0373 0374
	F1P F1C F1S R1S R1R R1N I2. I2L. I2M. I2C	Input signal I1 virtual F/F circuit operation 1 Input signal I1 virtual F/F circuit operation 2 Input signal I1 virtual F/F circuit operation 3 Set condition of RS F/F for I1 Reset condition of RS F/F for I1 RS F/F reset stitch amount for I1 I2 input function selection I2 input logic changeover Setting the function for I2 RS F/F clear setting RS F/F delay time setting	0364 0365 0366 0367 0368 0369 0370 0371 0372 0373

	name	Function	No.
	14.	I4 input function selection	0378
	I4L.	I4 input logic changeover	0379
	I4A.	14 input alternating operation	0380
	<b>I5</b> .	15 input function selection	0381
	15L.	15 input logic changeover	0382
	I5A.	15 input alternating operation	0383
	16.	16 input function selection	0384
	I6L. I6A.	I6 input logic changeover I6 input alternating operation	0385
	17.	17 input function selection	0386 0387
	17L.	17 input logic changeover	0388
	17A.	17 input alternating operation	0389
	OA.	OA output function selection	0390
	OAL.	OA output logic changeover	0391
	OAC.	OA output chopping operation	0392
	OAT.	OA output forced OFF	0393
	DA.	OA output delay time	0394
	OB.	OB output function selection OB output logic changeover	0395
	OBC.	OB output chopping operation	0396 0397
	OBT.	OB output forced OFF	0398
€	DB.	OB output delay time	0399
ӽ	OC.	OC output function selection	0400
C	OCL.	OC output logic changeover	0401
]+	OCC.	OC output chopping operation	0402
[ <u>†</u> ]	ОСТ.	OC output forced OFF	0403
C mode (For setting input/output signal to function): [ $\downarrow$ ]+[C] key	DC.	OC output delay time	0404
o	OD.	OD output function selection	0405
cţi	ODL.	OD output logic changeover OD output chopping operation	0406
Ĭ	ODC.	OD output chopping operation  OD output forced OFF	0407 0408
) f	DD.	OD output delay time	0409
t	OF.	OF output function selection	0410
ıal	OFL.	OF output logic changeover	0411
g	FUD.	Presser foot lifter output chopping duty	0412
S	FO.	Presser foot lifter FU full wave output time	0413
ort	FU.	Presser foot lifter FU momentary mode	0414
l¥	DF.	OF output delay time	0415
10/	01. 01L.	O1 output function selection	0416
ut,	01C.	O1 output logic changeover O1 output chopping function	0417 0418
up	010. 01T.	O1 output forced OFF	0418
g	D1.	O1 output delay time	0420
ù	O2.	O2 output function selection	0421
ett	O2L.	O2 output logic changeover	0422
S	O2C.	O2 output chopping function	0423
Ō	O2T.	O2 output forced OFF	0424
(F	D2.	O2 output delay time	0425
ge	O3. O3L.	O3 output function selection O3 output logic changeover	0426
Q	03C.	O3 output chopping function	0427 0428
ū	O3T.	O3 output forced OFF	0428
0	D3.	O3 output delay time	0430
	04.	O4 output function selection	0431
	O4L.	O4 output logic changeover	0432
	O4T.	O4 output forced OFF	0433
	D4.	O4 output delay time	0434
	O5. O5L.	O5 output function selection O5 output logic changeover	0435
	OSL.	O5 output forced OFF	0436 0437
	D5.	O5 output delay time	0438
	06.	O6 output function selection	0439
	O6L.	O6 output logic changeover	0440
	O6C.	O6 output chopping function	0441
	O6T.	O6 output forced OFF	0442
	D6.	O6 output delay time	0443
	07.	O7 output logic changes yor	0444
	07L. 07C.	O7 output logic changeover O7 output chopping function	0445
	07C.	O7 output forced OFF	0446 0447
	D7.	O7 output folded Of F	0447
	OM.	OM output function selection	0449
	OML.	OM output logic changeover	0450
	OMT.	OM output forced OFF	0451
	DM.	OM output delay time	0452
	ON.	ON output function selection	0453
	ONL.	ON output logic changeover	0454
	ONT.	ON output forced OFF	0455

	nomo	Lungtion	No							
	name DN.	Function ON output delay time	No. 0456							
	00.	OO output function selection	0457							
	OOL.	OO output logic changeover	0458							
	OOT.	OO output forced OFF	0459							
	DO.	OO output delay time	0460							
	OP.	OP output function selection	0461 0462							
	OPL. OPT.	OP output logic changeover OP output forced OFF OP output delay time								
	DP.									
	OQ.	OQ output function selection	0464 0465							
	OQL.	OQ output logic changeover								
	OQT.	OQ output forced OFF	0467							
	DQ.	OQ output delay time	0468							
	O.R. O.RL.	OR output logic changes yer	0469							
	O.RT.	OR output logic changeover OR output forced OFF	0470 0471							
	DR.	OR output delay time	0471							
	PO.	OR output delay time  Full wave output time for each output								
	POD.	Output chopping duty except of FU output								
	OTT.	Forced OFF timer setting function for each								
	FCT.	output Time setting for FUM operation mode	0475							
	A1.	Logic [AND] module input function selection	0476							
>	A1L.	Logic [AND] module setting of Hi/Low logic	0477 0478							
ê.	A1A.	Logic [AND] module Alternate	0479							
input/output signal to function): [↓]+[C] key	N1.	Logic [AND] module	0480							
<del>수</del>		output function selection								
$\overline{\supseteq}$	N1L.	Logic [AND] module setting of Hi/Low logic Logic [AND] module	0481							
<u>::</u>	N2.	output function selection	0482							
on	N2L.	Logic [AND] module setting of Hi/Low logic	0483							
: <u>च</u>	A2.	Logic [AND] module input function selection	0484							
E	A2L.	Logic [AND] module setting of Hi/Low logic	0485							
) Į	A2A.	Logic [AND] module Alternate  Logic [AND] module	0486							
=	N3.	output function selection	0487							
Da	N3L.	Logic [AND] module setting of Hi/Low logic	0488							
sig	N4.	Logic [AND] module	0489							
=		output function selection								
nd:	N4L.	Logic [AND] module setting of Hi/Low logic	0490							
'n	A3.	Logic [AND] module input function selection Logic [AND] module setting of Hi/Low logic	0491							
Tt/C	A3A.	Logic [AND] module Alternate	0492 0493							
ď		Logic [AND] module								
.⊑	N5.	output function selection	0494							
рū	N5L.	Logic [AND] module setting of Hi/Low logic	0495							
₩	N6.	Logic [AND] module output function selection	0496							
S	N6L.	Logic [AND] module setting of Hi/Low logic	0497							
ō	OR.	Logic [OR] module input function selection	0498							
F)	ORL.	Logic [OR] module setting of Hi/Low logic	0499							
Зе	ORA.	Logic [OR] module Alternate	0500							
C mode (For setting	R1.	Logic [OR] module output function selection	0501							
_	R1L. R2.	Logic [OR] module setting of Hi/Low logic Logic [OR] module output function selection	0502							
J	R2L.	Logic [OR] module setting of Hi/Low logic	0503 0504							
	CSP.	Variable speed command for digital input	0505							
	CSG.	Variable speed command for digital input	0506							
		(Gray code)								
	LB.	Thread release + backstitch output	0507							
	T1C.	Virtual output OT1 forced OFF function  Forced OFF timer setting function for virtual	0508							
	T1T.	output OT1	0509							
	T2C.	Virtual output OT2 forced OFF function	0510							
	T2T.	Forced OFF timer setting function for virtual	0511							
		output OT2								
	T3C.	Virtual output OT3 forced OFF function Forced OFF timer setting function for virtual	0512							
	T3T.	output OT3	0513							
	D11.	ON delay time setting function for virtual	0514							
	D11.	output OT1	0514							
	D12.	OFF delay time setting function for virtual output OT1	0515							
	DC:	ON delay time setting function for virtual								
	D21.	output OT2	0516							
	D22.	OFF delay time setting function for virtual	0517							
		ON delay time setting function for virtual	2±.,							
	D31.		0518							
		output OT3								

	name	Function	No.
	D32.	OFF delay time setting function for virtual output OT3	0519
	CPK.	Feed pulse output (CP) cancel function	0520
	CP.	Setting CP pulse amount	0521
	CPC.	Prohibited angle of output CP pulse	0522
>	PSW.	Panel switch operation prohibit	0523
C mode : [↓]+[C] key	CKB.	O4, O5 output cancel during backtack term	0524
<u></u>	CPB.	CP output cancel during backtack term	0525
2	C.	Speed setting for the [SPC] output	0526
‡	D.	Speed setting for the [SPD] output	0527
⇒	E.	Speed setting for the [SPE] output	0528
۵.	CNF.	F key function on control panel	0529
ğ	PDS.	Variable speed pedal changeover setting	0530
12	V2C.	Speed instruction VC2 cancellation	0531
0			

	name	Function	No.
	D1.	Operation mode during tacking	0600
	D2.	Operation mode during start tack completion	0601
	CT.	Stop time at each corner during start and backtacking	0602
Θ	BM.	Tack alignment	0603
Ž		No. of stitch compensation for start tacking	
[a]	BT1.	alignment	0604
D mode (For tacking setting mode): [↓]+[D] key	BT2.	No. of stitch compensation for start tacking alignment	0605
де):	BT3.	No. of stitch compensation for end tacking alignment	0606
шос	BT4.	No. of stitch compensation for end tacking alignment	0607
g	BTP.	No. of tacking stitches (+) 15 stitches function	0608
əttin	вто.	No. of tacking stitches addition stitches function	0609
g S(	ВТТ.	Full heeling function immediately after start tacking stop	0610
ij	CSJ.	Not used.	0611
충	CDN	The speed operation mode when both the	
ta	SPN.	medium speed signal and S5V signal is ON	0612
or	BTM.	Set table types of tacking	0613
Э) e	S7M.	Input signal S7 operation mode during preset stitching	0614
ğ	S7U.	Manual backstitch ON timing 1	0615
υC	S7D.	Manual backstitch ON timing 2	0616
٥	7BD.	The OFF timing setting of output B when the backstitching signal (S7) is OFF setting.	0617
	BTN.	The maximum tacking stitches (maximum stitches is 99 stitches)	0618
	BCC.	No. of end tacking stitches during direct heeling	0619
	TLS.	Operation mode during thread trimmer cancel signal [TL] setting	0620
	BTS.	Input signal BTL quick pressing operation	0621
	BS.	Input signal SB and EB quick pressing operation	0622
	BTD.	Operation when input signal BTL is ON	0623
	BD.	Operation when input signal SB and EB tacking OFF are set	0624
	PNE.	End tacking cancel mode with input signal PSU	0625
	BZ.	The buzzer of control panel validity	0626

	nama	Function	No.
	name 1.	Error code (The last error code)	
	2.	Error code (The last error code)	0700 0701
	3.	Error code (The third to last code)	0701
	4.	Error code (The fourth to last code)	0702
	P.	Total integration time of power on	0704
	M.	Total integration time of motor run	0705
	IA.	Input display	0706
	IB.	Input display	0707
	IC.	Input display	0708
	ID.	Input display	0709
	IE.	Input display	0710
	IF.	Input display	0711
	IG.	Input display	0712
>	IH.	Input display	0713
ke	II. IJ.	Input display	0714
٨J	IK.	Input display Input display	0715
-[	IL.	Input display	0716 0717
Ċ	IP.	Input display	0717
Ξ	IQ.	Input display	0719
$\rightarrow$	IR.	Input display	0720
.(	I1.	Input display	0721
E mode (For H/W checking mode): [↓]+[↑]+[A] key	I2.	Input display	0722
ΠO	14.	Input display	0723
J n	<b>I5</b> .	Input display	0724
ĵ	ECA.	Encoder signal display (A phase)	0725
Ķ	ECB.	Encoder signal display (B phase)	0726
jec	UP.	Detector signal display (UP signal)	0731
ch	DN.	Detector signal display (DN signal)	0732
>	DR. VC.	Display the angle from down position	0733
$\leq$	VC.	Display the voltage of VC Display the voltage of VC2	0734 0736
ŗ	OAD.	Output signal display	0736
Б	OBD.	Output signal display	0738
) (	OCD.	Output signal display	0739
de	ODD.	Output signal display	0740
no	OFD.	Output signal display	0741
	O1D.	Output signal display	0742
ш	O2D.	Output signal display	0743
	O3D.	Output signal display	0744
	04D.	Output signal display	0745
	O5D.	Output signal display	0746
	06D.	Output signal display	0747
	O7D. OPD.	Output signal display	0748
	OPD.	Output signal display Output signal display	0749 0750
	ORD.	Output signal display  Output signal display	0750
	OAO.	Solenoid output	0752
	OBO.	Solenoid output	0753
	OCO.	Solenoid output	0754
	ODO.	Solenoid output	0755
	OFO.	Solenoid output	0756
	010.	Solenoid output	0757
	020.	Solenoid output	0758
	030.	Solenoid output	0759
	040.	Solenoid output	0760
	O5O. O6O.	Solenoid output Solenoid output	0761
	070.	Solenoid output Solenoid output	0762 0763
	OPO.	LED output for G500 type control panel	0763 0764
	0QO.	LED output for G500 type control panel	0764
	ORO.	LED output for G500 type control panel	0766
	WT.	Rated output display	0767
	VL.	Voltage display	0768
	TP.	Model display	0769
	DV.	Data version No.	0770
	RV.	Software version No.	0771
	T.	Display previous simple setting selected.	0772

	name	Function	No.
	CO 4	Set No. of stitches A for cutter output (Setting	
	COA.	the delay time during chain-off output ON)	0800
	сов.	Set No. of stitches B for cutter output (Setting	0004
	COB.	the delay time during chain-off output OFF)	0801
	COC.	Set No. of stitches C for cutter output	0802
	х.	No. of stitches for BT output ON after sensor	0803
	^ .	OFF setting	0000
	Υ.	No. of stitches for sewing machine stop after	0804
		BT output ON setting	
	Ζ.	No. of stitches for BT output OFF after start of	0805
		stitching setting  Delay time to when SL output turns from OFF	
	SD.	to ON	0806
		Delay time to when SL output turns from ON	
	ED.	to OFF	0807
		No. of set stitches during SL output ON	
	SLH.	selection mode	8080
<u>&gt;</u>	SLK.	SL output start position setting	0809
ke		SL output start position during SLS function	
3]	SLT.	ON setting	0810
ᆜ	SLL.	Speed limit M except tacking and SL on	0811
Ţ	SLS.	SL output operation during motor stop	0812
Ť	O1B.	OT1 output blower output setting	0813
<u>-</u>	O2M.	OT2 output chain-off output setting	0814
	O3M.	OT3 output cutter output setting	0815
le)	I2M.	Mesh judgment control with I*2 input	0816
Cutter setting mode): [↓]+[↑]+[B] key	CTY.	Setting I*3 signal for manual cutter output	0817
Ш	CTM.	Status of cutter output photo switch (I*2)	0818
g	CTW.	signal according to OT3 output	0010
tin	CTR.	Turn OT3 output ON/OFF per set No. of	0819
et	•	stitches when I*3 signal is ON	0013
S	CSC.	Automatic cutter output prohibit during	0820
Ę		sensor ON	
τ	CEC.	Automatic cutter output prohibit during	0821
$^{\circ}$		sensor OFF	
е (	CTS.	Cutter output prohibit when sensor is ON while stopped	0822
mode ((		Automatic thread trim setting after cutter	
ĭ	CAT.	sensor is turned off	0823
F١		Set I*1 input, OP1 output to cutter BT	
	CTL.	specifications input/output	0824
		Preset stitching operation after operation	
	NMD.	signal OFF	0825
	RLM.	ROL output mode	0826
	RLN.	No. of stitches setting for auxiliary feeding	
	KLN.	rear roller	0827
	CTG.	Not used.	0828
- -	CGD.	Not used.	0829
	EDT.	Not used.	0830
	EDS.	Not used.	0831
	CAS.	Not used.	0832
	ESC.	Not used.	0833

	name	Function	No.
	TR.	Thread trimming mode	0900
	TRM.	Motor operation mode during thread trimming	0901
	LTM.	Thread trimming output (T) output mode	0902
	LLM.	Thread release output (L) output mode	0903
	TS. TE.	Thread trimming output start angle	0904
	LS.	Thread trimming output angle Thread release output start angle	0905 0906
	LE.	Thread release output start angle	0907
	T1.	Thread trimming output start time	0908
	T2.	Thread trimming output time	0909
	L1.	Thread release output start time	0910
	L2.	Thread release output time	0911
key	R1.	Thread release output start time (Output TF start time)	0912
$\Box$	R2.	Thread release output time (TF output time)	0913
]+[	R3.	Condensed stiching start time (Stop time before thread trimming)	0914
느	W1.	Wiper output start time	0915
$\stackrel{\mathtt{T}}{\rightarrow}$	W2.	Wiper output time	0916
] :	WMD.	Wiper output operation mode	0917
(e)	F1.	Presser foot lifting output start time	0918
00	FD.	Time to motor drive after presser foot lifter bring down	0919
J	IL.	Interlock time during thread trimming	0920
Ľ.	IT.	Interlock time during no thread trimming	0921
sett	TDS.	Motor rotation after motor stop before thread trimming	0922
g S	TD.	Motor stop time during lockstitch and R	0923
mir		output time during chain stitch  Delay setting before reverse run during RU	
g ti	RUS.	setting	0924
nin	RT.	Delay time before reverse run during RU setting	0925
ıim	RUM.	Reverse run needle lifting [RU] after output T, L and W	0926
=	WS1.	Wiper output OFF trimming with (S1) signal	0927
G mode (Thread trimming timing setting mode): [↓]+[↑]+[C] key	S2T.	Operation mode with thread trimming signal to shift the needle stop position and return to the original needle stop position before the thread trimming signal	0928
mode	S2P.	Operation mode with thread trimming signal when shifting the needle stop position before the thread trimming signal	0929
വ	MAN.	Solenoid output OT1 manual/automatic change	0930
	HOF.	Setting of no. of stitches during MAN [OFF] setting	0931
	WB.	Weak brake ON simultaneously with wiper	0932
	TDT.	output (W)  Motor rotation operation when LTM function	0933
	C1 .	is set to T1, T2 or T3  Not used	
	C2.	Not used	0934 0935
	C3.	Not used	0936
	T3.	Not used	0937
	T4.	Not used	0938
	T5.	Not used	0939
	PET.	Not used	0940
	P9U. HHC.	Not used  Not used	0941
	PAA.	Not used	0942 0943
	STL.	Not used	0943
	L8.	Not used	0945
	PEK.	Not used	0946
	PPA.	Setting A which can be used by step sequence	0947
	PPB.	Setting B which can be used by step sequence	0948
	PPC. PPD.	Setting C which can be used by step sequence	0949
	PPD.	Setting D which can be used by step sequence Setting E which can be used by step sequence	0950 0951
	PPF.	Setting E which can be used by step sequence  Setting F which can be used by step sequence	0951
	PPG.	Setting G which can be used by step sequence	0953
	PPH.	Setting H which can be used by step sequence	0954

	name	Function	No.
it key	LHH.	Upper limit of maximum speed [H]	1000
	LHL.	Lower limit of maximum speed [H]	1001
	LLH.	Upper limit of low speed [L]	1002
ed lim ]+[D]	LLL.	Lower limit of low speed [L]	1003
lect	LTH.	Upper limit of thread trimming speed [T]	1004
g s∤ √]+	LTL.	Lower limit of thread trimming speed [T]	1005
(Setting	LNH.	Upper limit of start/end tacking (condensed stitching) speed	1006
H mode (Sett setting mode):	LNL.	Lower limit of start/end tacking (condensed stitching) speed	1007
1 n	LMH.	Upper limit of medium speed [M]	1008
- 8	LML.	Lower limit of medium speed [M]	1009
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<u>&gt;</u>	12C.	1-2 position changeover prohibit	1103
ᅕ	SLC.	Slow start changeover prohibit	1104
3	SPC.	Speed setting key changeover prohibit	1105
亍	JKC.	Not used	1106
Ą	SBC.	Start tacking validity changeover prohibit	1107
/]+[↓	SNC.	No. of start tacking stitches changeover prohibit	1108
王	EBC.	End tacking validity changeover prohibit	1109
[↑] :(;	ENC.	No. of end tacking stitches changeover prohibit	1110
ge	SKC.	Start tacking type changeover prohibit	1111
υQ	EKC.	End tacking type changeover prohibit	1112
<u> </u>	TSC.	Pattern stitching validity changeover prohibit	1113
ance	TNC.	Pattern stitching No. of stitches and times changeover prohibit	1114
μ	MDC.	Pattern mode pattern changeover prohibit	1115
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J mode (Panel switch cancel mode): [↓]+[↑]+[A]+[B] key	BPC.	Prohibit the teaching mode key switches on control switch panel	1117
e (Pa	BSC.	Prohibit the following key switches on control switch panel	1118
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Jm	вкс.	Prohibit the key switches on the control switch panel before thread trimming	1120
-	NSV.	The use number is preserved by the number call.	1121
	CMP.	It blinks compared with a set value.	1122
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		Setting the thread trimming key of control	.200
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	CNM.	Decelerate per step when Continuous is set	1205
	Ortini.	with control panel XC-G500-Y	1200
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		control	
	IOD.	Validity of operation delay when IO1 signal is input	1207
	S7B.	Delay to motor drive after B output ON	1208
	UFD.	Delay when S2 signal is U or UF	1209
	E8R.	Not used	1210
	MRA.	Not used	1211
	DAD	UP position needle lifting at the power is	
	PAP.	turned ON	1212
	ST1.	One stitch operation mode during UCR	1213
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		Thread trimming protection signal (S6)	
	S6A.	operation mode	1216
	I/Th	End tacking mode when TR function is set to	
ey	KTM.	chain stitch	1217
] k	KDM.	Lock stitch tacking menu display	1218
setting mode): [J+[1]+[A]+[C] key	UFP.	U, UF signal needle lift prohibit at position	1219
+		other than set position	1213
[A	UPB.	Weak brake validity when UP signal is ON	1220
ļ <del>, _</del>	ESB.	Weak brake forced OFF when stopped with	1221
1	UPS.	ES signal	4000
$\overline{\Rightarrow}$	UP2.	UP position detection stop  Stop status after low speed detection	1222 1223
]: (	K.	Low speed detection speed	1223
de	NAN.	Deceleration mode	1225
٥L		Presser foot lifter operation during	
J n	ESF.	emergency stop	1226
ing	PRC.	OP output and OP1 output prohibit at restart	1227
ətt	TS6.	S2 signal validity when S6 signal is ON.	1228
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ij	MFN.	Input port IL, I1 and I2 software noise filter validity	1230
/aı	PFN.	All input port software noise filter validity	1231
		No. of stitches fornoise removal during	1201
K mode (Various	SEF.	sensor input setting	1232
no	PSM.	Deceleration state during PSU, PSD signal	4000
\ \ \ \	roivi.	ON	1233
	2ST.	Low stitching speed validity when the preset	1234
		stitching is two stitches	.207
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	name	Function	No.
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÷	SPT.	T output, L output protection function	1250
K mode (Various setting mode): [↓]+[↑]+[A]+[C] key	FW .	Wiper output W ON simultaneously with presser foot lifting output FU	1251
A]±[	PS1.	Input signal check function when power is turned on	1252
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王	TOB.	Setting "OT1" output while "B" output is ON	1254
$\rightarrow$	2SL.	Special specification setting of limit contorol	1255
<u></u>	NCK.	Setting output at FWD input ON	1256
ode	UDN.	Needle lift function is invalidated, excluding the needle down position.	1257
Ξ	FSL.	The set value of full speed	1258
g	UPR.	Not used	1259
settir	HWG.	Operation gain for the big inertia sewing machine	1260
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.⊑	PCB.	Not used	1262
\ \	TQT.	Not used	1263
	E8T.	Not used	1264
g	WBO.	Not used	1265
2	R3D.	Not used	1266
	MEA.	Not used	1267
X	ocs.	Not used	1268
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	17.	signal functions	1300
	IAL.	Logical conversion function to make IA two	1301
		input signal functions	
	IAA.	Not used	1302
	IB.	Function selection of making IB two input	1303
		signal functions	
	IBL.	Logical conversion function to make IB two input signal functions	1304
	IBA.	Not used	1305
		Function selection of making IC two input	1303
>	IC.	signal functions	1306
ş l		Logical conversion function to make IC two	
$\overline{}$	ICL.	input signal functions	1307
艼ㅣ	ICA.	Not used	1308
쥰	ID.	Function selection of making ID two input	4000
뿌ᅵ	ID.	signal functions	1309
⇇	IDL.	Logical conversion function to make ID two	1310
王		input signal functions	
$\geq$	IDA.	Not used	1311
<u>;</u>	IE.	Function selection of making IE two input	1312
ō		signal functions	
ţ	IEL.	Logical conversion function to make IE two	1313
un l	IEA.	input signal functions  Not used	1314
<u>+</u>	ILA.	Function selection of making IF two input	1314
$\leq$	IF.	signal functions	1315
O mode (Extended I/O function): [↓]+[↑]+[B]+[D] key		Logical conversion function to make IF two	
용 	IFL.	input signal functions	1316
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¥	IFM.	signal functions	1317
Ú)	RFS.	Not used	1318
ю	RFR.	Not used	1319
g	RFN.	Not used	1320
Ĕ	IG.	Function selection of making IG two input	1321
ō	10.	signal functions	1321
_	IGL.	Logical conversion function to make IG two	1322
		input signal functions	1022
	IGA.	Not used	1323
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		signal functions	
	IHL.	Logical conversion function to make IH two	1325
	IHA.	input signal functions	4000
	іпа.	Not used Function selection of making II two input	1326
	II.	signal functions	1327
		Logical conversion function to make II two	
	IIL.	input signal functions	1328
	IIA.	Not used	1329
	IJ.	Not used	1330
	IJL.	Not used	1331
	IJA.	Not used	1332
	IK.	Not used	1333
	IKL.	Not used	1334
	IKA.	Not used	1335
	IL.	Not used	1336
	ILL.	Not used	1337
	ILA.	Not used	1338
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	R1S.	Not used	1349
	R1R.	Not used	1350
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	12	signal functions	1002
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		input signal functions	

	name	Function	No.
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_	I2C.	Not used	1355
(e)	2CT.	Not used	1356
<u> </u>	R2S.	Not used	1357
	R2R.	Not used	1358
±,	R2N.	Not used	1359
]±B	14.	Function selection of making I4 two input signal functions	1360
    -  -  -	I4L.	Logical conversion function to make I4 two input signal functions	1361
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O mode: [↓]+[↑]+[B]+[D] key	15.	Function selection of making I5 two input signal functions	1363
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	I5A.	Not used	1365

	name	Function	No.
	VCS.	Virtual S1 operation with VC levels	1400
	VCL.	Setting of VC1 and VC2 where virtual S1 turns ON	1401
Q mode (Speed command, Speed limit, Thread break detector setting mode): [↓]+[A]+[C] key	VCD.	Input voltage hysteresis during virtual S1 signal ON/OFF by VC and VC2 level	1402
	V1R.	VC curve reversal mode	1403
우	V15.	VC input 5V/12V changeover mode	1404
4	VC2.	VC2 operation mode	1405
7	V2R.	VC2 curve reversal mode	1406
$\geq$	V25.	VC2 input 5V/12V changeover mode	1407
de):	VL1.	Speed limiter curve inflection point 1 percentage	1408
υQ	VP1.	Speed limiter curve inflection point 1 point	1409
g	VP2.	Speed limiter curve inflection point 2 point	1410
tin	FLM.	Operation speed limit specification mode 1	1411
set	2LM.	Operation speed limit specification mode 2	1412
ctor s	LMD.	Speed command value correctly by middle speed digital during speed limit process	1413
detec	HMD.	Speed limit with digital speed setting on control switch panel	1414
퐀	E8C.	Ignore detector error	1415
īē.	TH.	Thread break sensor valid	1416
ad b	TST.	Operation after thread break sensor detection	1417
ıre	В.	Speed to ignore thread break sensor	1418
iit, T	THS.	No. of stitches to ignore thread break sensor after starting stitching	1419
d lin	THF.	Number of stitches for judgment of thread break.	1420
Spee	RFU.	Operation mode with F input during sewing machine operation	1421
and,	S7C.	Output of backtacking output (B) during OT1 output ON inhibited	1422
mmc	LIM.	Medium speed (M) limit mode during OT1 output ON	1423
ed cc	O1P.	Simultaneously ON of OP1 output during OT1 output ON	1424
be	LVB.	Disregard of S3 signal of Lever Unit	1425
de (S	PD1.	1 step heeling setting for the internal lever unit	1426
١٥	VCSET	Adjustment mode for the internal lever unit	1427
٦	MTJ.	Not used.	1428
9	MOA.	Not used.	1429
	MOB.	Not used.	1430
	MOC.	Not used.	1431
	VCA.	VC assistance ON/OFF	1432
	VCP.	Strength of VC assistance	1433

	name	Function	No.
	KSM.	KS1, KS2 output run mode	1500
	SQS.	Simple sequence start conditions	1501
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		Simple sequence output KS1 output	
	NS1.	beginning is time or the number of stitch is	1503
		selected	
	NE1.	Simple sequence output KS1 output is time	1504
		or the number of stitch is selected	1001
(e)	S1S.	Output beginning standard of simple	1505
ㅗ		sequence output KS1	
	S1E.	Output end standard of simple sequence output KS1	1506
<u>+</u>		Simple sequence output KS2 output	
中	NS2.	beginning is time or the number of stitch is	1507
<del>*</del>		selected	1001
<u> </u>	NEO	Simple sequence output KS2 output is time	
(e)	NE2.	or the number of stitch is selected	1508
9	S2S.	Output beginning standard of simple	1500
Ε	323.	sequence output KS2	1509
၂၂	S2E.	Output end standard of simple sequence	1510
Jer		output KS2	.0.0
) jd	Nes	Simple sequence output KS3 output	4544
S	NS3.	beginning is time or the number of stitch is selected	1511
l e		Simple sequence output KS3 output is time	
S mode (Simple sequence mode): [↓]+[B]+[D] key	NE3.	or the number of stitch is selected	1512
S)		Output beginning standard of simple	
<u>0</u>	S3S.	sequence output KS3	1513
8	COE	Output end standard of simple sequence	4544
∈	S3E.	output KS3	1514
S		Simple sequence output KS4 output	
	NS4.	beginning is time or the number of stitch is	1515
		selected	
	NE4.	Simple sequence output KS4 output is time	1516
		or the number of stitch is selected  Output beginning standard of simple	
	S4S.	sequence output KS4	1517
		Output end standard of simple sequence	
	S4E.	output KS4	1518
	V44	KS1 output start [Time]/[No. of Stitches]	4540
	K11.	setting	1519
	K12.	KS1 output [Time]/[No. of Stitches] setting	1520
	K21.	KS2 output start [Time]/[No. of Stitches]	1521
		setting	1021
	K22.	KS2 output [Time]/[No. of Stitches] setting	1522
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	K32.	setting   KS3 output [Time]/[No. of Stitches] setting	1504
		KS4 output start [Time]/[No. of Stitches]	1524
	K41.	setting	1525
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	K1M.	KS1 output run mode	1527
	K1D.	Run prohibit during KS1 output ON	1528
	K1C.	K11, K12 time clear during KS1 output ON	1529
	K2C.	K21, K22 time clear during KS2 output ON	1530
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	KSL.	Increase the number of K11 through K42 by	1532
		ten	1002
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	INE I.	setting each by ten times setting	1533
	KI O	Sequence output time setting/No. of stitch	4=0:
	KL2.	setting each by ten times setting	1534
	KL3.	Sequence output time setting/No. of stitch	1535
		setting each by ten times setting	1000
	KL4.	Sequence output time setting/No. of stitch	1536
		setting each by ten times setting	

Caution
Operation validity
O mark: The sewing machine can be operated in the function setting state.
X mark: The sewing machine cannot be operated in the function setting state.
Operate the sewing machine after returning to the normal mode. 24 Table of Program Mode Function

l mode.		Specification		The maximum speed can be set.	The low speed can be set.	The thread trimming speed to reach the needle UP position stop from the needle DOWN position during full heeling or when thread trimmer signal (S2) is turned ON can be set.	The speed of start tacking can be set.	The speed of end tacking can be set.	The medium speed can be set.	The slow start speed can be set.	The No. of slow start stitches can be set. This is valid when the [B, SL] key is ON in the normal mode.	The slow start operation mode is selected. This is valid when the [B, SL] key is ON in the normal mode.	Slow start operation will begin when the power is turned ON or when the first toe down after thread trimming, or the first external run signal (S0, S1) is turned ON.	Slow start operation will begin when the pedal is toed down or when the external run signal (S0, S1) is turned ON.	Slow start operation will begin when the pedal is toed down for the first time after turning the power ON, or when the first external run signal (S0, S1) is turned ON even if the [B, SL] key is turned OFF in the normal mode.	The one shot function can be selected. One shot operation (automatic operation) will begin when the external run signals (S0, S1, S4) is turned ON.	The one shot SH operation mode is selected. This is valid when one shot SH is [ON].	When one of the external run signals (S0, S1, S4) is turned ON the sewing machine will rotate at the commanded speed while ON, and will continue operating even when the signal is turned OFF. However, the speed will be that commanded with the speed setting key ([C, <==], [D, ==>] key) while OFF. Stops with PSD, PSU, ES or SEN signal.	When one of the external run signals (S0, S1, S4) is turned ON, the sewing machine will rotate at the speed commanded with each signal even if the signal is turned OFF.	The same operation as when [SS] is set is included. When one of the external run signals (S0, S1, S4) is turned (1)OFF=>ON=> (2)OFF=>ON, the sewing machine will stop at (1) and will restart at (2). (Alternate operation).
tne normai	ting			* * * *	* * *	* *	* * * *	* * * *	* * * *	* * * *	*		Ь	A	ON OF	N PO		SH	SS	SA
eturning to	Setting	isplay		***	***	* **	* * * *	* * * *	* * * *	***	*		L_	OC:	30 30	0 0 Crt		Н5	58	58
nachine affer re	Function name	Digital display		ŭ	نہ	١	Ç	Ď	C.	vi	5t.n.	51.11.			5L P.	5 <i>H</i> .	ับหร			
Operate the sewing machine after returning to the normal mode		Setting range		$6668 \sim 0$	$0\sim499$	$0\sim499$	$0 \sim 2999$	$0 \sim 2999$	6668 ~ 0	$0 \sim 2999$	1 ~ 5	ı			1	1	ı			
Opera		Unit		rpm	rpm	rpm	rpm	rpm	rpm		stitche s									
i	Factory	setting	GMFY	4000	250	200	1700	1700	1700	250	2	F			OF	OF	SH			
	► Op	erabilit	:y	0	0	0	0	0	0	0	0	0			0	0	0			
		rect cal umber		0000	1000	0005	0003	0004	0002	9000	2000	8000			6000	0010	0011			
			_	Ή.	L.	T.	Ä	٧.	M.	S.	SLN.	SLM.			SLP.	SH.	SHM.			
		Function name		Maximum speed	Low speed	Thread trimming speed	Start tacking speed	End tacking speed	Medium speed	Slow start speed	No. of slow start stitches	Slow start operation mode			Slow start when power is turned ON	One shot	One shot operation mode			CONTINUED ON THE NEXT PAGE
	Мо	de nam	ne										P mode	$\rightarrow$	+(-					

Мо				Op	Factory			Function	Setting	bu	
de na	Function name		rect c iumbe	erabi	setting	Unit	Setting range		30		Specification
ıme				lity	GMFY	T	1	Digital	Digital display		
	CONTINUED FROM PREVIOUS PAGE One shot operation mode	SHM.	0011	0	ΗS	,	,	SHI.	ú	RV	If the automatic operation function is OFF and the one shot signal (SH) is turned ON, the sewing machine will run at the low speed. If the lever connector variable speed command [VC] is input in this state, the sewing machine speed will be approximately in proportion with the voltage. The sewing machine will continue to run at the speed proportional to the variable speed command [VC] even if the one shot signal (SH) is turned OFF in the normal mode. If the automatic operation function is ON and the one shot signal (SH) is turned on, the sewing machine will run at the speed set with the speed setting key ([C], [D] key). The sewing machine will continue to run at the set speed even if the one shot signal (SH) is turned OFF.
									x	RH	The sewing machine will run at the maximum speed [H] when the one shot signal (SH) is turned ON. The sewing machine will continue to run at that speed even if the signal is turned OFF.
P mode									E.	RM	The sewing machine will run at the medium speed [M] when the one shot signal (SH) is turned ON. The sewing machine will continue to run at that speed even if the signal is turned OFF.
<b>→</b>									- <u>-</u> ا	RL	The sewing machine will run at the low speed [L] when the one shot signal (SH) is turned ON. The sewing machine will continue to run at that speed even if the signal is turned OFF.
+ (+)									B.	AV	When the one shot signal (SH) is turned OFF=> (1)ON =>OFF=> (2)ON=>OFF => (3)ON =>OFF, the same operation as the sewing machine speed is set to [RV] above is executed at (1). The sewing machine will stop at (2) and will run at the same conditions as [RV] at (3). (This operation is referred to as alternate operation hereafter.)
									æ	АН	The alternate operation of [RH] is executed.
									C: .	AM	The alternate operation of [RM] is executed.
	No. of stitches after PSU		0012	c	_	stitche	2	000	C *	**	After the UP position priority stop signal PSU is input, the no. of stitches
	input No. of stitches after PSD input	PSD.	0013	0	0	s stitche s	5	P5d.	*	*	until stopping can be set.  After the DOWN position priority stop signal PSD is input, the no. of stitches until stopping can be set.
	Sensor input signal PS1 operation mode	PS1.	0014	0	_			P5 (			The operation of the sensor input signal PS1 can be set.
	-								<b>23</b>	n	The needle will stop at the UP position. The thread trimming operation is not done. However, after stopping, the thread trimming operation is done when the pedal is heeling or when the thread trimming signal (S2) is turned ON.
									סר	Q	After thread trimming, the needle will stop at the DOWN position. This setting is the same operation as the DOWN position priority stop signal PSD.
									f	Т	After thread trimming, the needle will stop at the UP position. This setting is the same operation as the UP position priority stop signal PSU.
	No. of stitches after PS1 input	1.	0015	0	0	stitche s	6666 ~ 0		* * * *	* * * *	After the sensor input signal PS1 is input, the no. of stitches until stopping can be set.

Function Setting setting	Specification		7. The operation of the sensor input signal PS2 can be set.	The needle will stop at the UP position. The thread trimming operation is not done. However, after stopping, the thread trimming operation is done when the pedal is heeling or when the therad trimming signal (S2) is turned ON.	After thread trimming, the needle will stop at the DOWN position. This setting is the same operation as the DOWN position priority stop signal PSD.	After thread trimming, the needle will stop at the UP position. This setting is the same operation as the UP position priority stop signal PSU.	**** After the sensor input signal PS2 is input, the no. of stitches until stopping can be set.	After detecting the end of the fabric by a sensor with the PSU, PSD and SEN signals and stopping, restarting is possible with the pedal toe down or external run signal (S0, S1) even if the sensor does not detect the fabric (even if PSU, PSD signals are ON).	ON Sensor input function "SEN" is valid. [SEN] have to be set on C mode. (as OF same as the sensor key on control panel)		ON This is the momentary function of the presser foot lifting.		After thread trimming with full heeling or the external thread trimmer signal S2, the presser foot lifting operation is continued.	After thread trimming with full heeling or the external thread trimmer signal S2, the presser foot lifting operation is continued while the timer is on, and then the presser foot will lower. The timer time is set with the timer setting FCT.	The presser foot lifting operation is activated with full heeling, light heeling, or the external control signal (S2, F) ON. Then, when the full heeling, light heeling or external control signal (S2, F) is turned ON, the presser foot will bring down, and when turned ON again, the presser foot will lift. (Alternate operation.)	The timer operates in the same manner as the [C] setting. However, after the presser foot bring down, the same alternate operation as the [A] setting will occur.	The timer time for the presser foot output to turn ON and then turn OFF when the mode P FUM operation mode FU is set to [C], [T] can be set.	The time for the motor to start driving after the presser foot output FU is
			P52.				<del>من</del>	P5n.	5£ n.	9 SE.	FUU	T,					FEF.	- L
	Setting range		-				6666 ~ 0		-	$66 \sim 0$	-						$1\sim99$	0
	Onit						stitche s	1	ı	stitche s	ı	1					эəs	
Factory	setting	GMFY	D				0	OF	OF	0	OF	Σ					12	1
Ор	erabil	lity	0				0	0	0	0	0	0					0	(
	rect ca umbe		0016				0017	0018	0019	0020	0021	0022					0023	7000
			PS2.				2.	PSN.	SEN.	SE.	FUM.	FU.					FCT.	í
	Function name		Sensor input signal PS2 operation mode				No. of stitches after PS2 input	Restart after PSD,SEN input PSN	Input sensor function valid / invalid	Setting stitch amount to stop by "SEN"	Presser foot lift momentary	FUM operation mode					Time setting for FUM operation mode (FU is set to [C], [T])	Time to motor drive after
Мо	de na	me					ı	P mode	<b>→</b>	+(+		1						I

	Specification		The full wave time of the presser foot lifter output during [FU] operation can be set.	Full wave time 200mS	Full wave time 250mS	Full wave time 300mS	Full wave time 400mS	Full wave time 500mS	Full wave time 600mS	Full wave time 800mS	Full wave time 1 sec.	The delay time for the presser foot output FU to turn ON when the light heeling (lever signal presser foot lifting signal S3) is input before thread trimming can be set	The chopping output duty during holding after the presser foot lifting	output FU presser foot lifting operation can be set.	4ms ON/OFF, 50% duty	2ms ON/OFF, 50% duty	4ms ON,2ms OFF,66% duty	2ms ON,6ms OFF,25% duty	6ms ON,2ms OFF,75% duty	8ms ON,4ms OFF,66% duty	100% (full wave)	2ms ON, 4ms OFF, 33% duty	The presser foot lifting operation begins when power is turned ON. This is valid when the FUM function is set to [ON]. When FU is set to [C] or [T], the presser foot will lift only while the timer is ON.	The presser foot lifting operation after thread trimming with full heeling or the external thread trimmer signal S2 is prohibited. However, the presser foot lifting is carried out with the presser foot lifting signal F or light heeling.	The presser foot lifting operation with light heeling is prohibited. The presser foot operation is carried out with full heeling or the presser foot lifting signal F.	The thread trimming operation and subsequent presser foot lifting operation with full heeling or external thread trimmer signal S2 is prohibited.
ng				20	25	30	40	50	09	80	100	*			MS	MF	ᇁ	26	62	84	4	ГО	OP	OP	OP OF	ON
Setting	X Classic	uspiay		ري دي	<b>2</b> 5	س دی	<u></u>	53 53	C)	9 <u>0</u>	<u> </u>	* *			<u>د:</u> ص	Lu <u>.</u> C::	X	ر م	ص ص	ე- ე-		o 	ربر 0 0	0.P	ქ°	0 P
Function name		Digital display	Fo.									534	רונט	j 5									PFU	FL.	.768	521.
	Setting range											$1\sim 99$	,	ı												
	Unit		X10 msec									X10 msec											1	1		
Factory	setting	GMFY	20									10	Ш	Ξ									N O	OF	OF	OF
Ор	erabi	lity	0									0	c	)									0	0	0	0
	rect c umbe		0025									9700	7000	7700									0028	0029	0030	0031
			G									S3D.	2	2									PFU.	FL.	S3L.	S2L.
	Function name		Full wave time of presser foot lifter output									Delay time of presser foot signal S3 input	Presser foot lifting output	chopping duty									Presser foot lifting output when power is turned ON	Cancel the presser foot lifting with full heeling	Cancel presser foot lifting with light heeling	Cancel of thread trimming operation
Mod	de na	me		_	_	_		_	_		_			۵	mode		<b>→</b> ) ·	+(•	+			_				

			_								70		<u>ب</u> س					
	Specification		The operation can be changed when the thread trimming protection signal (S6) is turned Short/Open.	The sewing machine will stop when the input signal (S6) is Open.	The sewing machine will stop when the input signal (S6) is Short.	Automatic operation (standing operation) can be set.	The thread trimming operation with full heeling of the pedal or with the thread trimming signal S2 is not performed, and instead needle UP position stop will occur.	Auto-stop of preset stitch sewing before thread trimming. And then it is free sewing till thread trimming.	The motor is reverse run after thread trimming, and the needle will stop near the needle bar top dead point.	The reverse run angle from the UP position after thread trimming can be set for when the reverse run needle lifting after thread trimming RU is set to ON. The setting angle is in two degrees intervals.	The thread is trimmed with reverse feed by driving the backstitch solenoid simultaneously with the thread trimmer solenoid.	Not used.	The operation mode of full heeling or external thread trimmer signal S2 is selected. This is valid when cancel of thread trimming operation S2L is set to [OF].	With full heeling or the external thread trimmer signal S2 after the needle UP position stop, the motor will rotate once to trim the thread. Then the presser foot will lift. When stopped at the needle DOWN position, the motor will make a half-rotation and then the presser foot will lift.	The needle will remain at the UP position even when full heeling or external thread trimmer signal S2 is turned ON after stopping at the UP position. Only the presser foot lifting operation will operate after this. When full heeling or external thread trimming signal S2 is input after the needle DOWN position stop, motor will make a half-rotation and trim the thread. Only the presser foot lifting operation will operate after this.	This releases the restart operation prohibit command during thread trimming.  [ON]:Restart is possible for a designated time after the pedal toe down or external operation signal (So, S1) is turned ON immediately after full pedal heeling. This is used with a sewing machine that does not have thread trimming.  [OF]:Restart is not possible. Restart is not possible. Restart is possible if the pedal toe down or external run signal (So, S1) is turned ON again after a set time is passed.		
D				王	ГО	NO PO	OP OF	OF	NO PO	* * *	NO PO			N O	-OF		NO	占
Setting	Velcas	Spidy		- - - - -	0	00 70	9.5 9.5	00 95	00 70	* * *	00 0 0 0			C O	40		c	٠ ا
Function name	Jo letici O	Digital display	561.	•		AF.	ſĹ.	FL 5.		r 8.	ſb.	764	52r.			٠.		
	Setting range		,			ı		1	ı	$0\sim 500$	ı	1						
	Unit					ı		-	ı	degree		1				1		
Factory	setting	GMFY	P			OF	OF	OF	OF	30	OF	PO	N O			OF		
Ор	erabil	lity	×			0	0	0	0	0	0	0	0			0		
	rect c		0032			££00	0034	9800	9800	2800	8600	6800	0040			0041		
			S6L.			AT.	TL.	TLS.	RU.	R8.	TB.	TBJ.	S2R.			II.		
	Function name		Thread trimming protection signal (S6) logical changeover	•		Automatic operation	Thread trimmer cancel	Auto-stop of preset stitch sewing before trim	Reverse run needle lifting after thread trimming	RU reverse run angle	Thread trimming with reverse feed	Not used	Full heeling, S2 signal operation mode			Cancel of interlock after full pedal heeling		
Мо	de na	me			ı		•		P	<b>→</b> +	+(+)							

Function Setting	Specification Digital display	The thread trimming for each manufacturer's thread trimming sewing machine can be set.  M1 Mitsubishi, Toyota, Seiko, Yakumo, Brother (excluding those noted below)	<b>Pr C</b> PRG For free setting of the thread trimming.	NO Not thread trimming sewing machine	KA1~ Not used		<b>Eb</b> KB1∼ Not used	× × × × × × × × × × × × × × × × × × ×	B1		J JUKI (Lock stitch type)			P1		P3	P4			direction!	<b>EAG</b> KA9 Not used			KAA	KAC	RK The thread is trimmed by reverse running the motor at the set angle from the University of the DOWN position with full heeling or the thread trimmer signal S2. The	set angle can be adjusted with the reverse run angle K8 from the DOWN position. This can be used for blind stitch sewing	The present will ston in the 11D precition after thread trimming during
	Setting range			the following	edures,		( ) -	ignal SZ	- - - - -	5									 		I_	NO pag						
	ug Unit	'	=	refer to t	ment proc			I nread trimmer signal SZ		- E8	[ }	5		-		-	·			<u> </u>		S along 5	g aligie oc					
Factory	setting	M		agaidaga	niacillites ne adjusti		Ī	- I hread		88	[											N etarting	) for F8 )					
	erability	0		Caution (Toyota)	(Toyota) ng machi	- -		<b>₹</b>	:   : -   -		<b>∳</b> =  	:==	==	= = : - - :		:==	==	===== 	l::	===	==	o'lego:						
	rect call umber	0042		ر 1	he sewir		in DN		■ An e	r D	mming	Σ			T guin	Jest			T guin	ase L		o MT doi	50 for S					
	Function name	Thread trimming mode TR.		Caution (Archar) or T2 (Tourse) machines refer to the following	when setting to the Discouns of the Sewing machine adjustment procedures,	and adjust the setting.	Needle DOV position DN		Needle UP	position UP	Thread trimming	position TM			Thread trimming T	Thread release L	Wiper W		Thread trimming T	Thread release L	Wiper W	Ading the thread trimming position TM cignal's ON starting angle S8 and ON	andle F8 (The factory setting is 50 for S8 and 90 for F8)					Thread trimming validity at
		Thread trii	L		‡	<u></u>																		_				Thread

Particion name   Part			l .											
Particle   Particle		Specification	When 1 position is set with the [A, 1-2] key in the normal mode, the needle will left to the UP position if not in the UP position when the power is turned ON.	When 2 position is set with the [A, 1-2] key in the normal mode, the needle will lift to the UP position if not in the UP position when the power is turned ON.	The needle stop position angle can be set just above the fabric looking from the UP position when the input signal is set the [BC] or [BCR]. (The setting angle is in 2 degrees intervals.)	The reverse run angle from the DOWN position to the UP position can be set when the S0 operation mode [USR] or reverse thread trimming mode operation mode TR[RK] is set in mode P.		The start angle of virtual signal "TM". :When [TR] = [B1] or [T2], it is possible to use this function.		Sewing machine run without down signal. The angle between up and down position is set to "K8".  The width is set at 60 degree automatically.	It set the up and down signal width to 60 degree automatically.	Not used.	The coasting angle at the needle DOWN position stop can be set. (The setting angle is in 2 degrees intervals.)	The coasting angle at the needle UP position stop can be set. (The setting angle is in 2 degrees intervals.)
Punction name   Function name   Punction name   Function name   Punction nam	ng		ON OF	NO PO	* * *	* * *	* * *	* *	NO OF	ON OF	NO NO	ON OF	* * *	* * *
Purity   P	Setti	lisplay	0 0 Crr	0 0 Crt	* * * *	* * *	* * *	**	jo	9.5 9.5	30 0	jo	* * *	* *
Punction name	Function name	Digital c	P 1P.	P2P.	C 8.	Ł 8.	£8	58.	5ոՈ	Łď.	t dU.	P5d	d8.	UB.
Function name    Function name   Function name   Function name		Setting range			`	`	?	5	ı	-	-	ı		
Function name  Pure function name  Deperation when power is turned ON during 1 position P1P.  Operation when power is turned ON during 2 position Setting.  Needle stop position before C8. 0046 O fabric  Needle stop position before C8. 0046 O fabric  Needle stop position before C8. 0046 O fabric  NowN position to UP K8. 0049 O position  ON start angle of virtual TM S8. 0049 O  Setting sensor "SEN" input SNM. 0050 O function  Virtual down Setting KD. 0051 O  Virtual width of up and down KDU. 0052 O  Setting sensor "SEN" input SNM. 0050 O  Not used  Not used  Not used  Needle DOWN position stop D8. 0055 O  angle  Needle UP position stop D8. 0055 O  angle  Needle UP position stop D8. 0055 O  angle		Unit		1	degree	degree	degree	degree			ı	ı	degree	degree
Function name  Operation when power is turned ON during 1 position Setting. Operation when power is turned ON during 2 position Operation when power is turned ON during 2 position Operation when power is turned ON during 2 position Operation when power is turned ON during 2 position ON setting.  Needle stop position before fabric ON angle of virtual TM SR O048 ON start angle of virtual TM SR O048 ON start angle of virtual TM SR ON start angle of virtual TM Setting sensor "SEN" input Virtual down Setting Nor used  Not used  Not used  Not used  Needle DOWN position stop angle Needle UP position stop	Factory	setting GMFY	OF	PO	09	180	06	20	NO	OF	OF	OF	28	14
Function name  Operation when power is turned ON during 1 position setting. Operation when power is turned ON during 2 position P2P. setting. Needle stop position before fabric C8. Reverse run angle from DOWN position to UP K8. Position ON angle of virtual TM E8. ON start angle of virtual TM S8. Setting sensor "SEN" input SNM. Virtual down Setting KD. Virtual width of up and down KDU. Not used PSJ. Not used PSJ. Needle UP position stop D8. angle Needle UP position stop U8.	Ор	erability	0	0	0	0	0	0	0	0	0	0	0	0
Function name Operation when power is turned ON during 1 position setting. Operation when power is turned ON during 2 position setting. Operation when power is turned ON during 2 position setting. Needle stop position before fabric Reverse run angle from DOWN position to UP position ON angle of virtual TM Setting sensor "SEN" input function Virtual down Setting Virtual width of up and down signal Not used Needle DOWN position stop angle Needle UP position stop angle Needle UP position stop angle	Dir n	rect call umber	0044	0045	0046	0047	0048	0049	0900	0051	0052	0053	0054	0055
			P1P.	P2P.	89	K8.	E8.	S8.	SNM.	KD.	KDU.	PSJ.	D8.	U8.
Mode name		Function name	Operation when power is turned ON during 1 position setting.	Operation when power is turned ON during 2 position setting.	Needle stop position before fabric	run angle f position to	ON angle of virtual TM	ON start angle of virtual TM	Setting sensor "SEN" input function	Virtual down Setting	Virtual width of up and down signal	Not used	Needle DOWN position stop angle	e UP position
· · · · · · · · · · · · · · · · · · ·	Mod	de name				P mode	<b>→</b> +	· (+						

	Specification	The high/low gain can be set. Set with the following	Sewing machine with carge literia.	This is used when there is a slight vibration when stopping even when the gain is set to [L].	The size of the curve of the speed changes for Speed Speed	the pedal toe down amount can be set. The A Setting [30]	\ \ 	will change from small to large according to	the small => large of Pedal toe down	the set value.	The time for the sewing machine to reach the high speed after the pedal	toe down of external full algula (O1) is illipar call be set easily.	100ms 140ms	240mS	The time set in the next acceleration time ACT is used.	The acceleration time for the sewing machine to reach the high speed	after pedal toe down or external run signal (S1) ON can be set. This is valid when the acceleration time simple setting AC is set to [-].	The deceleration time for the sewing machine to stop after returning to	neutral from pedal toe down or when the external run signal (S1) is turned OFF can be set easily.	90mS	160mS	230mS	The time set in the next deceleration time DCT is used.	The deceleration time for the sewing machine to stop after returning to neutral from pedal toe down or when the external run signal (S1) is turned OFF can be set. This is valid when the deceleration time simple setting DC is set to [-]. Normally use this at 350 milliseconds or less.
ng		٦	C -				*					=	□ ≥	≣ _		:	*			エ	Σ	_		* *
Setting	lisplay	77	C ~	ر. د. د			**					-	cc			:	* *			æ	<b>C</b> :	4	•	* *
Function name	Digital display	S.R.					יירם				RC.							ي	ر. د.					dEr.
	Setting range	1					10 ~ 99										66 ∼ 9							66 ~ 9
	Unit	ı						ı								X10	msec		ı					X10 msec
Factory	Setting	٦					90	8			Σ						4	:	Σ					16
Оре	erability	0					C	)			0						0	(	0					0
	ect call umber	0100					0101	2			0102						0103		0104					0105
	Function name	Gain high/low selection GA.					Pedal cirve				Acceleration time simple AC.						Acceleration time ACT.	time simple						Deceleration time DCT.
Mod	de name				•						4 g	200	<b>→</b>	)+(	* <u>*</u>									

	Specification		The speed change curve is accelerated slowly for the time after pedal toe down or the external run signal (S1) is turned ON, and then the sewing machine accelerates rapidly and enters the high speed operation. This is effective when carrying out one stitch sewing with the external run signal (S1) when automatic operation function is set in the P mode.	The "t" time can set when S-character cushion is set to [ON].	The operation mode of the full heeling or S2 signal when the power is turned on or after thread trimming is determined.	The presser foot lifting operation is entered.	The needle lifting operation is entered.	No operation.	The presser foot lifting operation after needle lifting is entered.	The speed setting is set so that the normal sewing machine shaft speed is constant, but by the [ON] setting, it is possible to operate at the value which was set by the [MR], [SR] function. This is effective when the motor pulley diameter is small, the V belt slips and the sewing machine speed is unstable.	Set the diameter of motor pulley When "PL" is "ON", this function is valid.	Set the diameter of sewing machine pulley When "PL" is "ON", this function is valid.	Variable operation is possible when the detector has broken by setting to [ON] to invalidate the detector. The positioning stop and thread trimming operations will not be possible.	When machine will be stopped, first priority become speed control. (Usually first priority to stop is stopped angle.)	The brake time for stopping the sewing machine can be set.	Setting the angle to clear weak break. Minimum setting angle is 0.2 degree.
ng			OP OF	*		IJ	כ	ON	UF	OF	* *	* * *	ON OF	ON OF	*	*
Setting	lisplay		40 0	* *		27	<b>≂</b> ⊃	00	ΩĘ	ქ0 00	* * *	* * * *	<i>ქ</i> 0	30	**	* *
Function name	Digital display		5£.	.135	520.					PŁ.	Ir.	5r.	500	ับ /5	.744	89
;	Setting range		ı	66 ~ 0							$20 \sim 349$	20 ~ 349	ı	1	$66 \sim 0$	$4\sim 500$
	Unit		,	X10 msec	1					1	mm	шш	-	-	X10 msec	X0.1 degree
Factory	setting	GIVIFY	OF	7	FU					OF	20	02	OF	OF	14	14
Оре	erability	,	0	0	0					0	0	0	0	0	0	0
	ect call umber		0106	0107	0108					0109	0110	0111	0112	0114	0115	0116
	ате		S.	e sct.	ower S2M.					motor <b>PL.</b> ection	meter MR.	machine <b>sR</b> .	NOS.	speed STM.	BKT.	B8.
	Function name		S-character cushion	S-character cushion time setting	Full heeling S2 signal operation mode when power is turned on or after thread trimming	, ,				Sewing machine shaft/motor shaft speed setting selection	Setting motor pulley diameter	Setting sewing ma pulley diameter	No detector mode	First priority stop => s control	Brake time	Weak brake angle
Mod	le name	Э			A mode	+ (	<u>+                                    </u>	)								

Function Setting name	Specification	Digital display	<b>bnr.</b> OF Reducing the sound (noise) of weak brake.	<b>b.E.S.</b> ** The weak brake force can be set.	The weak brake force can be set for when stopping the sewing machine when the weak brake [BK] is set to [ON].	E Brake that allows manual rotation.	R Strong brake.	<b>b</b> E. OF The weak brake validity can be set.
	Setting range		•	$1\sim99$	ı			
	Onit		-	%				
Factory	setting	GMFY	NO	66	Ш			OF
Ор	erabi	lity	0	0	0			0
	ect c umbe		0117	0118	0119			0120
	Function name		Reduction of weak brake <b>BNR</b> . sound	Weak brake force BKS.	Weak brake mode BKM.			Weak brake BK.
Mod	de na	me		Α.	mode -	<del>)</del> +[	Z - 1 - 2 - 1 - 2 - 1	

	Specification	Selection of count down condition.	After thread trimming is finished	The number of sewing stitch become "N" ("N" have to be set at "CNU")	The number of trimming times become "N" ("N" have to be set at "PRN")	When input function "IO1" become ON. ("IO1" have to be set to input signal on the program mode C.)	When output signal "O1"become ON. ("O1"have to be set to output function on "O1" of the program mode C.)	Selection of operation at count over. (Down counter)	Control panel buzzes and running is prohibited after thread trimming with buzzer sound. And then when Down counter clear key "CCD" is pressed, buzzer and sewing become possible. (Buzzer will stop after a while.) (Factory setting of Up counter clear key is "P" key on control panel.)	Sewing is possible to continue without buzzer sound.	Sewing is possible to continue with buzzer sound. (Buzzer will stop after a while.)	[ON]:When sewing pattern is changed, it clear "down counter".	[ON]:The down counter is valid.	The down counter action, after counting over. (It is valid, when [DSC] is set to "OF", "BZ".	The display shows "0" and the counting is stopped.	The display shows "-" and the counting is continued.	When power switch is turned on.	Up counter is clear (zero) and down counter is set the setting number.	Both counter keep previous amount.	When "CUP" and "CDN" are PR, trimming times "N" is set.	When "CUP" and "CDN" are ST, number of stitch "N" is set.
ng			20	ST	PR	Z	OO		ST	Р	BZ	N P	N P P		NO	R		NO	유	* *	* *
Setting	lisplay		ננ	<b>S</b> ŗ	مرم	ć	υÜ		5,	96		, , ,	30 00		υo	0 ل		co	7,0	*	* *
Function name	Digital display	[dn						.356				dEn.	do£.	o!!d.			ับ Jd			Pro	じっぴ
	Setting range							1					,							66 ~ 0	1 ~ 99
	Unit	ı											1				1			times	stitche s
Factory	Setting	CC						ST				OF	OF	OF			OF			0	1
Ор	erability	0						0				0	0	0			0			0	0
	ect call umber	0210						0211				0212	0213	0214			0215			0216	0217
	Function name	Down counter the selection CDN. of setting mode	,					Down counter the selection <b>DSC</b> . of counter operation				Down counter changing <b>DCM</b> . sewing pattern	Down counter valid / invalid DNC.	Down counter operation after NXD. counting over			Counter condition turning on <b>PCM</b> . power switch			Setting Thread trimming PRN. times "N"	Setting Number of stitches CNU. "N"
Mod	de name								ω.	mode	<b>→</b> +	. (° ± ± 0)					•				

	Specification	Modification of count amount.	When input function "IO1" is turned on, it becomes count up. When input function "IO2" is turned on, it becomes count down. (Input function can set input signal on program mode "C".)	Modification is prohibited.	Selection display mode, when power switch is turned on.	When power switch turned on, display shows previous condition. (Keep previous condition)	When power switch turned on, display shows normal mode.	Reset for Up / Down counter during operation.	Reset for Up / Down counter is valid.	Reset for Up / Down counter is invalid.
Setting			o O	冶		NO N	R		8 O	P
Set	isplay		co	0 بر		CO	0 ک		c o	οF
Function name	Digital display				PAd			CCA		
	Setting range									
	Unit							1		
Factory	setting	R			OF			OF		
Оре	erability	0			0			0		
	ect call umber	0218			0219			0220		
	Function name	Count modification (to use CCI.			Display condition turning on <b>PMD</b> . power switch	-		Reset for Up / Down counter <b>CCM.</b>		
Mod	de name			B mode		+ [	19	<u> </u>		

nde			0	Factory			Function	Setting	Бu	
ne	Function name	irect o	perab	setting	Unit	Setting	5			Specification
ame			ility	GMFY			Digital display	display		
T S	Function selection of input <b>IA.</b> signal IA	0300	×	PSU			,R	* * *	* * *	The input functions of each input signal IA can be selected from 80 types of functions. $(*1)$
7 0	Logical conversion function IAL. of input signal IA	0301	×	OF		,	,AŁ.	jo Jo	ON OF	The input logic of each Input signal IA is reversed.
8	Alternating operation of input IAA. signal IA	0302	×	Ą	1	,	,A.A.	0 0 Crt	ON OF	If each input signal IA performs OFF => (1)ON => OFF => (2)ON => OFF => (3)ON => OFF the signal will stay ON at (1) ,stops (turn OFF) at (2) , and will turn ON again at (3). (This is hereafter referred to alternate operation.) (*2)
T S	Function selection of input IB.	0303	×	PSD			á	* * *	* *	The input functions of each input signal IB can be selected from 80 types of functions. $(*1)$
	Logical conversion function IBL. of input signal IB	0304	×	OF	-	,	ıbł.	go go	ON OF	The input logic of each Input signal IB is reversed.
s S	Alternating operation of input IBA. signal IB	0305	×	OF	1		,6 <i>R</i> .	до 20	ON OF	If each input signal IB performs OFF => $(1)$ ON => OFF => $(2)$ ON => OFF => $(3)$ ON => OFF the signal will stay ON at $(1)$ , stops (turn OFF) at $(2)$ , and will turn ON again at $(3)$ . (This is hereafter referred to alternate operation.) $(*2)$
<u>                                     </u>	Function selection of input IC.	9080	×	SO			ىي	* * *	* * *	The input functions of each input signal IC can be selected from 80 types of functions. $(*1)$
	Logical conversion function ICL. of input signal IC	0307	×	OF		ı	יני.	jo Jo	ON OF	The input logic of each Input signal IC is reversed.
PD → + (1	Alternating operation of input ICA. signal IC	0308	×	OF	1		ı.C.R.	ئ ئ و	ON OF	If each input signal IC performs OFF => $(1)ON => OFF => (2)ON => OFF => (3)ON => OFF$ the signal will stay ON at (1) ,stops (turn OFF) at (2) , and will turn ON again at (3). (This is hereafter referred to alternate operation.) (*2)
	Function selection of input ID.	6080	×	TL	-	1	ئم	* * *	**	The input functions of each input signal ID can be selected from 80 types of functions. $(*1)$
7	Logical conversion function IDL. of input signal ID	0310	×	OF	-	,	יפל.	jo	ON OF	The input logic of each Input signal ID is reversed.
8	Alternating operation of input IDA. signal ID	0311	×	OF	1		å. Ab	0 0 CA	ON OF	If each input signal ID performs OFF => $(1)ON => OFF => (2)ON => OFF => (3)ON => OFF$ the signal will stay ON at (1) ,stops (turn OFF) at (2) , and will turn ON again at (3). (This is hereafter referred to alternate operation.) (*2)
<u> </u>	Function selection of input <b>IE.</b> signal IE	0312	×	S7		1	ι'n	* * *	*	The input functions of each input signal IE can be selected from 80 types of functions. $(*1)$
0	Logical conversion function IEL. of input signal IE	0313	×	OF	-	,	.£Ł.	jo	ON OF	The input logic of each Input signal IE is reversed.
, s	Alternating operation of input <b>IEA.</b> signal IE	0314	×	OF	ı		.E.R.	0 ئو	ON OF	If each input signal IE performs OFF $\Rightarrow$ (1)ON $\Rightarrow$ OFF $\Rightarrow$ (2)ON $\Rightarrow$ OFF $\Rightarrow$ (3)ON $\Rightarrow$ OFF the signal will stay ON at (1) ,stops (turn OFF) at (2) , and will turn ON again at (3). (This is hereafter referred to alternate operation.) (*2)
<u> </u>	Function selection of input IF. signal IF	0315	×	Ь	-	-	υ <u>.</u>	* * *	* * *	The input functions of each input signal IF can be selected from 80 types of functions. (*1)

-							Function	3		
Mod			Оре	Factory		;	name	Semile	6	
	Function name	ect c	erabil	setting	Unit	Setting range	ָרְ נְיִבְּיָבְיִבְּיִבְּיִבְּיִבְּיִבְּיִבְּיִבְּיִב	Sold Gold		Specification
			lity	GMFY			Digital display	dispilay		
	Logical conversion function <b>IFL</b> of input signal IF	0316	×	-OF		ı	.F.	0 0 7	NO O	The input logic of each Input signal IF is reversed.
	Operation selection of input IFM.	0317	×	O <sub>N</sub>	,		,F.P.			The operation mode of each input signal IF can be selected.
								0	ON	Normal operation.
								æ	AL	Alternating operation.
								r V	RS	RS F/F (Flip-Flop) operation.
1	Set condition of RS F/F RFS. operation of input signal IF	0318	×	Z		ı	7.55			Set condition RS F/F of IF When [IFM] is set to [RS], it is valid.
	-							ć	Z	RS F/F of IF is set by IF
								<b>L</b>	⊢	After thread trimming operation (stop to up position.)
								L	~	When motor start, RS F/F will be set.
ပ								ഗ	တ	When motor stops, RS F/F will be set.
1)								ا اسم	TR	When sewing start, after thread trimming.
								56	SB	When start tacking or condensed stitch was finished.
) <b>+</b> [	Reset condition of RS F/F RFR. operation of input signal IF	0319	×	Z	,		ب کا کا م			Reset condition RS F/F of IF When [IFM] is set to [RS], it is valid.
	-							ć	Z	RS F/F of IF is reset by IOG.
								<b>L</b>	<b>⊢</b>	When thread trimming is done (stop to up position.)
								e.	~	When motor start, RS F/F will be reset.
								ורני	တ	When motor stops, RS F/F will be reset.
								L L-	뀖	When sewing start, after trimming.
								5 -0	SB	When start condensed stitch was finished.
								nί	NC	When sewing machine sew the setting stitch after set RS F/F, it will be reset. (R1N, R2N)
	Number of reset needles of <b>RFN.</b> RS F/F operation of input IF	0320	×	3	stitche s	$66 \sim 0$	r.F.n.	* *	*	When [RFR] set [NC], the number of stitch is set by this counter.
ı	Function selection of input IG.	0321	×	S1			ů.	* * *	* * *	The input functions of each input signal IG can be selected from 80 types of functions. $(*1)$
	Logical conversion function IGL. of input signal IG	0322	×	OF	1	ı	ىڭ!.	go go	ON OF	The input logic of each Input signal IG is reversed.
<u> </u>	Alternating operation of input IGA. signal IG	0323	×	OF	1	ı	,CR	90 90	OF OF	If each input signal IG performs OFF => (1)ON => OFF => (2)ON => OFF => (3)ON => OFF the signal will stay ON at (1) ,stops (turn OFF) at (2) , and will turn ON again at (3). (This is hereafter referred to alternate operation.) (*2)
1	Function selection of input IH.	0324	×	S2			πį	* * *	* * *	The input functions of each input signal IH can be selected from 80 types of functions. (*1)

	Specification		The input logic of each Input signal IH is reversed.	If each input signal IH performs OFF => (1)ON => OFF => (2)ON => OFF => (3)ON => OFF the signal will stay ON at (1) ,stops (turn OFF) at (2) , and will turn ON again at (3). (This is hereafter referred to alternate operation.) (*2)	The input functions of each input signal II can be selected from 80 types of functions. (*1)	The input logic of each Input signal II is reversed.	If each input signal II performs OFF => (1)ON => OFF => (2)ON => OFF => (3)ON => OFF the signal will stay ON at (1) ,stops (turn OFF) at (2) , and will turn ON again at (3). (This is hereafter referred to alternate operation.) (*2)	Not used.	Not used.	Not used.	Not used.	Not used.	Not used.	Not used.	Not used.	Not used.	The input functions of each input signal IM can be selected from 80 types of functions. (*1)	The input logic of each Input signal IM is reversed.	If each input signal IM performs OFF => (1)ON => OFF => (2)ON => OFF => (3)ON => OFF the signal will stay ON at (1) ,stops (turn OFF) at (2) , and will turn ON again at (3). (This is hereafter referred to alternate operation.) (*2)	The input functions of each input signal IN can be selected from 76 types of functions. (*1)
ing			N P	N P	* * *	N P	OP	* * *	N P	NO PO	* *	O O	S P	* *	O O	8 P	* * *	8 P	N P	* * *
Setting	, , , ,	ıısplay	jo	0 0 CA	* * *	30 00	00 70	* * *	30 00	jo	* *	jo	0 0 1	* * *	jo	0 C	* * *	0 0 0 0 0	0 0 CA	* * *
Function		Digital display	iHL.	ж. Э.	: -	، ن	, ,R.	, Ĵ	יל!.	,JR	ıt.	ن <del>د</del> از.	r G	١٠.	ין ן.	, P.	c.	III.	,A.R.	ć
	Setting range	1	1	1		1		•		1	-	1	1	-	1	1		1		
	Unit		1				,				-							1		
Factory	setting	GMFY	OF	OF	S3	OF	OF	ON	OF	OF	NO	OF	OF	NO	OF	OF	ON	OF	OF	ON
Ор	erabi	lity	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×
	rect c umbe		0325	0326	0327	0328	0329	0880	0331	0332	0333	0334	0335	0336	2820	0338	0339	0340	0341	0342
	Function name		Logical conversion function IHL. of input signal IH	Alternating operation of input IHA. signal IH	Function selection of input II.	Logical conversion function IIL. of input signal II	Alternating operation of input IIA. signal II	Not used IJ.	Not used IJL.	Not used IJA.	Not used IK.	Not used IKL.	Not used IKA.	Not used IL.	Not used	Not used	Function selection of input IM. signal IM.	Logical conversion function IML. of input signal IM	Alternating operation of input IMA. signal IM	Function selection of input IN. signal IN
Mod	de na	me				_	O	mode	<b>→</b> +	÷ 0 1								_		

	Specification		The input logic of each Input signal IN is reversed.	If each input signal IN performs OFF => (1)ON => OFF => (2)ON => OFF => (3)ON => OFF the signal will stay ON at (1) ,stops (turn OFF) at (2) , and will turn ON again at (3). (This is hereafter referred to alternate operation.) (*2)	The input functions of each input signal IO can be selected from 80 types of functions. (*1)	The input logic of each Input signal IO is reversed.	If each input signal IO performs OFF => (1)ON => OFF => (2)ON => OFF => (3)ON => OFF the signal will stay ON at (1) ,stops (turn OFF) at (2) , and will turn ON again at (3). (This is hereafter referred to alternate operation.) (*2)	The input functions of each input signal IP can be selected from 80 types of functions. (*1)	The input logic of each Input signal IP is reversed.	If each input signal IP performs OFF => (1)ON => OFF => (2)ON => OFF => (3)ON => OFF the signal will stay ON at (1) stops (turn OFF) at (2) , and will turn ON again at (3). (This is hereafter referred to alternate operation.) (*2)	The input functions of each input signal IQ can be selected from 80 types of functions. (*1)	The input logic of each Input signal IQ is reversed.	If each input signal IQ performs OFF => (1)ON => OFF => (2)ON => OFF => (3)ON => OFF the signal will stay ON at (1) ,stops (turn OFF) at (2) , and will turn ON again at (3). (This is hereafter referred to alternate operation.) (*2)	The input functions of each input signal IR can be selected from 80 types of functions. (*1)	The input logic of each Input signal IR is reversed.	If each input signal IR performs OFF => (1)ON => OFF => (2)ON => OFF => (3)ON => OFF the signal will stay ON at (1) ,stops (turn OFF) at (2) , and will turn ON again at (3). (This is hereafter referred to alternate operation.) (*2)	The input functions of each input signal 11 can be selected from 80 types of functions. (*1)	The input logic of each Input signal I1 is reversed.
Du Bu			N P	N O P	* * *	NO P	N P	* * *	NO PO	O O	* * *	NO PO	O O	* * *	NO PO	N O P	* * *	OP
Setting	yelde	lispidy	0 0 7	0 0 Cr	* * *	jo	0 0 Cr	* * *	CUL 0 0	0 0 Cr	* * *	0 0 C/J	0 0 7	* * *	30	0 0 CA'	* * *	30 30
Function	velasio latini	Digital	int.	a. A.	Õ	ıoł.	â.	ď.	.P.	P. P.	oį.	,9;	, 9,	ŕ.	ırt.	or.		, 1L.
	Setting range			1		-		-	1	,		1	1		-	1		
	Unit			1	,						,		1	,		1	,	
Factory	setting	GMFY	OF	Ą	ON.	OF	R	ccn	OF	OF	O <sub>N</sub>	OF	Ą	O <sub>N</sub>	OF	Ą	101	OF
Ор	erabil	lity	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×
	rect ca umbe		0343	0344	0345	0346	0347	0348	0349	0320	0351	0352	0353	0354	0355	0356	0357	0358
	Function name		Logical conversion function INL. of input signal IN	Alternating operation of input INA. signal IN	Function selection of input IO. signal IO	Logical conversion function IOL. of input signal IO	Alternating operation of input IOA. signal IO	Function selection of input <b>IP.</b> signal IP	Logical conversion function IPL. of input signal IP	Alternating operation of input IPA. signal IP	Function selection of input IQ.	Logical conversion function IQL. of input signal IQ	Alternating operation of input IQA. signal IQ	Function selection of input IR. signal IR.	Logical conversion function IRL. of input signal IR	Alternating operation of input IRA. signal IR	Function selection of input II.	Logical conversion function 11L. of input signal I1
			Logical conversic of input signal IN	Alternating signal IN	Function so signal IO	Logical conversio of input signal IO	Alternating signal IO	Function so signal IP	Logical cor of input sig				Alternating signal IQ	Function so signal IR	Logical conversic of input signal IR	Alternating signal IR	Function so signal 11	Logical conversic of input signal I1
Мо	de na	me								သ mode	<b>+</b> [0							

Function name  RS F/F reset stitch amount R1N.  Function selection of input I2.  I2 input logic changeover I2L.  Operation selection of input I2M.  Signal I2  AL operation clearness of I2C.  Input signal I2  Delay time of AL operation of 2CT.  Set condition of RS F/F for I2 R2S.	Direct call number 03 0 03 17 27 8 27 4 75 0 03 10 20	Operability O × × × × × O ×	Factory setting GMFY OF OF OF OF OF	Unit stitche stitche	Setting range   0 \( \times \)   1 \( \t	Function name of the property		* * * O O O A S O O A T A S O O A T A T A T A T A T A T A T A T A T	Specification  When [R1R] set [NC], the number of stitch is set by this counter.  The input functions of each input signal I2 can be selected from 80 types of functions. (*1)  The operation mode of each input signal I2 can be selected.  Normal operation.  Alternating operation.  AL operation of input signal [I2] is cleared by thread trimming operation.  When above setting I2C is valid, these delay timer is set.  Set condition RS F/F of I2 When [I2M] is set to [RS], it is valid.  RS F/F of I1 is set by I2  After thread trimming operation (stop to up position.)  When motor start, RS F/F will be set.  When motor stops, RS F/F will be set.  When sewing start, after thread trimming.
		12. 12L. 12L. 12M. R1N. R2S.	12L   12L	12L   12L	12L   0370   Setting setting setting setting setting setting large   Setting setting setting large   Setting	12L. 0370	Setting   Sett	Pactory Setting   Pactory Setting   Pactory Setting   Pactory   Pactory	Color   Pactory   Pactor

_		[	C				Function	Setting	ng	
	Function name	Direct ca number	perabili	setting	Unit	Setting range	Digital display	display		Specification
			ty	GMFY						
<b>—</b>	Reset condition of RS F/F for R2R. I2	0376	×	Z			י בי			Reset condition RS F/F of IF When [I2M] is set to [RS], it is valid.
								ć	≧	RS F/F of I2 is reset by IOF.
								L	⊢	When thread trimming is done (stop to up position.)
								L	∝	When motor start, RS F/F will be reset.
								ഗ	တ	When motor stops, RS F/F will be reset.
								ر اب	T	When sewing start, after trimming.
								56	SB	When start condensed stitch was finished.
								υĘ	NC	When sewing machine sew the setting stitch after set RS F/F, it will be reset. (R2N)
	RS F/F reset stitch amount R2N. for I2	0377	0	3	stitche	$66 \sim 0$	rZn	* *	*	When [R2R] set [NC], the number of stitch is set by this counter.
1	Function selection of input <b>14.</b> signal 14	0378	×	ON N			J.	* * *	* *	The input functions of each input signal I4 can be selected from 80 types of functions. (*1)
	Logical conversion function <b>14L.</b> of input signal 12	0379	×	OF		,	'ሕ'	jo Jo	JO NO	The input logic of each Input signal I4 is reversed.
	14 input alternating operation 14A.	0380	×	OF	1		بر بر	0 0 Crr	OF	If each input signal 14 performs OFF => (1)ON => OFF => (2)ON => OFF as (3)ON => OFF the signal will stay ON at (1) stops (turn OFF) at (2), and will turn ON again at (3). (This is hereafter referred to alternate operation.) (*2)
	Function selection of input 15. signal 15.	0381	×	NO			2,	**	**	The input functions of each input signal 15 can be selected from 80 types of functions. $(*1)$
	Logical conversion function <b>I5L.</b> of input signal I5	0382	×	OF			.5٤.	jo Jo	NO NO	The input logic of each Input signal I5 is reversed.
	Alternating operation of input <b>I5A.</b> signal I5	0383	×	OF			95.	ט ס נעג	OP OF	If each input signal 15 performs OFF => (1)ON => OFF => (2)ON => OFF => (3)ON => OFF the signal will stay ON at (1) ,stops (turn OFF) at (2) , and will turn ON again at (3). (This is hereafter referred to alternate operation.) (*2)
	Function selection of input I6. signal I6	0384	×	NO			,6.	* * *	* * *	The input functions of each input signal 16 can be selected from 80 types of functions. $(*1)$
	Logical conversion function <b>I6L.</b> of input signal I6	0385	×	OF			.56.	30 00	NO OF	The input logic of each Input signal 16 is reversed.
	Alternating operation of input <b>I6A.</b> signal I6	0386	×	OF		•	,6R.	90 90	OF OF	If each input signal 16 performs OFF => (1)ON => OFF => (2)ON => OFF as (3)ON => OFF the signal will stay ON at (1) ,stops (turn OFF) at (2) , and will turn ON again at (3). (This is hereafter referred to alternate operation.) (*2)
	Function selection of input I7.	0387	×	ON			در.	* * *	* *	The input functions of each input signal I7 can be selected from 80 types of functions. $(*1)$

		ı		ı							
	Specification	The input logic of each Input signal I7 is reversed.	If each input signal I7 performs OFF => (1)ON => OFF => (2)ON => OFF => (3)ON => OFF the signal will stay ON at (1) ,stops (turn OFF) at (2) , and will turn ON again at (3). (This is hereafter referred to alternate operation.) (*2)	<b>□</b>	(Option A connector)  IA:PSU(Needle UP position priority stop signal)  IB:PSD(Needle DOWN position priority stop signal)  IC:S0 (Low speed run signal)	= /,	(2) (a) (b) (c) (c) (c) (c) (c) (d) (d) (d) (d) (e) (e) (e) (e) (e) (e) (e) (e) (e) (e			The output functions of each output signal OA can be selected from 58 types of functions. (*3)	The output logic of each output signal OA is reversed.
ng		ON PO	OP OF	, L		4	<u>.</u>			**	ON
Setting	display	0.P	0 0 Cry			al) gnal)		nnector.		* *	ор о Е
Function name	Digital display	,3F.	,7R.		d run signal) er signal) ter signal)	nnector) sr cancel sign during run sig	onnector ) er signal)	l are not at co		o.R.	oAL.
	Setting range		,		(Lever connector) IG:S1(Variable speed run signal) IH:S2(Thread trimmer signal) II:S3(Presser foot lifter signal)	(Sewing machine connector) ID:TL(Thread trimmer cancel signal) IE:S7(Backstitching during run signal)	(Presser foot lifter connector ) IF:F(Presser foot lifter signal)	ese input signa	(3)ON => OFF n at (3).		-
	Unit	1		l zation]	(Leve 1G:S: 1H:S; 11:S3	(Sew ID:TL IE:S7	(Pres IF:F(	are. So th	> OFF => n ON agai		1
Factory	Setting	OF	OF	l on C mode tput customi	□			by the Softw	: => (2)ON = , and will tur	_	OF
Ор	erability	×	×	or signa t and ou		(1) (2) (3) (4) (4) (4) (4) (4) (4) (4) (4) (4) (4	$\bigcirc \bigcirc \bigcirc \bigcirc \bigcirc \bigcirc \bigcirc$	d output	=> OFF F) at (2) ttion.)	×	×
	ect call umber	0388	0389	unction f e of inpu		(-4) (-4)		input an	> (1)ON (turn OF ite opera	0380	0391
	Function name	Logical conversion function <b>I7L.</b> of input signal I7	Alternating operation of input 17A. signal 17	(*1) *Refer to [25.Table of input/output function for signal on C mode] *Refer to [26.The composition figure of input and output customization]	<u>'</u> =			Caution Input signal [16,17] are coupling port of input and output by the Software. So these input signal are not at connector.	(*2) If each input signal performs OFF => (1)ON => OFF => (2)ON => OFF => (3)ON => OFF the signal will stay ON at (1), stops (turn OFF) at (2), and will turn ON again at (3). (This is hereafter referred to alternate operation.)	Function selection of output <b>oA.</b> signal OA	Logical conversion function <b>OAL.</b> of output signal OA
Mod	de name		•			O wode + +	• 0 1				

	Specification		Each output is output with full wave immediately after output starts, and then is reduced to half-wave output for each output signal OA. (Chopping control) The full wave output time can be set with the full wave time [PO] function for each output.	In each output signal OA, each output is forcibly turned OFF after the time set in the OFF timer is passed. The OFF timer set time can be set with each output's forced OFF timer [OTT] function.	In each output signal OA the delay time to when each output is started can be set. Each delay time can be set in 2msec intervals.	The output functions of each output signal OB can be selected from 58 types of functions. (*3)	The output logic of each output signal OB is reversed.	Each output is output with full wave immediately after output starts, and then is reduced to half-wave output for each output signal OB. (Chopping control) The full wave output time can be set with the full wave time [PO] function for each output.	In each output signal OB, each output is forcibly turned OFF after the time set in the OFF timer is passed. The OFF timer set time can be set with each output's forced OFF timer [OTT] function.	In each output signal OB the delay time to when each output is started can be set. Each delay time can be set in 2msec intervals.	The output functions of each output signal OC can be selected from 58 types of functions. (*3)	The output logic of each output signal OC is reversed.	Each output is output with full wave immediately after output starts, and then is reduced to half-wave output for each output signal OC. (Chopping control) The full wave output time can be set with the full wave time [PO] function for each output.	In each output signal OC, each output is forcibly turned OFF after the time set in the OFF timer is passed. The OFF timer set time can be set with each output's forced OFF timer [OTT] function.	In each output signal OC the delay time to when each output is started can be set. Each delay time can be set in 2msec intervals.	The output functions of each output signal OD can be selected from 58 types of functions. (*3)	The output logic of each output signal OD is reversed.	Each output is output with full wave immediately after output starts, and then is reduced to half-wave output for each output signal OD. (Chopping control) The full wave output time can be set with the full wave time [PO] function for each output.
ng			JO NO	ON OF	* * *	* * *	ON PO	ON OF	JO NO	* * *	* *	ON OF	ON OF	ON OF	* * *	* * *	JO NO	OP OF
Setting	yolooj	ııspıay	3°	00 0 £	* * *	* * *	00 20	0 0 7	<i>ქ</i> 0	* * *	* *	jo	00 90	90 90	* * *	* * *	30 00	0 0 74 0
Function name	o letinio	Digital display	.JBo	oRF.	dR.	ob.	obł.	ob£.	.740	ďЪ	o£.	٥٤٤.	of C.	oEF.	dľ.	00	odł.	odť.
	Setting range		ı		$0\sim510$		1	1	-	$0 \sim 510$	-	-	ı		$0\sim510$		-	
	Unit		1		msec.					msec.			1		msec.	,		ı
Factory	setting	GMFY	OF	-OF	0	×	OF	OF	OF	0	В	OF	OF	OF	0		OF	OF
Ор	erabil	lity	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×
	ect caumbe		0392	0393	0394	0395	0396	0397	0398	0399	0400	0401	0402	0403	0404	0405	0406	0407
	Function name		Chopping operation of output <b>OAC.</b> signal OA	Output signal OA compulsion <b>OAT.</b> OFF	Delay time of output signal <b>DA.</b> OA	Function selection of output <b>OB.</b> signal OB	Logical conversion function <b>OBL</b> .	Chopping operation of output <b>OBC.</b> signal OB	Output signal OB compulsion <b>OBT.</b> OFF	Delay time of output signal <b>DB.</b> OB	Function selection of output oc. signal OC	Logical conversion function <b>ocl.</b> of output signal OC	Chopping operation of output occ. signal OC	Output signal OC compulsion oct.	Delay time of output signal <b>DC.</b>	Function selection of output <b>op.</b> signal OD	Logical conversion function <b>opl.</b> of output signal OD	Chopping operation of output obc. signal OD
Mod	de na	me			1	1	1			1	C mode	<b>→</b>	+ 0		1	1		

	Specification		In each output signal OD, each output is forcibly turned OFF after the time set in the OFF timer is passed. The OFF timer set time can be set with each output's forced OFF timer [OTT] function.	In each output signal OD the delay time to when each output is started can be set. Each delay time can be set in 2msec intervals.	The output functions of each output signal OF can be selected from 58 types of functions. (*3)	The output logic of each output signal OF is reversed.	The chopping output duty during holding after the presser foot lifter output FU lifting operation can be set.	4ms ON/OFF 50% duty	2ms ON/OFF 50% duty	4ms ON, 2ms OFF, 66% duty	2ms ON,6ms OFF,25% duty	6ms ON,2ms OFF,75% duty	8ms ON,4ms OFF,66% duty	100% (full wave)	2ms ON, 4ms OFF 33% duty	The full wave output time of the presser foot lifter output FU can be set.	200ms	250ms	300ms	400ms	500ms	600ms	800ms	1000ms	The operation mode of presser foot lifter momentary FUM is set. This is valid when	The presser foot lifter operation is continued after full heeling or after	thread trimmer with external thread trimmer signal S2.	The presser foot lifter operation is continued during the time after full heeling or	lifter is lowered. The time r can be adjusted with timer setting FCT in the P mode.	The presser foot lifting operation is activated with full heeling, light heeling, or the	external control signal (Sz., F) ON. Then, when the full heeling, light neeling of external control signal (Sz., F) is turned ON, the presser foot will bring down, and	when turned ON again, the presser foot will lift. (Alternate operation.)	presser foot bring down, the same alternate operation as the [A] setting will occur.
ing			N P	* * *	* * *	8 P		MS	MF	포	26	62	84	귙	9		20	25	99	40	20	09	80	100		:	Σ	c	)		⋖		⊢
Setting	y classic	iispiay	00 70	* * *	* * *	0 0 Cr7		<u>88</u>	<u>u</u>	- C	<u>ب</u>	<u>س</u>	00 D-	-J	0		<u>-</u>	Մ	ب دع	27 C2	(C)	<u></u>	C.3	100		c		<b>l</b>	J	I	מכ	Į	<b></b> -
Function name	) letioid	Digital display	odf.	dd.	oF.	oft.	FUd									,o 4	i								=======================================	i							
	Setting range			$0\sim510$												ı																	
	Unit			msec.	ı	1										X10	msec																
Factory	setting	GMFY	Ą	0	ΡŪ	OF	MF									20									Σ								
Ор	erabil	lity	×	×	×	×	×									×									×								
	ect caumbe		0408	0409	0410	0411	0412									0413									0414								
	ne		Ision ODT.	al DD.	out OF.	on OFL.	FUD.								_	FO.		_		_		_			FU.	_				_		_	
	Function name		Output signal OD compulsion OFF	Delay time of output signal OD	Function selection of output signal OF	Logical conversion function of output signal OF	Presser foot lifter output chopping duty									Presser foot lifter FU full	wave output time								Presser foot lifter FU	moniemaly mode							
Mod	de na	me												ပ	mode		→) ·	<b>+</b> [∪															

			Or	Factory			Function	Setting	рſ	
Function name		irect c	oerabi	setting	Unit	Setting range	:			Specification
			ility	GMFY			Digital display	isplay		
Delay time of output signal <b>C</b> OF	DF.	0415	×	0	msec.	0 ~ 510	dF.	* *	* * *	In each output signal OF the delay time to when each output is started can be set. Each delay time can be set in 2msec intervals.
Function selection of output csignal O1	9.	0416	×	OT1	,			* * *	* * *	The output functions of each output signal O1 can be selected from 58 types of functions. (*3)
Logical conversion function of output signal O1	01L.	0417	×	P			ه ال.	0 0 C/L	N P	The output logic of each output signal O1 is reversed.
Chopping operation of output csignal O1	010.	0418	×	OF			ه ال	C/L	N P	Each output is output with full wave immediately after output starts, and then is reduced to half-wave output for each output signal O1. (Chopping control) The full wave output time can be set with the full wave time [PO] function for each output.
Output signal O1 compulsion C	O1T.	0419	×	OF		,	o 1f.	0 0 Cr	N P	In each output signal O1, each output is forcibly turned OFF after the time set in the OFF timer is passed. The OFF timer set time can be set with each output's forced OFF timer [OTT] function.
Delay time of output signal <b>C</b>	Д.	0420	×	0	msec.	$0\sim510$	ص ت-	* * *	* * *	In each output signal O1 the delay time to when each output is started can be set. Each delay time can be set in 2msec intervals.
Function selection of output csignal O2	05.	0421	×	NCL			ەر ك	* * *	* * *	The output functions of each output signal O2 can be selected from 58 types of functions. (*3)
Logical conversion function of output signal O2	02L.	0422	×	OF		,	<i>هکا</i> .	0 0 Cr7	N P	The output logic of each output signal O2 is reversed.
Chopping operation of output <b>C</b> signal O2	02C.	0423	×	OF			.926.	90 90	ON OF	Each output is output with full wave immediately after output starts, and then is reduced to half-wave output for each output signal O2. (Chopping control) The full wave output time can be set with the full wave time [PO] function for each output.
Output signal O2 compulsion C	O2T.	0424	×	OF		,	o2f.	0 0 Crr	N P	In each output signal O2, each output is forcibly turned OFF after the time set in the OFF timer is passed. The OFF timer set time can be set with each output's forced OFF timer [OTT] function.
Delay time of output signal <b>C</b> O2	D2.	0425	×	0	msec.	$0 \sim 510$	42.	* * *	* * *	In each output signal O2 the delay time to when each output is started can be set. Each delay time can be set in 2msec intervals.
Function selection of output csignal O3	03.	0426	×	TF	-	•	.E o	**	* * *	The output functions of each output signal O3 can be selected from 58 types of functions. (*3)
Logical conversion function of output signal O3	03L.	0427	×	OF	-	ı	.760	jo jo	ON OF	The output logic of each output signal O3 is reversed.
Chopping operation of output csignal O3	03C.	0428	×	OF			о3Е.	00 P	OP OF	Each output is output with full wave immediately after output starts, and then is reduced to half-wave output for each output signal O3. (Chopping control) The full wave output time can be set with the full wave time [PO] function for each output.
Output signal O3 compulsion C	03Т.	0429	×	OF	-	,	o3f.	jo o	OP OF	In each output signal O3, each output is forcibly turned OFF after the time set in the OFF timer is passed. The OFF timer set time can be set with each output's forced OFF timer [OTT] function.
Delay time of output signal <b>E</b> O3	D3.	0430	×	0	msec.	$0\sim510$	d3.	* *	* * *	In each output signal O3 the delay time to when each output is started can be set. Each delay time can be set in 2msec intervals.
Function selection of output csignal O4	04.	0431	×	NPW		•	ە بر	* * *	* * *	The output functions of each output signal O4 can be selected from 58 types of functions. (*3)
Logical conversion function cof output signal O4	04L.	0432	×	OF	-	•	۰ ۲۲.	ол о Я	ON OF	The output logic of each output signal O4 is reversed.

	Setting	Specification Digital display		ON set in the OFF timer is passed. The OFF time can be set with each output's forced OFF timer [OTT] function.	*** In each output signal O4 the delay time to when each output is started can be set. Each delay time can be set in 2msec intervals.	*** The output functions of each output signal O5 can be selected from 58 types of functions. (*3)	ON The output logic of each output signal O5 is reversed.	N P	*** In each output signal O5 the delay time to when each output is started can be set. Each delay time can be set in 2msec intervals.	*** The output functions of each output signal O6 can be selected from 58 types of functions. (*3)	OP The output logic of each output signal O6 is reversed.	NO O	ON set in the OFF timer is passed. The OFF time can be set with each output's forced OFF timer [OTT] function.	*** In each output signal O6 the delay time to when each output is started can be set. Each delay time can be set in 2msec intervals.	*** The output functions of each output signal O7 can be selected from 58 types of functions. (*3)	OP The output logic of each output signal O7 is reversed.	OP	OP set in the OFF timer is passed. The OFF time can be set with each output's forced OFF timer [OTT] function.	*** In each output signal O7 the delay time to when each output is started can be set. Each delay time can be set in 2msec intervals.	*** The output functions of each output signal OM can be selected from 58 types of functions. (*3)	ON The output logic of each output signal OM is reversed.
Function	name	Diaita		o 4f.	7,0		056.	o5f.	50	o£.	.990	o6£.	o6f.	дę.	0.7	۰،1۲۰	۰٦٤.	.JL 0	d7.	off	Ĉ
		Setting range		,	$0 \sim 510$		1	,	$0\sim510$		,		,	$0\sim510$		,		,	$0\sim510$	,	
		Unit		,	msec.	,	,	1	msec.		1	ı	,	msec.		1	ı	1	msec.		
	Factory	setting	GMFY	OF	0	DNW	OF	OF	0	NO	OF	OF	OF	0	NO	OF	OF	OF	0	NO	Ľ.
	Оре	erabili	ity	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×
		ect ca umber		0433	0434	0435	0436	0437	0438	0439	0440	0441	0442	0443	0444	0445	0446	0447	0448	0449	0420
		90		sion 04T.	al D4.	out 05.	on O5L.	sion <b>05T.</b>	al D5.	out 06.	oo uc	tput O6C.	sion O6T.	al D6.	out 07.	on <b>07L.</b>	tput 07C.	sion <b>07T.</b>	al D7.	out OM.	oML.
		Function name		Output signal O4 compulsion OFF	Delay time of output signal O4	Function selection of output signal O5	Logical conversion function of output signal O5	Output signal O5 compulsion OFF	Delay time of output signal O5	Function selection of output signal O6	Logical conversion function of output signal O6	Chopping operation of output signal O6	Output signal O6 compulsion OFF	Delay time of output signal O6	Function selection of output signal O7	Logical conversion function of output signal O7	Chopping operation of output signal O7	Output signal O7 compulsion OFF	Delay time of output signal O7	Function selection of output signal OM	Logical conversion function
	Mod	de nar	ne							ပ	epou □	+ 0 ,									

	Specification	In each output signal OM, each output is forcibly turned OFF after the time set in the OFF timer is passed. The OFF timer set time can be set with each output's forced OFF timer IOTTI function.	In each output signal OM the delay time to when each output is started can be set. Each delay time can be set in 2msec intervals.	The output functions of each output signal ON can be selected from 58 types of functions. (*3)	The output logic of each output signal ON is reversed.	In each output signal ON, each output is forcibly turned OFF after the time set in the OFF timer is passed. The OFF timer set time can be set with each output's forced OFF timer [OTT] function.	In each output signal ON the delay time to when each output is started can be set. Each delay time can be set in 2msec intervals.	The output functions of each output signal OO can be selected from 58 types of functions. (*3)	The output logic of each output signal OO is reversed.	In each output signal OO, each output is forcibly turned OFF after the time set in the OFF timer is passed. The OFF timer set time can be set with each output's forced OFF timer [OTT] function.	In each output signal OO the delay time to when each output is started can be set. Each delay time can be set in 2msec intervals.	The output functions of each output signal OP can be selected from 58 types of functions. (*3)	The output logic of each output signal OP is reversed.	In each output signal OP, each output is forcibly turned OFF after the time set in the OFF timer is passed. The OFF timer set time can be set with each output's forced OFF timer [OTT] function.	In each output signal OP the delay time to when each output is started can be set. Each delay time can be set in 2msec intervals.	In each output signal OP the delay time to when each output is started can be set. Each delay time can be set in 2msec intervals. (*3)	The output logic of each output signal OQ is reversed.	In each output signal OQ, each output is forcibly turned OFF after the time set in the OFF timer is passed. The OFF timer set time can be set with each output's forced OFF timer [OTT] function.
ing		N P	* *	* * *	S P	NO PO	* * *	* * *	S P	NO PO	* *	* *	NO PO	OP.	* * *	* * *	NO P	OP
Setting	lisplay	0 0 Crt	* * *	* * *	ס ס כיר	30 0	* * *	* * *	0 0 Cr7	<i>ქ</i> 0	* * *	**	jo	jo Jo	* * *	* *	30 0	00 P
Function name	Digital display	ofif.	df.	Ċ	onł.	oof.	ďn.	Ö	00.	.Joo	do.	.до	۰۶۲.	.Jdo	dP.	90	.760	o9f.
	Setting range	ı	$0\sim510$			ı	0 ~ 510		ı	ı	$0\sim510$	•	ı	ı	0 ~ 510			
	Unit	,	msec.	ı	1		msec.		1		msec.		ı		msec.	1	1	
Factory	setting	OF	0	Q.	90	OF	0	9	OF	OF	0	NO	OF	OF	0	ON	OF	OF
Оре	erability	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×	×
	ect call umber	0451	0452	0453	0454	0455	0456	0457	0458	0459	0460	0461	0462	0463	0464	0465	0466	0467
		OMT.	DM.	O.	ONL.	ONT.	DN.	.00	00F.	. 100	DO.	OP.	OPL.	OPT.	DP.	OQ.	OQL.	OQT.
	Function name	Output signal OM compulsion OFF	Delay time of output signal OM	Function selection of output signal ON	Logical conversion function of output signal ON	Output signal ON compulsion OFF	Delay time of output signal ON	Function selection of output signal OO	Logical conversion function of output signal OO	Output signal OO compulsion OFF	Delay time of output signal OO	Function selection of output signal OP	Logical conversion function of output signal OP	Output signal OP compulsion OFF	Delay time of output signal OP	Function selection of output signal OQ	Logical conversion function of output signal OQ	Output signal OQ compulsion OFF
Mod	de name		•		•		ပ	mode	→)+[		•						-	

М				С	, a 0 to 0			Function	Setting	βι	
ode	:			per	setting	:	Settina	lalle			:
e name	Function name		ct call mber	rability	GMFY	Unit	range	Digital display	isplay		Specification
	Delay time of output signal OQ	DQ.	0468	×	0	msec.	$0\sim510$	96	* * *	* *	In each output signal OQ the delay time to when each output is started can be set. Each delay time can be set in 2msec intervals.
	Function selection of output signal OR	O.R.	0469	×	ON			٥.٢.	**	* *	The output functions of each output signal OR can be selected from 58 types of functions. (*3)
	Logical conversion function of output signal OR	O.RL.	0470	×	OF	-	ı	or t.	90 90	ON OF	The output logic of each output signal OR is reversed.
	Output signal OR compulsion OFF	O.RT.	0471	×	PO		,	or f.	0 0 Cr7	NO PO	In each output signal OR, each output is forcibly turned OFF after the time set in the OFF timer is passed. The OFF timer set time can be set with each output's forced OFF timer [OTT] function.
	Delay time of output signal OR	DR.	0472	×	0	msec.	$0 \sim 510$	dr.	***	* * *	In each output signal OR the delay time to when each output is started can be set. Each delay time can be set in 2msec intervals.
	Full wave output time for each output	PO.	0473	0	20	X10		ρ <sub>o.</sub>			The full wave output time of each output signal OA~OD, O1~O7 can be set.
(						msec			S C C	20	Set to [20] : 200ms
သ mode									ე <u>ა</u>	25	Set to [25] : 250ms
-										30	Set to [30] : 300ms
)+(									<u> </u>	40	Set to [40] : 400ms
<u></u> 0									50	50	Set to [50] : 500ms
									90	09	Set to [60] : 600ms
									80	80	Set to [80] : 800ms
									100	100	Set to [100] : 1000ms
	Output chopping duty except of FU output	POD.	0474	0	MF			Pod			Setting output chopping duty, except FU output
									75	MS	Set to [MS] : 2ms ON/OFF 50% duty
									n.	MF	Set to [MF] : 4ms ON/OFF 50% duty
									r x	豆	Set to [HI] : 4ms ON, 2ms OFF, 66% duty
									ر.	PO	Set to [LO] : 2ms ON, 4ms OFF 33% duty
	Forced OFF timer setting function for each output	отт.	0475	0	12	sec	$1\sim 24$	off.	**	*	The timer that forcibly turns off output signals OA to OD, O1 to O7 and OM to OR can be set.
	FUM operation mode timer setting function	FCT.	0476	0	12	sec	$1\sim 99$	F[r.	*	*	The timer from the time when the presser foot lifter output is turned ON to the time when it is turned OFF. (When FUM operation mode FU [C] or [T] is set can be set.)

б	Specification		O4 O (Option A connector) O4 O (Option A connector) O4:UPW(Needle UP position output)		03	*** Input function selection of the [A1] of the logic [AND] module.	ON [A1] logic of the [AND] module is set to opposite.	ON [A1] of the [AND] module is set to alternative.	*** Output function selection of the [N1] of the logic [AND] module.	ON [N1] logic of the [AND] module is set to opposite.	*** Output function selection of the [N2] of the logic [AND] module.	ON [N2] logic of the [AND] module is set to opposite.	*** Input function selection of the [A2] of the logic [AND] module.	ON [A2] logic of the [AND] module is set to opposite.
Setting	splay			O 40	Ó 90	**	0 0 C/J	20 20	**	0 0 Cri	* * *	0 0 C/T	* * *	90 95
Function	Digital display		or) output)	or) out)		7 80	A 11.	B 18.	: -:-:	٥ الـ	ئ	<i>م</i> کار.	<i>B</i> ∂.	AZL.
	Setting range		(Presser foot lifter connector) OF:FU(Presser foot lifter output)	(Sewing machine connector) OA:T(Thread trimmer output) OB:W(Wiper output) OC:B(Backstitch output) OD:L(Thread release output)			ı	ı		ı		ı	•	
	Unit	e] nization]	(Presser fc OF:FU(Pre	(Sewing machine or OA:T(Thread trimm OB:W(Wiper output OC:B(Backstitch ou OD:L(Thread releas			1	ı	1	1	1	ı	ı	1
Factory	setting	il on C mod	(- @ @ @)	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	ignal.	9	OF	ЭO	ON.	OF	ON.	OF	ON	OF
	erability	for signe	<u></u>	0000	d output s	×	×	×	×	×	×	×	×	×
	rect call umber	It function			on t solenoic	0477	0478	0479	0480	0481	0482	0483	0484	0485
	ō	of input/outpur mposition figu		5008	Caution 6,07] are not s at connector.	put A1.	A1L.	A1A.	Ž.	N1L.	N2.	N2L.	put A2.	A2L.
	Function name	(*3)  *Refer to [25.Table of input/output function for signal on C mode]  *Refer to [26.The composition figure of input and output customization]			Caution Output [O4,O5,O6,O7] are not solenoid output signal Output O5 is not at connector.	Logic [AND] module A1 input function selection	Logic [AND] module A1 setting of Hi /Low logic	Logic [AND] module A1 Alternate	Logic [AND] module N1 output function selection	Logic [AND] module N1 setting of Hi /Low logic	Logic [AND] module N1 output function selection	Logic [AND] module N2 setting of Hi /Low logic	Logic [AND] module A2 input function selection	Logic [AND] module A2 setting of Hi /Low logic
Мо	de name			O mode	+ 0									

			Оре	Factory			Function	Setting	бı	
Function name		ect c	erabil	setting	Unit	Setting range	ار اندار			Specification
			lity	GMFY			Digital display	ılspidy		
Logic [AND] module A2 Alternate	A2A.	0486	×	Ą	1		<i>R</i>	0 0 C/7	NO P	[A2] of the [AND] module is set to alternative.
Logic [AND] module N3 output function selection	N3.	0487	×	9	ı	1	ς Πή	* * *	* * *	Output function selection of the [N3] of the logic [AND] module.
Logic [AND] module N3 setting of Hi /Low logic	N3L.	0488	×	PO	1	ı	n3ł.	ס ס גיז	NO P	[N3] logic of the [AND] module is set to opposite.
Logic [AND] module N4 output function selection	N4.	0489	×	9	ı		کر د	* *	* *	Output function selection of the [N4] of the logic [AND] module.
	N4L.	0490	×	PO	1		 	0 0 C/J	NO P	[N4] logic of the [AND] module is set to opposite.
Logic [AND] module A3 input function selection	A3.	0491	×	9	1			* * *	* * *	Input function selection of the [A3] of the logic [AND] module.
Logic [AND] module A3 setting of Hi /Low logic	A3L.	0492	×	PO	1		<b>₽</b> 3€.	0 0 C/J	NO P	[A3] logic of the [AND] module is set to opposite.
Logic [AND] module A3 Alternate	A3A.	0493	×	OF		ı	<i>R</i> 38.	30 00	ON OF	[A3] of the [AND] module is set to alternative.
Logic [AND] module N5 output function selection	N5.	0494	×	ON.	1	ı	.5.	***	* *	Output function selection of the [N5] of the logic [AND] module.
	N5L.	0495	×	OF	,	ı	.55.	30	ON OF	[N5] logic of the [AND] module is set to opposite.
Logic [AND] module N6 output function selection	Ne.	0496	×	ON		ı	ъδ.	***	**	Output function selection of the [N6] of the logic [AND] module.
Logic [AND] module N6 setting of Hi /Low logic	N6L.	0497	×	OF	-	ı	.794	30	ON OF	[N6] logic of the [AND] module is set to opposite.
Logic [OR] module input function selection	OR.	0498	×	ON		•	or.	**	* *	Input function selection of the [OR] of the logic [OR] module.
Logic [OR] module setting of Hi /Low logic	ORL.	0499	×	OF	-	1	ort.	30	ON OF	[OR] logic of the [OR] module is set to opposite.
	ORA.	0200	×	OF	1	•	or R	30 95	ON OF	[OR] of the [OR] module is set to alternative.
Logic [OR] module R1 output function selection	R1.	0501	×	ON		•	ון נ	**	* *	Output function selection of the [R1] of the logic [OR] module.
	R1L.	0502	×	OF	1	•	r 11.	30 30	ON OF	[R1] logic of the [AND] module is set to opposite.
Logic [OR] module R2 output function selection	R2.	0503	×	ON		•	٦.	**	* *	Output function selection of the [R2] of the logic [OR] module.
Logic [OR] module R2 setting of Hi /Low logic	R2L.	0504	×	OF	1	•	r 2l.	30 30	ON OF	[R2] logic of the [AND] module is set to opposite.
Variable speed command for digital input	CSP.	0505	×	OF	,	1	[5P.	0 م	ON OF	Set variable speed command for digital input. (IOC, IOD, IOE, IOF) High speed is set to [H] on program mode "P". (CSP=ON, CSG=OFF)

		1																											
		IOF) High 2,1,0) = (I6,	Speed	(rpm)		VCZ= [Small]	,	_																		<b>→</b>		VC2=	[Large]
		Set variable speed command for digital input. (IOC, IOD, IOE, IOF) High speed is set to [H] on program mode "P" To use gray code. (3,2,1,0) = (I7, I2, I1). (CSP=ON, CSG=ON)	Decimal	number	-	(	7	3	4	-	2	(	œ.	7	-	∞		6	5	2	7	12	71	_		က	7	<u>†</u>	15
	Specification	al input. (IO "P" To use ç	(c)	201	OF	~ <b>&amp;</b>	1	8 <del>-</del>	OF	0	OF	े ठ	-	NO	-	OF	o (	<u></u> ე	So	7	8 -	OF	0	QF	0	5 -	NO	+	0F
	Spec	nand for digit gram mode G=ON)	(Gray code		OF	OF	0	NO -	NO	7	NO F	NO	+	OF	0	OF	0 6		OF	0	ON 1	NO	1	NO.	1.00	S +	OF	0	0F
		speed comm to [H] on pro SP=ON, CS(	CSG setting (Gray code)	IOE IOE	OF	- P	0	OF 0	OF	0	NO -	NO.	-	NO	+	<u>z</u> ,	- 1	§ -	NO	+	8 -	NO.	+	Р	0 0	<u></u> ე	OF	0	0
		Set variable sipeed is set to 7, 12, 11). (CS	ö	IOF	OF	OF	0	0F 0	OF	0	OF	OF	0	OF	0	OF	0	<del>-</del>	NO	1	NO -	. NO	1	8,	- 120	S -	NO	-	ON T
Вu		ON OF		201	OF	NO	1		NO	1	OF	NO		OF	0	NO.	- 0	<u></u> о	NO	1	OF 0	NO	1	P.	0	N -	OF	0	0N +
Setting	isplay	0 0 بار	CSP setting	dol	OF	O P	0	8 <del>-</del>	80	7	OF	P	0	રુ	+	ફ.	- 10	<u></u> ე	OF	0	§ -	S	-	OF.	0 6	<u></u> ე	, NO	T	NO T
Function	Digital display	C 5 G.	CSP (	IOE IOE	OF	OF	0	0F	OF	0	8 -	. NO	-	80	T	8 .	- 10	<u></u> 5 0	OF	0	OF 0	OF	0	ફ.	1	S +	NO	T	NO -
	Setting range			IOF	О.	占	0	OF 0	OF	0	P C	占	0	吊	0	ᆼ,	0	<del>5</del> -	NO	7	<u> </u>	. NO	1	8,	1.00	3-	. No	-	NO -
	Unit		Hexadeci	numbaer	0	,	1	7	ĸ	Ò	4	L	ç,	ď	ò	7		∞	đ	90	∢	α	۵	O		۵	ш	L	ш
Factory	Setting	R		4				- p			ode	Э. Э.																	
Оре	erability	×		4 7 7	of the l	٠		nmand			l of O m	Eand																	
	ect call	0506			ut VC2			eed cor	nn.		of IVC2	10p, 10	ignal.																
nu	Function name	Variable speed command for <b>CSG.</b> 05 digital input	Code table of speed command input	Note 1:	the variable speed command voltage input VC2 of the No.	4 più oi trie option b cominector is divided	Note 2.	This function is a function to input the speed command by the code in a right table.	It is necessary to input the S1 signal to run.		Note 3: Please set the operation mode function of	to [VS] to run only in a virtual input IOC, IOD, IOE and IOF.	It is possible to begin to run without S1 s																
Mod	de name													S	2	)	+[	ပ်											

	Specification		Backstitch output B will turn ON even while thread release output L is ON.	Virtual outputs OT1 will be turned OFF forcibly after the OFF timer set time has passed. The OFF timer set time can be set with the virtual output OFF timer setting function [T17].	The timer time for forcibly turning OFF virtual outputs OT1 can be set.	Virtual outputs OT2 will be turned OFF forcibly after the OFF timer set time has passed.  The OFF timer set time can be set with the virtual output OFF timer setting function [T2T].	The timer time for forcibly turning OFF virtual outputs OT2 can be set.	Virtual outputs OT3 will be turned OFF forcibly after the OFF timer set time has passed.  The OFF timer set time can be set with the virtual output OFF timer setting function [T3T].		The delay time (ON delay) to when the virtual output OT1 is started can be set.	The delay time (OFF delay) to when the virtual output OT1 is OFF can be set.	The delay time (ON delay) to when the virtual output OT2 is started can be set.	The delay time (OFF delay) to when the virtual output OT2 is OFF can be set.	The delay time (ON delay) to when the virtual output OT3 is started can be set.	The delay time (OFF delay) to when the virtual output OT3 is OFF can be set.	Feed pulse [CP] is invalid. When feed pulse will be used, set this function to "OF". This signal output is from the same pin of "O6".	Setting the number of pulse [CP]. After changing this number, turns on power switch again
Setting			NO O	NO NO	*	ON	*	NO OF	*	*	*	*	*	*	*	ON	*
	- i	Digital display	0 0	0 0 Cr7	*	3°	*	3°	*	*	*	*	*	*	*	0 70	*
Function	Ċ	Digital	 	7 IČ.	f 1f.	rec.	FZF.	ſ3Ľ	f 3f.	  	d 12.	d2 i.	422.	d3 !	432.	CPE.	ſΡ.
	Setting range	)			66 ~ 0		66 ~ 0		66 ~ 0	66 ~ 0	66 ~ 0	66 ~ 0	66 ~ 0	66 ~ 0	66 ~ 0	-	1 ~ 99
	Unit				X10 msec		X10 msec	1	X10 msec	X10 msec	X10 msec	X10 msec	X10 msec	X10 msec	X10 msec	-	
Factory	setting	GMFY	OF	OF	66	OF	66	JO	66	0	0	0	0	0	0	NO	32
Ор	erabi	ility	0	0	0	0	0	0	0	×	×	×	×	×	×	0	0
	ect c		0507	0508	0200	0510	0511	0512	0513	0514	0515	0516	0517	0518	0519	0520	0521
			LB.	T1C.	T1T.	T2C.	T2T.	T3C.	Т3Т.	D11.	D12.	D21.	D22.	D31.	D32.	CPK.	CP.
	Function name		Thread release + backstitch output	Virtual output OT1 forced OFF function	Forced OFF timer setting function for virtual output OT1	Virtual output OT2 forced OFF function	Forced OFF timer setting function for virtual output OT2	Virtual output OT3 forced OFF function	Forced OFF timer setting function for virtual output OT3	ON delay time setting function for virtual output OT1	OFF delay time setting function for virtual output OT1	ON delay time setting function for virtual output OT2	OFF delay time setting function for virtual output OT2	ON delay time setting function for virtual output OT3	OFF delay time setting function for virtual output OT3	Feed pulse output (CP) cancel function	Setting CP pulse amount
Mod	de na	ame								C	<b>→</b> +[	÷ O 1					

Мо				Ор	Factory			Function	Setting	бı	
de na	Function name		rect c umbe	erabi	setting	Unit	Setting range		<u>.</u>		Specification
me				lity	GMFY			Digital display	ııspiay		
	Prohibited angle of output CP pulse	CPC.	0522	0	OF	-	ı	CPC.	30 30	ON OF	The prohibited angle section of pulse generated can be set from UP position. The start prohibited angle can be set with [TS] (G mode). The end prohibited angle can be set with [TE] (G mode).
	Panel switch operation prohibit	PSW.	0523	0	OF	-	ı	P58.	<i>ქ</i> 0	ON OF	Panel switch operation ( [M], [A,1-2], [B,SL], [C,<==], [D,==>] key operations) during the normal mode, tacking mode and pattern mode will not be possible. However, changeover into each mode will be possible.
	04, 05 output cancel during back tack term	CKB.	0524	0	OF	-	ı	Ctb.	30 30	ON OF	Output signal O4 and O5 are prohibited during back tack term.
	CP output cancel during back tack term	CPB.	0525	0	OF		ı	<i>[Pb.</i>	30 00	ON OF	Output signal "CP" is prohibited during back tack term.
	Speed setting for the [SPC] output	ن	0526	×	1000	rpm	6668 ~ 0	ij	* * * *	* * *	SPC output is turned ON when reached setting speed [C].
	Speed setting for the [SPD] output	D.	0527	×	2000	rpm	$6668 \sim 0$	סי	* * * *	* * *	SPD output is turned ON when reached setting speed [D].
O	Speed setting for the [SPE] output	ш	0528	×	3000	rpm	$6668 \sim 0$	Ę	***	* * *	SPE output is turned ON when reached setting speed [E].
mode	F key function on control	CNF.	0529	0	SE		,	EnF.			Selection F key function
<b>→</b>	panel					_			dΩ	UP	Display Up counter amount
<b>+</b> ⊕									ď	N	Display Down counter amount
									35	SE	Display stitch amount of sensor
									Sp	SP	Display routine speed of sewing machine
	Variable speed pedal changeover	PDS.	0230	0	OF	-	,	P45.	30 20	ON OF	When the changeable velocity pedal etc, are uesd by the standing sewing machine making, it sets it.
	Speed insrtuction VC2 cancellation	V2C	0531	×	OF		ı	u2E.	ქo	ON OF	Speed instruction VC2 is canceled.

		ō	ס	D 0						_	- o					⊆	⊑
		By finely adjusting the backstitch solenoid operation timing of start tacking from reverse to forward, the no. of stitches can be compensated. The relation of the setting value and no. of stitch compensation is as shown below.	By finely adjusting the backstitch solenoid operation timing of end tacking from reverse to forward, the no. of stitches can be compensated. The relation of the setting value and no. of stitch compensation is as shown below.	By finely adjusting the backstitch solenoid operation timing of end tacking from forward to reverse, the no. of stitches can be compensated. The relation of the setting value and no. of stitch compensation is as shown below.		2	-2/4	ட	+1 <sup>2</sup> / <sub>4</sub>		15 stitches are added to the set No. of start and end tacking stitches. For example, if the set No. of start tacking stitches is 4 stitches, the actual No. of start tacking stitches will be 19 stitches (4 + 15).	[BTO] setting stitches are added to the set No. of start and end tacking stitches. For example, if the set No. of start tacking stitches is 4 stitches and [BTO] setting value is 20 stitches, the actual No. of start tacking stitches will be 24 stitches (4 + 20).	stops, end I stop after		signal S5, g speed run	If both the medium speed signal (S5, SPM) and the end tacking speed run signal (S5V) is ON, the speed will be the start tacking speed N.	If both the medium speed signal (S5, SPM) and the end tacking speed run signal (S5V) is ON, the speed will be the end tacking speed V.
		ration timing be comper ompensatior	ration timing be comper	ration timing can be com		3	-3/4	В	+111/4		id end tackir is 4 stitches 15).	of start and sking stitche aal No. of sta	art tacking s machine will		speed run s end tacking an be set.	d the end tac tacking spe	d the end tao acking spee
	Specification	olenoid ope stitches car o. of stitch co	olenoid ope stitches car o. of stitch	colenoid ope of stitches of stitch		4	1-	Ω	+1		o. of start and sing stitches stitches (4 +	o the set No. of start taches, the acture.	ately after st the sewing		nal (medium PM) and the ttion mode c	5, SPM) and be the start	5, SPM) and be the end t
	Spe	backstitch s t, the no. of alue and no	backstitch s the no. of alue and no own below.	backstitch se, the no. alue and no own below.		2	-1 <sup>1</sup> / <sub>4</sub>	ပ	+3/4		to the set No of start tack will be 19 s	are added to if the set No e is 20 stitch hes (4 + 20)	ned immedia ormed, and		n speed sigr Ind signal S speed opera	ed signal (S speed will	ed signal (S speed will
		djusting the se to forward the setting v	By finely adjusting the backstitch solenoid operation timing of end tack from reverse to forward, the no. of stitches can be compensated. The relation of the setting value and no. of stitch compensation is as shown below.	By finely adjusting the backstitch solenoid of from forward to reverse, the no. of stitcherelation of the setting value and no. of stitch compensation is as shown below.	ng value	9	-1 <sup>2</sup> / <sub>4</sub>	В	+ <sup>2</sup> / <sub>4</sub>		15 stitches are added to the set No. of start and el example, if the set No. of start tacking stitches is 4 of start tacking stitches (4 + 15)	[BTO] setting stitches are added to the set No. of start and end tacki stitches. For example, if the set No. of start tacking stitches is 4 stitcl and [BTO] setting value is 20 stitches, the actual No. of start tacking stitches will be 24 stitches (4 + 20).	If full heeling is performed immediately after start tacking stops, end tacking will not be performed, and the sewing machine will stop after thread trimming.		When both the medium speed signal (medium speed run signal S5, medium speed command signal SPM) and the end tacking speed run signal S5V is ON, the speed operation mode can be set.	If both the medium speed signal (S5, SPM) and the end tacking signal (S5V) is ON, the speed will be the start tacking speed N.	medium spe /) is ON, the
		By finely are from revers relation of below.	By finely a from revers relation of compensar	By finely a from forware relation of compensar	ies and settii	7	-13/4	٧	+1/4		15 stitches example, if of start tac	[BTO] setti stitches. Fi and [BTO] stitches wil	If full heeling is patacking will not bath thread trimming.	Not used.	When both medium sp signal S5V	If both the signal (S5/	If both the signal (S5\
ng		*	*	*	ated stitch	8	-5	0	0		OP OF	*	OP OF	ON OF		NO	OF
Setting	isplay	*	*	*	of compens	6	-21/4	-	-1/4		00 0 F	*	9. 9.	30 00		0	95
Function name	Digital display	<i>67 2.</i>	b 7 3.	<del>ن</del> رو	Relation of no. of compensated stitches and setting value	Setting value	Compensated stitches	Setting value	Compensated stitches		bfP.	bſo.	bff.	£54.	5 <i>P</i> n.		
3	Setting range	4 ~ 0	→ O	0		Se	Ō	S	Ö		,	66 ~ 0	ı	-	1		
	Unit	1	1		7	]	BT4	)	<i>i</i>			ı	1	1			
Factory	Setting	0	0	0	End			/ / /	'          		OF	0	N O	OF	OF		
Оре	erability	0	0	0			LT3	<u>}</u>	 		0	0	0	0	0		
	ect call umber	0605	9090	2090			_		 		8090	6090	0610	0611	0612		
		BT2.	ВТ3.	ВТ4.					 		ВТР.	вто.	втт.	CSJ.	SPN.		
	Function name	No. of stitch compensation for start tacking alignment	No. of stitch compensation for end tacking alignment	No. of stitch compensation for end tacking alignment	Start		BT1	> \	 		No. of tacking stitches (+) 15 stitches function	No. of tacking stitches addition stitches function	Full heeling function immediately after start tacking stop	Not used.	The speed operation mode when both the medium speed signal and S5V signal is ON		
Mod	le name									mode	→+(						

	Specification	Determine the type of tacking that can be set with the front and end tacking type ([B], [D] keys) in the tacking setting mode with setting values 1 to 7.	Once tacking (V tacking)	Double tacking (N tacking)	Triple tacking (M tacking)	4 repeat tacking (W tacking)	5 repeat tacking	6 repeat tacking	7 repeat tacking	If the backstitch related inputs are turned ON during preset stitching, the backstitch solenoid will turn ON.	The backstitch solenoid drive timing by the backstitch signal S7 is synchronized with the UP position. (When this function setting is [OF] setting, it will be synchronized with the random position.)	The backstitch solenoid drive timing by the backstitch signal S7 is synchronized with the DOWN position. (When this function setting is [OF] setting, it will be synchronized with the random position.)	When the manual backstitching signal (S7) is OFF setting, the OFF timing of the backstitching output B will be synchronized with the UP position. (When this function setting is [OF] setting, it will be synchronized with the DOWN position.)	The maximum tacking stitches can be set.	The No. of maximum tacking stitches will be 99 stitches. The No. of start and end tacking stitches will be the same stitches, the No. of start and end tacking stitches A and D can be set by the 2 figures of [A] and [B] of the operation panel, and the No. of start and end tacking stitches B and C can be set by the 2 figures of [C] and [D] of the operation panel.	The No. of maximum tacking stitches is 15 stitches.	The No. of end tacking stitches with direct heeling will be the No. of stitches C + 1 stitch when operation mode D1 is set to [D][M] during tacking.	The operation mode for when the thread trimmer cancel signal (TL) is input will be set.	The tacking cancel signal [BTL] operation is set. [ON] The tacking operation is prohibited once after one pushing (OFF-ON-OFF) of the tacking cancel signal [BTL]. [OF] Tacking is prohibited while the tacking cancel signal [BTL] is ON.
Setting			_	7	က	4	2	9	7	N P	N P	S P	ON		N O	占	N P	N P	OF
Set	display			∿	LÜ	<b>)</b> -	S	ω	c-	0 0 C/L	0 0 Crr	0 0 Crr	20 20		c o	0 بار	0 0 Crr	0 0 Crr	0 0 Cr7
Function name	Digital display	<b>6</b> F.R.								5711.	วนร	574	764.	bſπ			b££.	7.5	675.
,	Setting range	1 ~ 1									ı			,			ı	,	
	Unit													1				1	
Factory	setting GMFY	9								OF	OF	OF	OF	OF			OF	OF	NO
Ор	erability	0								0	0	0	0	0			0	0	0
	ect call umber	0613								0614	0615	0616	0617	0618			0619	0620	0621
		BTM.								S7M.	S7U.	S7D.	7BD.	BTN.			BCC.	TLS.	BTS.
	Function name	Set table types of tacking								Input signal S7 operation mode during preset stitching	Manual backstitch ON timing	Manual backstitch ON timing 2	The OFF timing setting of output B when the backstitching signal (S7) is OFF setting.	The maximum tacking stitches (maximum stitches is 99 stitches)			No. of end tacking stitches during direct heeling	Operation mode during thread trimmer cancel signal [TL] setting	Input signal BTL quick pressing operation
Мос	de name											۵	mode → +	<u>+</u>					

Мо				Ор	Factory			Function name	Setting	бı	
de name	Function name	<u> </u>	ect call	erability	setting GMFY	Unit	Setting range	Digital display	lisplay		Specification
	Input signal SB and EB quick B pressing operation	B.S.	0622	0	R	,		λ γ	00 F0	O O P	The start and end tacking cancel signals SE and EB operations are set. [ON] The start tacking operation is prohibited once after one pushing (OFF-ON-OFF) of the start tacking signal SE. (Same for end tacking cancel signal EB.) [OF] The start tacking operation is prohibited while the start tacking cancel signal SE is ON. (Same for end tacking cancel signal EB.)
D mode	Operation when input signal BTL is ON	ВТБ. (	0623	0	OF			b∫d.	0 0 Crr	NO PO	When the tacking is set to OFF, if tacking cancel signal (BTL) turns ON, the tacking will be permitted. (When this function is set to OFF, the tacking will be prohibited.)
→ + <u>+</u>	Operation when input signal SB and EB tacking OFF are B set	BD.	0624	0	OF	ı		<i>bd.</i>	₹°	ON	If the start tacking validity ([A] key) is set to OFF (-) in the tacking setting mode, start tacking can be validated by turning the start tacking cancel signal SE ON. (Same for end tacking cancel signal EB.)
	End tacking cancel mode <b>P</b> with input signal PSU	PNE.	0625	0	-OF	ı		اب ب	00 F0	ON OF	When end tacking is set, if the needle UP position priority stop signal PSU turns ON during operation, the end tacking will not be executed after stopping at the needle UP position. After thread trimming, the presser foot will lift.
	The buzzer of control panel <b>B</b> validity	BZ.	0626	0	N O			-Q	0 0 Crt	N P	The buzzer of control panel will be validated.

									IA.	IB.	IC.	ID.	Ē.	JE.	lG.	Ĥ.	II.	IJ.	天	IL.	ŀ.
	Specification		The last error code is displayed.	The second to last code is displayed.	The third to last code is displayed.	The fourth to last code is displayed.	Display total integration time of power on	Display total integration time of motor run	The input status (ON/OFF) of the input signal	The input status (ON/OFF) of the input signal	The input status (ON/OFF) of the input signal	The input status (ON/OFF) of the input signal	The input status (ON/OFF) of the input signal	The input status (ON/OFF) of the input signal	The input status (ON/OFF) of the input signal	The input status (ON/OFF) of the input signal	The input status (ON/OFF) of the input signal	The input status (ON/OFF) of the input signal	The input status (ON/OFF) of the input signal	The input status (ON/OFF) of the input signal	The input status (ON/OFF) of the input signal
ing			E	E	Ш	E	* * *	* * *	ON OF	ON	ON OF	O P	OP	ON OF	ON OF	OP	ON	ON OF	ON	ON OF	OP OF
Setting	display		3	3	£	£	* * *	* * *	00 90	30 0	30 00	0 0 CW	0 0 C/J	30 00	00 05	30 30	30 00	30 30	30 0	00 90	0 0 CÅ
Function name	Digital display	)	7	5	Ωį	ታ	ρ.	$\mathcal{U}$	<b>'</b> 8'	.þ.	،ڙ	مَ.	نِد	' <del>ل</del> ا	·Ţ'	'ዝ'	71 1	<i>.</i> p.	،ڊ	יך.	jg!
	Setting range		-	-		-	0 ~ 9999	$0 \sim 9999$	-	1	-	1	1	-	-	1	1	-	1	-	
	Unit		ı	1		-	X10 hours	X10 hours	-	,		1			-	,	ı	-	,	-	1
Factory	setting	GMFY	E	E	Е	E	0	0	•			1									•
Ор	erabilit	ty	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	ect ca umber		0020	0701	0702	0703	0704	0705	0706	0707	0708	020	0710	0711	0712	0713	0714	0715	0716	0717	0718
	Function name		Error code (The last error 1.	Error code (The second to 2.	Error code (The third to last 3.	Error code (The fourth to last 4.	Total integration time of <b>P.</b> power on	Total integration time of M. motor run	Input signal IA display	Input signal IB display IB.	Input signal IC display IC.	Input signal ID display ID.	Input signal IE display IE.	Input signal IF display	Input signal IG display IG.	Input signal IH display	Input signal II display	Input signal IJ display	Input signal IK display IK.	Input signal IL display	Input signal IP display IP.
Mod	de nam	ne							L	mode	<b>→</b> + (	<b>←</b> ]+[	Z Z								

	Specification	The output status (ON/OFF) of the output signal O2.	The output status (ON/OFF) of the output signal O3.	The output status (ON/OFF) of the output signal O4.	The output status (ON/OFF) of the output signal O5.	The output status (ON/OFF) of the output signal O6.	The output status (ON/OFF) of the output signal O7.	The output status (ON/OFF) of the output signal OP.	The output status (ON/OFF) of the output signal OQ.	The output status (ON/OFF) of the output signal OR.	The output status (ON/OFF) of the solenoid output OA with the [D, ==>] key ON/OFF is changed. Do not turn the O4 to O7 outputs ON/OFF with the [D, ==>] key.	The output status (ON/OFF) of the solenoid output OB with the [D, ==>] key ON/OFF is changed. Do not turn the O4 to O7 outputs ON/OFF with the [D, ==>] key.	The output status (ON/OFF) of the solenoid output OC with the [D, ==>] key ON/OFF is changed. Do not turn the O4 to O7 outputs ON/OFF with the [D, ==>] key.	The output status (ON/OFF) of the solenoid output OD with the [D, ==>] key ON/OFF is changed. Do not turn the O4 to O7 outputs ON/OFF with the [D, ==>] key.	The output status (ON/OFF) of the solenoid output OF with the [D, ==>] key ON/OFF is changed. Do not turn the O4 to O7 outputs ON/OFF with the [D, ==>] key.	The output status (ON/OFF) of the solenoid output O1 with the [D, ==>] key ON/OFF is changed. Do not turn the O4 to O7 outputs ON/OFF with the [D, ==>] key.	The output status (ON/OFF) of the solenoid output O2 with the [D, ==>] key ON/OFF is changed. Do not turn the O4 to O7 outputs ON/OFF with the [D, ==>] key.	The output status (ON/OFF) of the solenoid output O3 with the [D, ==>] key ON/OFF is changed. Do not turn the O4 to O7 outputs ON/OFF with the [D, ==>] key.
ing		ON OF	ON	NO P	OP	OP	O O P	O O P	O O P	OF	O O P	OP						
Setting	display	0 درم م	90 90	ر 0 0 1	0 C7	0 0 ک	00 20	90 30	00 0 £	0 م کر ه	0 دې	0 0 CY	ر د ه	ر د ه	ر د ه	30 30	30 30	0 ع
Function name	Digital display	o 2 d.	o 3 <i>d</i> .	o Yd.	o 5 <i>d</i> .	o6d.	o 9d.	oPd.	o 9d.	ord.	оВо.	opo.	o Co.	odo.	ofo.	o ło.	020.	o 3o.
	Setting range										-							
	Unit																	
Factory	Setting																	
Оре	erability	0	0	0	0	0	0	0	0	0	×	×	×	×	×	×	×	×
	ect call umber	0743	0744	0745	0746	0747	0748	0749	0220	0751	0752	0753	0754	0755	0756	0757	0758	0759
		02D.	O3D.	04D.	O5D.	О6D.	O7D.	OPD.	OQD.	ORD.	OAO.	OBO.	.000	ODO.	OFO.	010.	020.	030.
	Function name	Output signal O2 display	Output signal O3 display	Output signal O4 display	Output signal O5 display	Output signal O6 display	Output signal O7 display	Output signal OP display	Output signal OQ display	Output signal OR display	Solenoid output of output signal OA	Solenoid output of output signal OB	Solenoid output of output signal OC	Solenoid output of output signal OD	Solenoid output of output signal OF	Solenoid output of output signal O1	Solenoid output of output signal O2	Solenoid output of output signal O3
Mod	le name		_ <del></del>							mode	→)+(•	+ [4]	]			_ <del></del> _		

	Specification		The output status (ON/OFF) of the solenoid output O4 with the [D, ==>] key ON/OFF is changed. Do not turn the O4 to O7 outputs ON/OFF with the [D, ==>] key.	The output status (ON/OFF) of the solenoid output O5 with the [D, ==>] key ON/OFF is changed. Do not turn the O4 to O7 outputs ON/OFF with the [D, ==>] key.	The output status (ON/OFF) of the solenoid output O6 with the [D, ==>] key ON/OFF is changed. Do not turn the O4 to O7 outputs ON/OFF with the [D, ==>] key.	The output status (ON/OFF) of the solenoid output O7 with the [D, ==>] key ON/OFF is changed. Do not turn the O4 to O7 outputs ON/OFF with the [D, ==>] key.	The output status (ON/OFF) of the solenoid output OP with the [D, ==>] key ON/OFF is changed. Do not turn the O4 to O7 outputs ON/OFF with the [D, ==>] key.	The output status (ON/OFF) of the solenoid output OQ with the [D, ==>] key ON/OFF is changed. Do not turn the O4 to O7 outputs ON/OFF with the [D, ==>] key.	The output status (ON/OFF) of the solenoid output OR with the [D, ==>] key ON/OFF is changed. Do not turn the O4 to O7 outputs ON/OFF with the [D, ==>] key.	The motor's rated output value is displayed.	750W.	550W.	The rated input voltage value in the control box is displayed.	Refers to 100V class.	Refers to 200V class.	The control box model name is displayed.	٨	The data version No. (3-digit alpha-numeral) of the EEPROM is displayed.	The version No. (3-digit alpha-numeral) of the software is displayed.	Display previous simple setting selected.
			The output status key ON/OFF is c the [D, ==>] key.	The output status key ON/OFF is class the [D, ==>] key.	The output status key ON/OFF is class of the [D, ==>] key.	The output status key ON/OFF is c the [D, ==>] key.	The output status key ON/OFF is class of the [D, ==>] key.	The output status key ON/OFF is c the [D, ==>] key.	The output status key ON/OFF is controlled the [D, ==>] key.	The mot	Refers to 750W.	Refers to 550W.	The rate	Refers to	Refers to	The con	XC-GMFY	The data	The vers	Display
ing			OP	OP.	N O	N O	N O	N O	OP		75	55		100	200		MFY	* *	* *	* * *
Setting	display		20 30	0 م کر ه	0 0 Crr	0 0 Crr	0 0 Crr	0 0 Crr	0 0 CÅ		75	52		<u> </u>	2002		7 11:11:11:11:11:11:11:11:11:11:11:11:11:	* *	* * *	**
Function name	Digital display		o 4o.	.050	обо.	ه، ٥٠٠	o bo.	.040	0.0	.J <i>B</i>			υĹ.			ЪЪ		·nρ	J.	ال:
3	Setting range									•			•					-	-	-
	Unit									watt			volt			ı				-
Factory	setting	GMFY	1	ı	1	ı	ı	ı	1	* *			* * *					* * *	* * *	-
Оре	erabilit	у	×	×	×	×	×	×	×	0			0			0		0	0	0
	ect cal ımber	II	0920	0761	0762	0763	0764	0765	9920	2920			0768			6920		0770	0771	0772
			040.	050.	.090	.070	OPO.	000.	ORO.	WT.			VL.			TP.		DV.	RV.	T.
	Function name		Output for small signal of output signal O4	Solenoid output of output signal O5	Electromagnetic value output of output signal 06	Electromagnetic value output of output signal O7	LED output for G500 type control panel	LED output for G500 type control panel	LED output for G500 type control panel	Rated output display			Voltage display			Model display		Data version No.	Software version No.	Display previous simple setting selected.
Mod	le nam	ne							mode [	→) -	+(-	+[4	2 -1							

			<u> </u>		l .	1								1			
	Specification		The No. of stitches A (delay during chain-off output ON) for chain-off output operation can be set. When CTR = ON, the No. of stitches for cutter output OFF can be set.	The No. of stitches B (delay during chain-off output OFF) for chain- off output operation can be set. When CTR = ON, the No. of stitches for cutter output ON can be set.	The No. of stitches C (delay during cutter output ON) during cutter output operation can be set.	The No. of stitches to be stitched before the output BT for the in-tacking signal is turned ON after the sensor turns OFF can be set.	The No. of stitches to be stitched before the sewing machine stops after the output BT for the in-tacking signal turns ON can be set.	The No. of stitches to be stitched before the output BT for in-tacking signal is turned OFF after stitching is started can be set.	The delay time for the output SL to turn from OFF to ON can be set in 2msec intervals. The cutter output time setting is also possible.	The delay time for the output SL to turn from ON to OFF can be set in 2msec intervals. The chain-off output mesh judgment time setting is also possible.	The No. of set stitches for the output SL can be selected from HOF set No. of stitches (during ON setting) or SLN set No. of stitches (during OFF setting).	Setting HOF function in G mode.	Setting SLN function in P mode.	The output of SL for thread dislocation prevention starts when the needle lift operation (US, U, UF) is completed.	When the SL output operation mode SLS is ON while the motor is stopped, the output of SL for thread dislocation prevention will start after the thread is trimmed.	If the output SL turns ON during an operation other than tacking, the speed is limited to that set in the medium speed M.	The output SL is ON even when the motor is stopped.
Вu			* *	* *	* *	*	*	* *	* * *	* * *		NO	占	N P	OP OF	ON OF	ON OF
Setting	200	uspiay	*	**	* *	* *	* *	* *	* * *	**		CO	J-0	0 0 Cr7	30 00	og of	00 70
Function name	10:10	Digital display	Co.R.	Cob.	CoC.	11	7.	ıı <b>i</b>	5d.	ה פר	51.H.			5t.t.	56.5.	51.1.	575
:	Setting range		66 ~ 0	66 ~ 0	66 ~ 0	66 ~ 0	66 ~ 0	1 ~ 99	0 ~ 508	0 ~ 508					1	•	
	Unit		stitche s	stitche s	stitche s	stitche s	stitche s	stitche s	msec	msec				1	ı		
Factory	setting	GMFY	0	0	0	0	0	12	0	0	-OF			OF	OF	OF	OF
Оре	erabi	lity	0	0	0	0	0	0	0	0	0			0	0	0	0
	ect c		0800	0801	0802	0803	0804	0805	9080	0807	8080			6080	0810	0811	0812
			COA.	COB.	COC.	×	Υ,	<b>Z</b> .	SD.	ED.	SLH.			SLK.	SLT.	SLL.	SLS.
	Function name		Set No. of stitches A for cutter output (Setting the delay time during chain-off output ON)	Set No. of stitches B for cutter output (Setting the delay time during chain-off output OFF)	Set No. of stitches C for cutter output	No. of stitches for BT output ON after sensor OFF setting	No. of stitches for sewing machine stops after BT output ON setting	No. of stitches for BT output OFF after start of stitching setting	Delay time to when SL output turns from OFF to ON	Delay time to when SL output turns from ON to OFF	No. of set stitches during SL output ON selection mode			SL output start position setting	SL output start position during SLS function ON setting	Speed limit M except tacking and SL on	SL output operation during motor stopping
Mod	de na	me				F mode	<b>→</b> +	+ +	o or								

			ı	ı	1								
Specification	Virtual output OT1 will be set to blower output of cutter function.	Virtual output OT2 can be used as the chain-off output.	Virtual output OT3 can be used as the cutter output.	The mesh judgment control of cutter specification is added to chain-off output. Refer to the section for details on the IO2, IR2 and IS2 signal function.	When the IO3, IR3 and IS3 signals are ON, the output is set to the manual cutter output. Refer to the section for details on the IO3, IR3 and IS3 signal function.	The change status of the IO2, IR2 signal photo switch that outputs the cutter output by the virtual output OT3 can be selected. Refer to the section for details on the IO2, IR2 signal function. The OT3 output time is SD. It is possible to set it by the function.	The cutter output by the OT3 is output at both changes (OFF=>ON) (ON=>OFF) of the IO2, IR2 signal photo switch.	The cutter output by the OT3 is output at only the (ON=>OFF) change of the IO2, IR2 signal photo switch.	When the IO3, IR3 and IS3 signals are ON, the virtual output OT3 is turned ON/OFF per set No. of stitches. (When this is turned ON, the cutter specifications by the sensor will be invalidated.) The set No. of stitches can be set with the cutter specifications No. of stitches A (non-stitching chain ON delay) setting COA function, cutter specifications No. of stitches B (non-stitching chain ON delay) setting COC function. Refer to the section for details on the IO3, IR3 and IS3 signal function.	The output of the automatic cutter output is prohibited while the sensor is ON.	The output of the automatic cutter output is prohibited while the sensor is $OFF$ .	The output of the automatic cutter output is prohibited when the sensor input is ON while the sewing machine is stopped.	Automatic stops and trim setting, after the cutter sensor is turned off and then the number of stitch "C" set by "COC" function $\;$ is run.
	ON OF	ON OF	N P	N P	N P		NO	OF	NO P	N P	ON OF	ON OF	ON PO
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Digital c	o 16.	o2f.	o 3f.	,2 <i>1</i> 1.	[FP.	[ F A.			[fr.	£5£.	CEC.	£ r S.	CBF.
setting range	ı	ı		ı	ı					1	1	1	
Unit	ı	ı									1		
Setting	OF	OF	OF	OF	OF	OF			Ą	OF	OF	OF	OF
erability	0	0	0	0	0	0			0	0	0	0	0
ect call ımber	0813	0814	0815	0816	0817	0818			0819	0820	0821	0822	0823
	01B.	02М.	ОЗМ.	I2M.	СТУ.	CTM.			CTR.	CSC.	CEC.	CTS.	CAT.
Function name	OT1 output blower output setting	OT2 output chain-off output setting	OT3 output cutter output setting	Mesh judgment control with I*2 input	Setting I*3 signal for manual cutter output	Status of cutter output photo switch (1*2) signal according to OT3 output			Turn OT3 output ON/OFF per set No. of stitches when I*3 signal is ON	Automatic cutter output prohibit during sensor ON	Automatic cutter output prohibit during sensor OFF	Cutter output prohibit when sensor is ON while stopped	Automatic thread trim setting after cutter sensor is turned off
						1							
	range Digital display  GMFY GMFY	Function name and the securing and securing	Function name         a sering and part of part blower output         A sering and part blower output         Unit range and part blower output         OR13         O         OF         -         -         o 1b.         o 1b.	Function name         gas a serung a serung and splay         Unit range and splay         Digital display           tput blower output chain-off output chain-off output a sput cutter output         0.813         O OF         -         -         0 Ib.         0 P OF	Function name         a big state and a big st	Function name aggington aggington aggington aggington aggingts aggingted agg	Function name         Example of part of the plant of the plant of the plant control with photo         Example of the plant of the plant control with photo         Example of the plant control with photo         OF         -	Function name         Base of the part of the plane	Function name         a box of bo	Function name again to the follower output of the lower of the lower output of the low	Function name	Function name	Function name

	Specification	The IO1, IR1 and ISI signals and the run output OP1 are set to the cutter BT specifications input/output signals. Refer to the section for details on the IO1, IR1 and IS1 signal function.	Only the preset No. of stitches is stitched after the operation signal (S1) is turned OFF.	The roller lift output ROL will turn ON when presser foot lifting output FU, back tacking output B, virtual output OT2 are ON, and during tacking and thread trimming.	The roller lower No. of stitches is set for the auxiliary feeding rear roller.	Not used.	Not used.	Not used.	Not used.	Not used.	Not used.
Вu		N P	N P	N P	*	NO PO	ON OF	OP OF	*	ON OF	ON OF
Setting	isplay	20 30	ر د د د د د د د	0 ئو	*	30 00	3°	30	*	30	30 30
Function name	Digital display	LFL.	ъIJп	นาว	ין יי	71]	ዖያጋ	.JP3	593	583	.353
3	Setting		1	ı	$66 \sim 0$		•		$66 \sim 0$		1
	Unit			1	stitche s		-		stitche s	-	1
Factory	Setting	PO	OF	OF	0	OF	OF	OF	0	OF	OF
Оре	erability	0	0	0	0						
	ect call umber	0824	0825	0826	0827	0828	0829	0830	0831	0832	0833
		CTL.	NMD.	RLM.	RLN.	ств.	CGD.	EDT.	EDS.	CAS.	ESC.
	Function name	Set I*1 input, OP1 output to cutter BT specifications input/output	Preset stitching operation after operation signal OFF	ROL output mode	No. of stitches setting for auxiliary feeding rear roller	Not used.	Not used.	Not used.	Not used.	Not used.	Not used.
Mod	le name			F mode	<b>→</b>	+ (+	⊢ ∰ I				

Mod				Ор	Factory			Function	Setting	ing	
de name	Function name		ect call umber	erability	setting	Unit	Setting range	Digital	Digital display		Specification
•											The thread trimming timing for each manufacturer's thread trimming
	Thread trimming mode	Ä.	0060	0	M			ر ر	* * *	* * *	sewing machine can be set. Same function as the P mode thread trimming machine can be set. Same function as the P mode thread trimming mode [TR]. When [PRG] is set, the sewing machine operation and thread trimming timing can be set when combined with the functions [TRM], [LTM] or [LLM].
	Motor operation mode during thread trimming	TRM.	0901	0	K			FrA			The motor operation mode during thread trimming can be set when thread trimming mode TR is set to [PRG].
	)								 	ᆂ	The motor will run for the lockstitch thread trimming sewing machine.
									ب.	퐀	The motor will run for reverse thread trimming.
									ت ص	ΑĀ	Not used.
									-0 -0	ΚB	Not used.
									<u>0</u>	Ы	Not used.
									o C	R	Not used.
											The output timing mode of the thread trimming output (T) can be set when
	į										thread trimming mode TR is set to [PRG]. The output timing of the thread
ტ	Thread trimming output (T)	LTM.	0902	0	T		,	C:			trimming output [T] can be set. (Lock stitch setting) It becomes effective
mode	output mode			ı				: :			when the thread trimming mode [1 K] sets [PKG]. Keter to "[15] 1. I hread
Ŀ											trimming timing when thread trimming mode TK setting is PKG." for details of output timing.
+ (									 L.	1	Please refer to the LTM setting of string swithing off output T which has
<u></u>											Deen described to the technical milotination.
+									<u>ر</u>	T2	Please refer to the LTM setting of string swithing off output T which has been described to the technical information.
ပ် [									ر د	F	Please refer to the LTM setting of string swithing off output T which has
									רו	- 13	been described to the technical information.
									۲- کـ	T4	Please refer to the LTM setting of string swithing off output T which has been described to the technical information.
									-J.) 	¥	Not used.
							_		r- M	TS	Not used.
									<u>-</u>	77	Please refer to the LTM setting of string swithing off output T which has been described to the technical information.
											The output timing mode of the thread release output (L) can be set when
	Thread release output (L)	:		(							release output [L] can be set (Lock stitch setting) It becomes effective
	output mode	LLM.	0903	0	5		1	  			when the thread trimming mode [TR] sets [PRG]. Refer to "[15] 1. Thread
											trimming timing when thread trimming mode TR setting is PRG." for details of output timing.
									 -J	7	Please refer to the LLM setting of string loosening output L which has been described to the technical information
									<u>ر</u>	7	Please refer to the LLM setting of string loosening output L which has
	CONTINUED ON THE								, n	-	Please refer to the LLM setting of string loosening output L which has
	NEXT PAGE								ĹĴ	3	been described to the technical information.

	Specification		Please refer to the LLM setting of string loosening output L which has been described to the technical information.	Not used.	Not used.	Please refer to the LLM setting of string loosening output L which has been described to the technical information.	When the thread trimming mode TR is set to [PRG], the output start angle of the thread trimming output (T) can be set. Set according to the thread trimming output (T) timing chart.	When the thread trimming mode TR is set to [PRG], the output end angle of the thread trimming output (T) can be set. Set according to the thread trimming output (T) timing chart.	When the thread trimming mode TR is set to [PRG], the output start angle of the thread release output (L) can be set. Set according to the thread release output (L) timing chart.	When the thread trimming mode TR is set to [PRG], the output end angle of the thread release output (L) can be set. Set according to the thread release output (L) timing chart.	The output start time of the thread trimming output (T) for chain stitch sewing machine can be set. When the thread trimming mode TR is set to [PRG], the output start time of the thread trimming output (T) for lock stitch sewing machine can be set. Set according to the thread trimming output (T) timing chart.	The output time of the thread trimming output (T) for chain stitch sewing machine can be set.  When the thread trimming mode TR is set to [PRG], the output time of the thread trimming output (T) for lock stitch sewing machine can be set. Set according to the thread trimming output (T) timing chart.	The output start time of the thread release output (L) for chain stitch sewing machine can be set. The output start time of the thread release output (L) during chain stitching thread trimming timing A can be set. The chain stitching thread trimming timing B is invalid at this time. When the thread trimming mode TR is set to [PRG], the output start time of the thread release output (L) for lock stitch sewing machine can be set. Set according to the thread release output (L) timing chart.	The output time of the thread release output (L) for chain stitch sewing machine can be set. The output time of the thread release output (L) during chain stitching thread trimming timing A can be set. The chain stitching thread trimming timing B is invalid at this time. Set according to the thread release output (L) timing chart. When the thread trimming mode TR is set to [PRG], the output time of the thread release output (L) for lock stitch sewing machine can be set. Set according to the thread release output (L) timing chart.
ng			14	놀	rs	77	* * *	* * *	* * *	* * *	* * *	* * *	* *	* *
Setting	isplav		<i>ከ</i> 7	-J.J	(J)		* * *	* * * * * * * * * * * * * * * * * * * *	* * * * * * * * * * * * * * * * * * * *	* * * *	***	***	**	**
Function name	Digital display						.5	£E.	57	LE.	<i>!</i>	ſ2.	7 7	1.2.
	Setting range						098 ~ 0	098 ~ 0	098 ~ 0	098 ~ 0	866 ~ 0	866 ~ 0	866 ~ 0	866 ~ 0
	Unit	, -			degree	degree	degree	degree	msec	msec	msec	msec		
Factory	setting	GMFY					0	06	0	06	20	06	150	70
Оре	erabili	ity					0	0	0	0	0	0	0	0
	ect ca umber						0904	9060	9060	2060	8060	6060	0910	0911
							75.	Ē.	LS.	Ë	Т1.	T2.	7.	12
	Function name		CONTINUED FROM PREVIOUS PAGE				Thread trimming output start angle	Thread trimming output angle	Thread release output start angle	Thread release output angle	Thread trimming output start time	Thread trimming output time	Thread release output start time	Thread release output time
Mod	de nar	ne							Ö	mode →	)+(+  + <sup>f</sup> <sub>0</sub>			

	Specification		The output start time of the thread release output (L) during chain stitching thread trimming timing B can be set. The chain stitching thread trimming timing A is invalid at this time. The output start time of the output (TF) can be set. Set according to teach output's timing chart.	The output time of the thread release output (L) during chain stitching thread trimming timing B can be set. The chain stitching thread trimming timing A is invalid at this time. The output time of the output (TF) can be set. Set according to teach output's timing chart.	The time to when the sewing machine begins condensed stiching after the condensed stiching(CH) turn ON during start/end condensed stiching can be set. However, during the end condensed stiching in the chain stiching thread trimming timing B, this time [R3] will be the time for end condensed stiching after the thread release output (L) turns OFF. (If end condensed stiching is not set, the time will be that for the needle to rise from the DOWN to UP position after the thread release output (L) is turned OFF.)	When the thread trimming mode TR is set to [PRG], the output start time of the wiper output (W) can be set. Set according to the wiper output (W) timing chart.	When the thread trimming mode TR is set to [PRG], the output time of the wiper output (W) can be set. Set according to the wiper output (W) timing chart.	The output timing mode of the wiper output (W) can be set. The timing that the wiper output W is turned OFF can be set with the thread trimming signal S2. Refer to "[15] 2. Wiper output timing." for details on setting the OFF timing.	If the S2 signal turns OFF within the wiper output W set time, the W output will turn OFF after the set time has passed. If the S2 signal turns OFF after the wiper output W set time has passed, the W output will turn OFF after the set time has passed.	If the S2 signal turns OFF within the wiper output W set time, the W output will turn OFF after the set time has passed. If the S2 signal turns OFF after the wiper output W set time has passed, the W output will turn OFF when the S2 signal turns OFF.	If the S2 signal turns OFF within the wiper output W set time, the W output will turn OFF when the S2 signal turns OFF. If the S2 signal turns OFF after the wiper output W set time passes, the W output will turn OFF after the set time has passed.	This setting is valid when the reverse run needle setting after thread trimming RU is ON. When the reverse run needle lifting is completed after the thread is trimmed, the W output will turn ON. If the S2 signal turns OFF within the wiper output W set time, the W output will turn OFF after the set time has passed. If the S2 signal turns OFF after the wiper output W set time has passed, the W output will turn OFF after the set time has passed.	Not used.	Not used.
βι			* * *	* * *	* *	* *	* *		≯	OR	AN	RU	공	FW
Setting	<u>.</u>	Ispiay	* * *	**	**	* *	* *		סב	00	Яn	ה	X)	FB
Function		Digital display	 L	ئ	μ	 20	82.	BAG						
	Setting range		0 ~ 508	0 ~ 508	0 ~ 508	866 ~ 0	666 ~ 0	1						
	Unit		msec	msec	msec	msec	X10 msec	,						
Factory	setting	GMFY	40	99	50	10	8	<b>%</b>						
Ор	erabi	lity	0	0	0	0	0	0						
	ect c umbe		0912	0913	0914	0915	0916	0917						
			73	R2.	R3.	W1.	W2.	WMD.						
	Function name		Thread release output start time (Output TF start time)	Thread release output time (TF output time)	Condensed stiching start time (Stop time before thread trimming)	Wiper output start time	Wiper output time	Wiper output operation mode						
Mod	de na	me			(	mode	<b>→</b>	+ (+ )+						

	Specification	When the thread trimming mode TR is set to [PRG], the output start time for the presser foot lifting output (FU) is set. Set according to the presser foot lifting output (FU) timing chart.	The time for the motor to start driving after the presser foot output FU is turned OFF when pedal toe down or external run signal (S0, S1) ON during presser foot lifting can be set in 2 millisecond units.	The interlock time that prohibits operation during thread trimming can be set. Manual calculation will be used during the [P] mode thread trimming (TR) timing [PRG], [KA3], [KA4], [KB3], [KB4], so the setting is valid. [KA1], [KA2], [KB1], [KB2] are for automatic calculation and cannot be set	The interlock time during the no thread trimming timing can be set. This is valid when the [P] mode thread trimming timing [NO] or thread trimming release signal (TL) is turned ON.	After the motor stops, it will start rotating after the thread trimming output T turns ON and the delay time has passed. The delay time can be set by the [TD] function.	The motor stop time before thread trimming during lock stitch can be set in 2msec intervals. The output R output time during chain stitch can be set in 2msec. When the chain stitch mode is set, it is possible to set to the delay time of the motor "R3".	Delay time before reverse run (RU operation) after thread trimming is completed can be set with RT when the thread trimming reverse needle lift RU is set to ON.	When reverse needle lift after thread trimming RU is ON and RUS is ON, the delay time before the motor reverse run after thread trimming can be set in 2msec intervals.	Change [RU] function for chain stich type. "OF" is factory setting for lock stich (Reverse run after T) "ON" is for chain stich (Reverse run after T, L and W)	If the pedal is toed down or external output signal (S1) is turned ON during the wiper output time [W2] (after thread trimming interlock time), the wiper output time [W] will turn OFF. The presser foot lifting output (FU) will also turn OFF simultaneously, and the sewing machine will run after the [FD] time. Use this for the air type wiper. This is effective for standing operation (automatic machine operation).	If the sewing machine pulley is rotated by hand and set to 1 position while the sewing machine is stopped before thread trimming, if the needle UP position is 2 position, the needle DOWN position will shift. To return to the original stop position after that, fully heel the pedal, or set the operation mode by turning thread trimming signal (S2) ON. The same operation as then next [S2P] setting value ([NO], [TR], [PS]) is executed. The thread trimming operation is executed according to the thread trimming mode TR setting value ([KA1], [KA2], etc.).		
ling		* *	* *	* *	* *	OP	* *	N P	NO PO	N P	OP		N O	P
Setting	lisplay	* * *	* * *	* * *	* * *	90 90	* * *	0 0 Cr7	30 30	0 0 Cr7	0 0 14		0	96
Function name	Digital display	) J	Ъ3	٠٢.	ال:	5 <i>P J</i>	ŀď.	50-	<i>د ا</i> ر.	ับกา	? SA	527.		
	Setting range	866 ~ 0	866 ~ 0	866 ~ 0	$0 \sim 510$	1	$0\sim 508$	ı	$0\sim 508$	ı		ı		
	Unit	msec	msec	msec	msec	1	msec	1	msec	1	1			
Factory	setting	140	176	140	0	OF	20	OF	92	OF	OF	-Q-		
Оре	erability	0	0	0	0	0	0	0	0	0	0	0		
	ect call umber	0918	0919	0920	0921	0922	0923	0924	0925	0926	0927	0928		
		F.	FD.	ij	Ë	TDS.	TD.	RUS.	RT.	RUM.	WS1.	S2T.		
	Function name	Presser foot lifting output start time	Time to motor drive after presser foot lifter bring down	Interlock time during thread trimming	Interlock time during no thread trimming	Motor rotation after motor stop before thread trimming	Motor stop time during lockstitch and R output time during chain stitch	Delay setting before reverse run during RU setting	Delay time before reverse run during RU setting	Reverse run needle lifting [RU] after output T, L and W	Wiper output OFF trimming with (S1) signal	Operation mode with thread trimming signal to shift the needle stop position and return to the original needle stop position before the thread trimming signal		
Mod	de name						G mode	<b>→</b> +	· (+ [					

Ope Oper	Specification  Setting Comparison Setting Comparison Setting Digital display  A Specification Specification Specification Comparison	The operation mode started with the full pedal heeling or thread trimming signal (S2) ON when rotating the sewing machine pulley, etc., manually, and leaving the UP position when in 1 position, and leaving the DOWN position when in 2 position.	When [KA1] to [KA4] of the thread trimming mode [TR] are set, the thread trimming operation will be performed according to the settings after the needle is lifted. When [KB4] are set, the thread trimming operation will be performed according to the settings after the needle is lowered.	PS The presser foot lifting operation will be executed after the needle is lifted. The thread trimming operation will not be executed.	<b>Λο</b> NO The sewing machine does not rotate or perform thread trimming, and only the presser foot lifting operation is executed.	ON ON - Physical Part of the solenoid output [OT1] manual/automatic output is selected. The solenoid output [OT1] manual/automatic output is selected. The solenoid output [OT1] will be set to manual. The solenoid output [OT1] will be set to automatic. The solenoid input signal IO1 is invalidated.	Oggraph of the stitche control of the second on the solenoid output [OT1] manual/automatic output $^{**}$ This is valid when the solenoid output [OT1] manual/automatic output $^{**}$ signal (S00, S1, SH) is turned ON while the solenoid output [OT1] is ON, the OT1 output will turn OFF after the set No. of stitches.	OB32 O OF Bb. OF The weak brake will turn ON when the wiper output (W) turns ON.	When the thread trimming output T mode LTM for lockstitch is set to [T1],  ON [T2] or [T3], after the motor stops, it will start again after the thread  OF CON Trimming output T turns ON and the delay time has passed. Set time can be set by the [TD] function.	$0934$ O $0$ - $0 \sim 99$ <b><math>[i]</math> **</b> Not used.	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$0936$ O $0$ . $0 \sim 99$ <b>[3</b> ** ** Not used.	$0937$ O $0$ - $0 \sim 998$ <b><math>f</math> 3.</b> *** Not used.	$0938$ O $0$ - $0 \sim 998$ <b><math>f</math> <math>f</math>,</b> *** Not used.	$0939$ O $0$ - $0 \sim 998$ <b><math>f</math> S</b> . *** Not used.	0940 O OF . PEF, OP OF OP OF OF OP	0941 O OF . PgU OF OF OF Not used.	Jan
Dire	ect call																	0000
	-	S2P.				MAN.	HOF. (	WB.	<b>TDT.</b>	<u>م</u>	<b>C2</b> .	<b>C3</b> .	Т3.	<b>T4.</b> (	Т5.	PET. (	<b>P9U.</b> (	9
	Function name	Operation mode with thread trimming signal when shifting the needle stop position before the thread trimming	signal			Solenoid output OT1 manual/automatic change	Setting of no. of stitches during MAN [OFF] setting	Weak brake ON simultaneously with wiper output (W)	Motor rotation operation when LTM function is set to T1, T2 or T3	Not used	Not used	Not used	Not used	Not used	Not used	Not used	Not used	7-12
Mod	le name					G mode	<b>→</b> + (←	+ 0				•						

	Specification		Not used.	Not used.	Not used.	Not used.	Setting A which can be used by step sequence	Setting B which can be used by step sequence	Setting C which can be used by step sequence	Setting D which can be used by step sequence	Setting E which can be used by step sequence	Setting F which can be used by step sequence	Setting G which can be used by step sequence	Setting H which can be used by step sequence
ing			NO PO	OF	* *	OF	NO PO	NO PO	NO PO	NO PO	O O	NO PO	OP	OP
Setting	Velusiv	uspidy	30 30	90 90	**	90 90	0 م 0 ج	30 30	30 00	jo Jo	30 0	jo Jo	30 95	00 F0
Function name	velasio letipia	Digital	РЯЯ	5 <i>F</i> Ł.	<i>t 8</i> :	PEŁ.	ррд	ppb.	PPE.	рbд	эδ	ррξ	PPG	ррң
	Unit Setting range		ı	1	.98 ~ 98	1	ı	1	ı	1	1	1	1	1
			-	-	-	-		-		-		-	-	-
Factory	setting	GMFY	OF	OF	0	OF	OF	OF	OF	OF	OF	OF	OF	OF
Ор	erabil	ity	0	0	0	0	0	0	0	0	0	0	0	0
Dir nı	ect ca umbe	all r	0943	0944	0945	0946	0947	0948	6760	0960	0951	7960	8360	0954
			PAA.	STL.	L8.	PEK.	PPA.	PPB.	PPC.	PPD.	PPE.	PPF.	PPG.	PPH.
	Function name		Not used	Not used	Not used	Not used	Setting A which can be used by step sequence	Setting B which can be used by step sequence	Setting C which can be used by step sequence	Setting D which can be used by step sequence	Setting E which can be used by step sequence	Setting F which can be used by step sequence	Setting G which can be used by step sequence	Setting H which can be used by step sequence
Mod	de nai	me				Ŋ	mode	<b>→</b> )+(	+ <sup>€</sup> 0					

		1	Г	ı	ı		1	1		Г			
	Specification	The upper limit value of the maximum speed [H] in P mode is set. A value that exceeds the value set in this limiter cannot be set for the maximum speed [H].	The lower limit value of the maximum speed [H] in P mode is set. A value that is lower than the value set in this limiter cannot be set for the maximum speed [H].	The upper limit value of the low speed [L] in P mode is set. A value that exceeds the value set in this limiter cannot be set for the low speed [L].	The lower limit value of the low speed [L] in P mode is set. A value that is lower than the value set in this limiter cannot be set for the low speed [L].	The upper limit value of the thread trimming speed [T] in P mode is set. A value that exceeds the value set in this limiter cannot be set for the thread trimming speed [T].	The lower limit value of the thread trimming speed [T] in P mode is set. A value that is lower than the value set in this limiter cannot be set for the thread trimming speed [T].	The upper limit value of the start/end tacking (condensed stitching) speed in P mode is set. A value that exceeds the value set in this limiter cannot be set for the start/end tacking (condensed stitching) speed.	The lower limit value of the start/end tacking (condensed stitching) speed in P mode is set. A value that is lower than the value set in this limiter cannot be set for the start/end tacking (condensed stitching) speed.	The upper limit value of the medium speed [M] in P mode is set. A value that exceeds the value set in this limiter cannot be set for the medium speed [M].	The lower limit value of the medium speed [M] in P mode is set. A value that is lower than the value set in this limiter cannot be set for the medium speed [M].	The upper limit value of the slow start speed [S] in P mode is set. A value that exceeds the value set in this limiter cannot be set for the slow start speed [S].	The lower limit value of the slow start speed [S] in P mode is set. A value that is lower than the value set in this limiter cannot be set for the slow start speed [S].
ng		*	* *	*	*	*	*	*	* *	* *	* *	*	*
Setting	lisplay	*	* *	* *	*	* *	* *	*	*	* *	* *	*	* *
Function name	Digital display	LHH	LHL.	LLK	111.	LFH	LFL.	LnK	Lnt.	LNH	ר טר.	L5H.	. 51.
	Setting range	66 ~ 0	66 ~ 0	66 ~ 0	66 ~ 0	66 ~ 0	66 ~ 0	$66\sim0$	$66\sim 0$	66 ~ 0	66 ~ 0	66 ~ 0	66 ~ 0
	Unit	X100 rpm	X100 rpm	X100 rpm	X100 rpm	X100 rpm	X100 rpm	X100 rpm	X100 rpm	X100 rpm	X100 rpm	X100 rpm	X100 rpm
Factory	setting GMFY	06	0	5	0	Ŋ	0	30	0	06	0	30	0
Ор	erability	0	0	0	0	0	0	0	0	0	0	0	0
	ect call umber	1000	1001	1002	1003	1004	1005	1006	1007	1008	1009	1010	1011
		ĘĘ.	Ä	LLH.	LLL.	LTH.	LTL.	LNH.	LNL.	LMH.	LML.	LSH.	TSF.
	Function name	Upper limit of maximum speed [H]	Lower limit of maximum speed [H]	Upper limit of low speed [L]	Lower limit of low speed [L]	Upper limit of thread trimming speed [T]	Lower limit of thread trimming speed [T]	Upper limit of start/end tacking (condensed stitching) speed	Lower limit of start/end tacking (condensed stitching) speed	Upper limit of medium speed [M]	Lower limit of medium speed [M]	Upper limit of slow start speed [S]	Lower limit of slow start speed [S]
Mod	de name						H	+(+	+(-)				

	1					1	
	Specification	It is possible to save the present data into the "Simple setting table". When this [SAVE] function is set, the setting data will be saved into the [LOAD1] on the program mode [ 1 ]. It is possible to load the saved data by the selection of [LOAD1] in the program mode [ 1 ].	It is possible to save the present data into the "Simple setting table". When this [SAVE] function is set, the setting data will be saved into the [LOAD2] on the program mode [1]. It is possible to load the saved data by the selection of [LOAD2] in the program mode [1].	[ON] : All data but user 1 and 2 are copied.	[ON] : User 1 data is copied.	[ON] : User 2 data is copied.	SRI, [CU1], and [CU2].  **C-G500 Control panel Current data   CCR] ON / OFF setting (Factory setting: ON)   Description data
ing				ON OF	N P	N O P	ng: ON) Teach User Back Step Ng: ON) User Step Ng: ON) User Step CUZ]=ON User Step Step
Setting	splay			jo čo	0 0 CU	0 0 CUL	etting: O
Function	Digital display	SRuE i	SAu£2.	EEr.	<i>CU</i> 1.	CU2.	[CCR] ON / OFF setting (Factory setting: ON) [CU1] ON / OFF setting (Factory setting: ON) [CU2] ON / OFF setting (Factory setting: ON) [CU2] ON / OFF setting (Factory setting: ON) [CU1] ON / OFF setting (Factory setting: ON) [CU1] ON / OFF setting (Factory setting: ON) [CU2] ON / OFF setting: ON / OFF setting: ON / OFF setting (Factory setting: ON) [CU2] ON / OFF setting: ON / OFF settin
	Setting		1				N / OFF settir N / OFF settir N / OFF settir I / OFF settir I / OFF settir I / OFF settir
	Unit					ı	CR] ON / U2] ON / CZ]
Facto	Settin g GMF Y	1		NO	NO	NO	is [Cu2].
Оре	erability	×	×	0	0	0	U1], and
Dire	ect call ımber						o of [CCR], [CU1], and data data stomize data duence data quence data data quence data LED corres [CCR]=ON
	o.	SAVE1.	SAVE2.	CCR.	CU1.	CU2.	The explanation of [CCR], [CU1], and [CU2].  Current data  Current data  User customize data  Backup data Step sequence data User 1 data Step sequence data User 2 data Step sequence data  User 2 data Step sequence data  CCR]=ON
	Function name	Save function 1 of the setting data	Save function 2 of the setting data	Current data is copied	User 1 data is copied	User 2 data is copied	The e.
Mod	e name						- ₩ + ← + m + + m + m + m + m + m + m + m +

			Factory			Function	Setting	ng	
	rect c	erabi	setting	Unit	Setting range		-		Specification
			GMFY	1	,	Digital display	display		
BSC.	. 1118	0	Ą	'	,	656.	00 F0	ON PO	Prohibit the following key switches on control switch panel. $ \bigcirc \mathbf{N} \\ \\ \mathbf{N} \\ \bigcirc \mathbf{N} \\ \\ \mathbf{N} \\ \bigcirc $
PSW.	. 1119	0	РO		,	PSK.	0 0 Cri	NO PO	Control panel operation ([M], [A], [B], [C], [D] key operations) during the normal mode, tacking mode and pattern mode will not be possible. However, changeover into each mode will be possible.
ВКС.	. 1120	0	OF	-		bt C.	₹°	ON OF	The key switch operation on the control switch panel will be possible before thread trimming.
NSV.	. 1121	0	OF	1	,	5u	ქ° 0°	OP OF	The display when the parameter setting key is pushed can be selected. [ON]: The number set last time is displayed. [OF]: The 0th is displayed.
CMP.	1122	0	NO	1	,	EAP.	0 0 Cr	N P	[ON]:The dot is blinked when differing than the data set with CMS.
CMS.	. 1123	0	BK	1	ı	£ 115.			It compares it with the shipment setting value.
							δt	BK	It compares it with the BACKUP setting value.
							 ຫ	S1	It compares it with the SAVE1 setting value.
							5 <sub>2</sub>	S2	It compares it with the SAVE2 setting value.
PKC.	. 1124	0	OF	-	•	PŁ C.	3°	ON OF	The parameter setup (ABCD) key is invalidated during the normal mode.
N T M	. 1125	0	OF			nf fi.	0 0 Crr	ON OF	Not used
UDC.	. 1126	0	OF			UdC.	0.P.	ON OF	Not used

nur	nur	nur			Ope	Factory		S. Soittie	Function name	Setting	ng _	
	erability ect call	erability ect call	Grability ect call	GMFY		$\supset$	Unit	range	Digital display	display		Specification
Operation during 2 - 1 P21. 1200 O OF position changeover	<b>P21.</b> 1200 O OF	1200 O OF	O OF	OF			_		P2 (	0 5 9	ON	When changeover from the 2 position to the 1 position with the [A] key during the normal mode, the needle will rise to the UP position when not in the UP position, when turned ON.
Sewing machine speed during solenoid input signal IO1 X NO IIO11 setting	<b>101.</b> 1201 X	<b>101.</b> 1201 X	×		O <sub>N</sub>			1	ō 			The speed for when the signal IO1 output to the virtual output 1 can be selected.
										00	ON	The speed designation when the IO1 signal is input is invalidated.
										C	0	The speed will be approximately proportional to the variable speed command VC or VC2 voltage of the lever connector.
										<b>-</b> J	_	The speed will be at the speed set in low speed [L].
										כ	۸	The speed will be at the speed set in condensed stitching speed [V].
										<b>C</b> ::	Σ	The speed will be at the speed set in medium speed [M].
										x	Н	The speed will be at the speed set in high speed [H].
mode										םי	R0	The sewing machine will run at the variable speed command VC or VC2 command of the lever connector. The sewing machine will stop when the IO1 signal turns OFF.
										ار ر	RL	The sewing machine will run at the speed set in low speed [L]. The sewing machine will stop when the IO1 signal turns OFF.
										) L	ΑV	The sewing machine will run at the speed set in condensed stitching speed [V]. The sewing machine will stop when the IO1 signal turns OFF.
======================================										۳	RM	The sewing machine will run at the speed set in medium speed [M]. The sewing machine will stop when the IO1 signal turns OFF.
										χı	RH	The sewing machine will run at the speed set in high speed [H]. The sewing machine will stop when the IO1 signal turns OFF.
Speed specification when COR. 1202 O L COR input is ON	<b>COR.</b> 1202 O	<b>COR.</b> 1202 O	0					1	for.			The sewing machine speed for when the correction stitching signal COR is ON.
										co	0	The speed will be approximately proportional to the variable speed command VC or VC2 voltage of the lever connector.
										-J	_	The speed will be at the speed set in low speed [L].
										2	>	The speed will be at the speed set in condensed stitching speed [V].
										C:	Σ	The speed will be at the speed set in medium speed [M].
										Œ	I	The speed will be at the speed set in high speed [H].

			Оре	Factory		;	Function	Setting	ing	
Function name		ect c	erabi	setting	Unit	Setting range		· · · · · · · · · · · · · · · · · · ·		Specification
			lity	GMFY		,	Digital	Digital display		
Speed specification when RND input is ON	RND.	1203	0	Г	ı	,	r n d.			The sewing machine speed for when the input signal RND is ON.
								a	0	The speed will be approximately proportional to the variable speed command VC or VC2 voltage of the lever connector.
								J	_	The speed will be at the speed set in low speed [L].
								<b>5</b>	>	The speed will be at the speed set in condensed stitching speed [V].
								<b>C</b> :	Σ	The speed will be at the speed set in medium speed [M].
								Н	Н	The speed will be at the speed set in high speed [H].
Setting the thread trimming key of control switch panel (mark of scissors) valid or invalid, when the preset stitching is active.	N J	1204	0	OF	1	·	of t.	0 0 Cu	NO OF	The thread trimming by the control panel scissors switch when preset stitching is ON will be validated (enabled).
Decelerate per step when Continuous is set with control panel XC-G500-Y	CNM.	1205	0	PO	1		[nl]	00 90	N PO	The speed will decelerate at each step when Continuous is set with the control panel XC-G500-Y.
DN signal is valid during the virtual DOWN control	KD2.	1206	0	OF			<i>è</i> ሪ?	0 0 Cr7	NO O	During operation control (virtual DOWN) by only the needle UP position signal UP, the DOWN position signal DN will also be valid. The value set for the reverse run angle K8 from the DOWN position to the UP position in the [B] mode, must be smaller than the angle at which the DN signal turns ON.
Validity of operation delay when IO1 signal is input	IOD.	1207	0	OF	1		od.	0 2 3	NO PO	When the signal IO1 (output to the virtual output OT1) is input, the operation delay [S7B.] is validated. This is valid when the function IO1 is [R0], [RL], [RV], [RM], [RH].
Delay to motor drive after B output ON	S7B.	1208	0	5	X10 msec	$1\sim 99$	576.	**	*	The delay time to motor drive after backstitching output (B) output starts can be set. The factory setting [5] refers to [ $5 \times 10 = 50$ ] msec.
Delay when S2 signal is U or UF	UFD.	1209	0	OF	1		ህF ፊ.	og of	ON OF	The delay time set in the P mode S3D will forcibly be added to the delay time when the A mode S2 signal operation mode S2M is set to U or UF.
Not used	E8R.	1210	0	OF	1		£8r.	o P F	OP OF	Not used.
Not used	MRA.	1211	0	OF	1		Ar R.	og of	ON OF	Not used.
UP position needle lifting at the power is turned ON	PAP.	1212	0	OF	1		PRP.	₫°	NO PO	If the needle UP position is applied at the power is turned ON when the P1P or P2P setting is [ON], the needle will be lifted. (Sewing machine rotates once again.)

	Specification		Stop control when needle UP position is detected.	The stop control of low speed detection control is applied. This is valid when the function NAN in K mode is [ON].	The stop control of high speed positioning is applied.	The sewing machine will always rotate once and then stop after the low speed is detected. This is valid when the function NAN is [ON] and UPS is [ON].	The low speed detection speed can be set.	Deceleration is not started when needle position is detected after the run signal is turned OFF, but starts immediately when the run signal turns Off.	The presser foot lifter can be operated during emergency stop by the emergency stop signal (ES) is turned ON.	The OP output and OP1 output is prohibited when the sewing machine restart. It is reset by the power switch is [ON] again. This is valid when the function PR is [ON] and P1R is [ON].	The thread trimming signal S2 will be valid when the thread trimming safety signal S6 is ON. Note that the motor will not rotate.	When this function setting is [ON], the stopping control when the sewing machine is overrun with the preset stitching will be the No. of stitches priority stop. (The stop position is loose.) When this function setting is [OF], it will be the needle position priority stop. (It may be one rotation.)	The software noise filter for the input port IL (inside control box signal), input port I1 (option B connector No. 6 pin) and input port I2 (option B connector No. 9 pin) is invalidated.	The software noise filters for all input ports are invalidated.	The No. of stitches for removing the noise during sensor input can be set.	The sewing machine will decelerate immediately when the UP position priority stop signal PSU or DOWN position priority stop signal PSD turn ON. Note that during the preset stitching, the stitching will continue at a low speed.	The stitching speed must not be set to the low speed L when tacking or preset stitching is two stitches or less.	This is the stitching speed for the set No. of stitches when the UP position priority stop signal PSU, DOWN position priority stop signal PSD or sensor signal SEN is ON.	The stitching speed of the setting No. of stitches is set to the middle speed M.	The speed when PSU, PSD, SEN signal turn ON is continued.
ing				NO	Ŗ	N O	****	OF OF	OP OF	OP	NO PO	OP PO	OP	OP OF	*	N N	N O P		NO	P
Setting	ion Velocity	lispidy		c o	٦	0 0 Cr7	****	0 7	0 0 CY	0 5 0	00 0 £	0 0 17	0 5 7	0 0 CY	* *	0 0 Crr	30 50		c o	0 Y
Function name	velosio letipiO	Digital	Sdn			UP 2.	ند	nAn.	E5F.	Pr [.	756	Pn.E.	ΠFn.	ρFn	5EF.	P5f.	251.	P55.		
	Setting range		-			ı	$0 \sim 2999$	-	-		ı	1		-	66 ~ 0	1	ı	ı		
	Unit					1	rpm	•	1		ı		1	1	stitche s					
Factory	setting	GMFY	PF			OF	280	OF	OF	OF	OF	OF	OF	OF	0	OF.	OF	OF		
Оре	erabil	ity	0			0	×	0	0	0	0	0	0	0	0	0	0	0		
	ect ca		1222			1223	1224	1225	1226	1227	1228	1229	1230	1231	1232	1233	1234	1235		
			UPS.			UP2.	K.	NAN.	ESF.	PRC.	TS6.	PNC.	MFN.	PFN.	SEF.	PSM.	2ST.	PSS.		
	Function name		UP position detection stop			Stop status after low speed detection	Low speed detection speed	Deceleration mode	Presser foot lifter operation during emergency stop	OP output and OP1 output prohibit at restart	S2 signal validity when S6 signal is ON.	Speed loop stopping control when the machine is overrun with the preset stitching	Input port IL, 11 and 12 software noise filter validity	All input port software noise filter validity	No. of stitches for noise removal during sensor input setting	Deceleration state during PSU, PSD signal ON	Low stitching speed validity when the preset stitching is two stitches	No. of set stitch stitching speed when PSU, PSD, SEN signal is ON		
Mod	de nai	me						۷	mode	<b>→</b> )+(←	+=	* + (U)				•				

	Specification		This is the speed for when the UP position priority stop signal PSU, DOWN position priority stop signal PSD or sensor signal SEN is ON.	ON The speed before the PSU, PSD, SEN signal was turned ON is maintained.	OF The speed is set to the variable speed.	The No. of stitches for removing noise with the No. of stitches of UP position priority stop signal PSU can be set.	The No. of stitches for removing noise with the No. of stitches of DOWN position priority stop signal PSD can be set.	UN prode is set to D, the speed will forcibly be set to the medium speed in the function of the medium speed in the function of the medium speed in the medium speed i	The No. of stitches of zigzag stitching (sway width) can be set. (No. of stitches.)		ON The set angle (reverse run/forward run) signal BCR operation is validated OF only after thread trimming.	This is the actual No. of reverse run needle lifting operation USR up to the set andle.	ON Can be executed any number of times.	OF Can be executed only once.	ON (W) will be output even if the motor is not revolving with full heeling at the needle UP position stop.	ON O1 output is prohibited during tacking and thread trimming.	The operation output OP prohibit/permit changeover is executed when input I1 turns ON during sewing machine operation.	ON OP output is prohibited during sewing machine operation.	OF OP output is permitted during sewing machine operation.	The operation output OP1 prohibit/permit changeover is executed when input I1 turns ON during sewing machine operation.	ON OP1 output is prohibited during sewing machine operation.	OF OP1 output is permitted during sewing machine operation.	ON Turning the backstitch output B OFF at the needle DOWN position during OF	ON The KS3 output and TF output are invalidated when thread trimming
Setting		ay		co	رر			CUL 0 0			رس دس			لار ٥		₹°			oF			0 F		
ion		Digital display		0	0		*		*				1	O				0	0		0	0		0
Function name	ä	<u> </u>	PSŁ.			PUF.	PdF.	רקט.	10		ا با	USn.			-2 r &	br E.	Pr.			P Ir.			fbE.	1 1
	Setting range	1	ı			66 ~ 0	66 ~ 0		~ 0							·				ı				
	Unit					stitche s	stitche s		stitche	s						-	-			-			-	
Factory	setting	GMFY	OF			0	0	OF	0		OF	OF			NO	40	40			OF			OF	ц
Оре	erabi	lity	0			0	0	0	0		0	0			0	0	0			0			0	C
	ect c umbe		1236			1237	1238	1239	1240		1241	1242			1243	1244	1245			1246			1247	1248
			PSK.			PUF.	PDF.	CDR.	ZNC.		BRC.	USN.			2RW.	втс.	PR.			P1R.			TBC.	KTL
	Function name		Speed at PSU, PSD, SEN signal is ON			No. of stitches for removing noise when PSU signal is ON	No. of stitches for removing noise when PSD signal is ON	zigzag during continuous tacking	No. of stitches of zigzag	stitch (sway width) setting	BCR operation after thread trimming	Actual No. of USR			W output mode during S2R=OFF setting	O1 output prohibit during tacking and thread trimming	OP output prohibit/permit changeover with input 11 during operation	-		OP1 output prohibit/permit changeover with input 11 during operation			B output OFF prohibit mode during thread trimming	KS3 output and TF output
Mod	de na	ıme					•	¥	mode	<b>→</b>	)+(-	+	, <u>.</u>	<b>+</b> €										

Mod				Ор	Factory			Function name	Setting	βι	
de name	Function name		ect call umber	erability	setting GMFY	Unit	Setting range	Digital display	display		Specification
	Presser foot operation of F, S2, S3 signal is OFF when FUM function is ON, FU function is M or C.	FLC.	1249	0	OF			FLE			The presser foot operation mode when the presser foot output FU stays ON and the full heeling (presser foot lift signal F, thread trimming signal S2, presser foot lift signal S3) is OFF.
									CO	NO	The FU output turns OFF (lowers) when the full heeling (F, S2, S3 signals) is OFF.
									90	OF	The FU output does not turn OFF when the full heeling (F, S2, S3 signals) is OFF.
	T output, L output protection function	SPT.	1250	0	NO		1	SPf.	0 0 Cr7	ON OF	The thread trimming solenoid T and thread release solenoid L are protected. (Solenoid damage prevention)
	Wiper output W ON simultaneously with presser foot lifting output FU	Ä.	1251	0	OF		,	73. 13.	0 0 Cri	ON OF	The wiper output W will turn ON when the presser foot lifting output FU turns ON.
K mode	Input signal check function when power is turned on	PS1.	1252	0	OF		ı	) 5d			If the input signal is S01, BC, BCR or USR, etc., and is ON when the power is turned ON, the set function will be invalidated. Turn the input signal OFF once and turn ON again, and the set function will be validated.
<b>→</b> + (←									Ç O	NO	When main power is turned ON, the system of control box confirm the "ON" "OFF" condition related run signal, excluding one stitch operation signal. If the run signal is "ON", this run signal has to be turned off once to be run.
+									٥٦	OF	It is not confirmed about the "S01", "BC", "BCR" and "USR", when main power switch is turned ON.
<b>+</b> to	Setting program stitch of the control switch panel	B20.	1253	×	P			62o.			Setting the backstitch (reverse feed) output of control switch panel in each step of program stitching.
	-								0	NO	Backstitch (reverse feed) output of step set to virtual output "OT1" in program stitching.
									40	OF	Backstitch (reverse feed) output of step set to output. "B" in program stitching.
	Setting "OT1" output while "B" output is ON	T0B.	1254	0	P		,	fob.			Setting virtual output "OT1" when the backstitch (reverse feed) output "B" is turned ON.
									כנ	NO	"OT1" output is turned ON when "B" output is turned ON.
									7 7	OF	"OT1" output is not turned ON even if "B" output is turned ON.
	Special specification setting of limit control.	2SL.	1255	0	OF	ı		25t.	0 0 Crt	ON OF	The speed limit which uses special specification of input signal "SPB" and "SPM". [ON]:The speed limit function by an external input signal is valid. [OF]:The speed limit function by an external input signal is invalidated.
	Setting output at FWD input ON	NCK.	1256	0	NO	1	,	n£Ł.			Setting output action when non-stitch feed input "FWD" is turned ON. (Union Special correspondence specification)
									C (	NO	Output "OT3" and "FU" are ON while "FWD" input is ON.
									70	OF	Output "OT3", "FU" and "NCL" are ON while "FWD" input is ON.
	Needle lift function is invalidated, excluding the needle down position.	UDN.	1257	0	OF			Udn.	op oF	ON OF	Needle lift function is prohibited, excluding the needle down position.
	The set value of full speed	FSL.	1258	0	06	%	1 ~ 98	F5t.	**	*	The value of full speed (standard value) can be set by percentage.

	1			I	I						!	!		! !						
Specification	The virtual operation signal S1 is turned ON when the variable speed voltage VC1 and VC2 exceeded the set voltage level.	The voltage level of the variable speed voltage VC1 and VC2 where virtual run signal S1 turns ON.	The voltage level hysteresis width for judging the ON/OFF of the virtual S1 signal when VCS turns ON can be set.	The voltage curve of the variable speed voltage VC1 is reversed.	The VC1 input range is set to 0~5V.	VC1 maximum input voltage is set to 5V	VC1 maximum input voltage is set to 12V	The external analog input VC2 function is set.	Speed command input	The virtual S1 signal turns on with the input voltage, and the sewing machine runs. This also acts as the speed command input.	The VC2 input acts as the variable resistor on the control box panel, and the variable resistor is invalidated.	During operation with the BC and BCR input, the speed set with the program P mode C8 is invalidated, and the speed is controlled with the VC2 input.	The speed control input for reciprocal stroke change.	The value set in the program P mode M is invalidated, and the middle speed is controlled with the VC2 input voltage.	Virtual input IO1 is selected	The external analog input VC2 curve is reversed.	The VC2 input range is set to 0~5V. [ON]VC2 maximum input voltage is set to 5V [OF]VC2 maximum input voltage is set to 12V	The inflection point is set when using the reciprocal stroke change specification speed limiter process (VC2 = LM).	Setting inflection point 1	Setting inflection point 2
	NO FO	*	*	NO PO		NO	OF		ΛC	۸S	VR	BC	M	MD	1	ON OF	ON OF	*	*	*
display	0 0 Cr7	* *	* *	ס ס גיז		00	95		υĹ	20	ر <u>۲</u>	ρſ	<u></u>	Лd	-	jo O	jo	*	*	* *
Digital o	υ[ S.	u£l.	u£d.	u fr.	. 15.			u C								ישפי	520	ነ ገባ	ነፈባ	.5do
Setting range	ı	1 ~ 99	66 ~ 0	1	ı											1	ı	$1\sim99$	$1 \sim 99$	$1\sim 99$
Unit			1	ı												ı	ı	-	-	
setting GMFY	Ą	24	4	OF	OF			۸C								OF	NO	29	40	70
erability	×	×	×	×	×			×								×	×	0	0	0
ect call umber	1400	1401	1402	1403	1404			1405								1406	1407	1408	1409	1410
	vcs.	VCL.	VCD.	V1R.	V15.			VC2.								V2R.	V25.	VL1.	VP1.	VP2.
Function name	Virtual S1 operation with VC levels	Setting of VC1 and VC2 where virtual S1 turns ON	Input voltage hysteresis during virtual S1 signal ON/OFF by VC and VC2 level	VC curve reversal mode	VC input 5V/12V changeover mode			VC2 operation mode								VC2 curve reversal mode	VC2 input 5V/12V changeover mode	Speed limiter curve inflection point 1 percentage	Speed limiter curve inflection point 1 point	Speed limiter curve inflection point 2 point
	Virtual S1 levels	Setting of where vir	Input volduring vilduring	VC curv	VC inpu mode			VC2 op								VC2 cui	VC2 inp change	Speed II	Speed limite point	Speed limite point 2 point
	setting Unit Setting Onit range Digital display	setting Unit range Digital display  CS. 1400 X OF - OF	be setting by the setting of the se	vC vcs. 1400 $\times$ OF	e         aging a big setting and a big plants and a big plants and a big plants are a big plants and a big plants and a big plants are a big plants and a big plants and a big plants are a big p	vC         vCs.         1400         X         OF         -         -         L         CS         ON         ON           vCL.         1401         X         24         -         -         -         L         CS         OP         ON           vCD.         1402         X         4         -         0 ~ 99         uCd.         **         **           ver         v18.         1404         X         OF         -         -         u ir.         OR         OR	e         aging a base of time and a	e digital display   Compared by the compared	vC         vCS.         1400         X         OF         -         -         L         CS.         1400         X         OF         -         -         L         CS.         OP         OP         OP         OP         OP         -         -         UCS.         OP         OP         OP         OP         -         -         OP         OP         OP         -         -         OP         OP <td>VC         VCB.         1402         X         24         -         L         C         ON         ON           VCD.         1402         X         OF         -         -         -         UC         **         **           VCD.         1402         X         4         -         0 ≈ 99         UC         **         **           VNR.         1404         X         OF         -         -         UC         **         **           VCD.         1405         X         OF         -         -         UC         **         **           VCD.         1405         X         OF         -         -         UC         **         **           VCD.         1405         X         OF         -         -         UC         OF         <td< td=""><td>vC         vcs.         1400         x         OF         .         .         LCS.         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LCS.         OF         .</td><td>vC vcs. 1400 × OF · · · · vCs. 1400 × OF · · · · · vCs. 1400 × OF · · · · · · vCs. 1400 × OF · · · · · · · vCs. 1400 × OF · · · · · · · · · · · · · · · · · ·</td><td>VC VCS. 1400 X OF</td><td>VC         VCS.         1400         X         OF         COF         COF</td><td>VC         VCS.         1400         X         OF         C         ON         ON</td><td>VC         VCS.         1400         X         OF         .         .         L         Setting           VC         VCS.         1400         X         OF         .</td></td<> <td>VC VCS. 1400 X OF</td> <td>  Setting   Setting   Digital display   Setting   Digital display   Setting   Digital display   Setting   Digital display   Setting   Se</td> <td>  Setting   Setting   Digital display   Setting   Digital display   Setting   Digital display   Setting   Digital display   Setting   On with VC   VCS.   1400   X   24   .</td> <td>  Continue</td>	vC         vcs.         1400         x         OF         .         .         LCS.         OF         .	vC vcs. 1400 × OF · · · · vCs. 1400 × OF · · · · · vCs. 1400 × OF · · · · · · vCs. 1400 × OF · · · · · · · vCs. 1400 × OF · · · · · · · · · · · · · · · · · ·	VC VCS. 1400 X OF	VC         VCS.         1400         X         OF         COF         COF	VC         VCS.         1400         X         OF         C         ON         ON	VC         VCS.         1400         X         OF         .         .         L         Setting           VC         VCS.         1400         X         OF         .	VC VCS. 1400 X OF	Setting   Setting   Digital display   Setting   Digital display   Setting   Digital display   Setting   Digital display   Setting   Se	Setting   Setting   Digital display   Setting   Digital display   Setting   Digital display   Setting   Digital display   Setting   On with VC   VCS.   1400   X   24   .	Continue

1				Ор	Factory			Function	Setting	βι	
_	Function name		rect ca umber	erabili	setting	Unit	Setting range	Digital	Digital display		Specification
_				ty	GMFY			)	-		
I	Operation speed limit specification mode 1	FLM.	1411	0	PO		,	FLA	ה היל	O O P	Operation speed limit is valid when all the below condition are met.  1. "VC2" operation mode" is set to "LM or LIM, medium speed limit mode during OT1 output ON" is set to "ON".  2. "RFU, operation mode with F input during sewing machine operation is set to ""ON".  3. The presser foot lifting output is ON.
	Operation speed limit specification mode 2	2LM.	1412	0	PO		,	2L A.	0 0 Cr	N PO	The speed limit is valid only if the virtual output OT2 is ON when the VC2 operation mode is set to LM or the medium speed limit function LIM is set to ON during OT1 output ON.
	Speed command value correctly by middle speed digital during speed limit process	LMD.	1413	0	OF	-	·	רטפי	30 20	ON	The middle speed during the speed limit process is read into the speed command value (speed high speed signal SPH, speed end tacking signal SPB, speed medium speed signal SPM, high speed run signal S4, end tacking speed run signal S5V, medium speed run signal S5) other than the low speed from an external source by the digit.
_	Speed limit with digital speed setting on operation panel	HMD.	1414	0	OF	ı	ı	нпа	jo jo	ON OF	The speed during stitching other than tacking is limited by the digital speed setting (LED.C and D) on operation panel.
om de →+(	Ignore detector error	E8C.	1415	0	Q F	,	ı	EBC.			The sewing machine detector error E8 will be ignored. If a signal is not received from the sewing machine detector within a set time during operation, the detector error E8 will not be displayed. If a signal is not received from the sewing machine detector within a set time during operation, the detector error E8 will be displayed and the sewing machine will stop.
_									0 C	N P	
_	Thread break sensor valid	TH.	1416	0	OF	,	ı	FR	כע.	S P	The thread break detector is validated.
_	Operation after thread break sensor detection	TST.	1417	0	T.		1	f 5f.			The operation after the thread break is detected (thread break sensor detection) is set.
· <u>-</u>									0	Q.	The operation continues, and the thread break sensor output THO turns ON.
_									L.	TR	The sewing machine stops after the thread trimming, and then the thread break sensor output THO turns ON.
_									5,7	ST	The sewing machine stops normally, and then the thread break sensor output THO turns ON.
_	Speed to ignore thread break sensor	B.	1418	0	009	rpm	$6668 \sim 0$	Ą	* * * *	* * * *	The speed to ignore the thread break sensor can be set.
_	No. of stitches to ignore thread break sensor after starting stitching	THS.	1419	0	2	stitche s	0 ~ F	ſH5.	*	*	Setting the number of stitch that the sensor of thread break detector becomes valid from first stitch.
	Number of stitches for judgment of thread break	THF.	1420	0	0	stitche s	0 ~ F	FHF.	*	*	The No. of stitches to judge the thread break detection when the thread break sensor input continues for a certain number of stitches can be set.
_	Operation mode with F input during sewing machine operation	RFU.	1421	0	PO	ı	·	i) i)	0 0 7	O O F	The presser foot lifting output will turn ON by turning ON the presser foot lifting signal F during sewing machine operation. Note that the presser foot lifting signal S3 is invalid during sewing machine operation.

Мо			Dii n	Ор	Factory			Function	Setting	βι	
de na	Function name		rect c	erabi	setting	Unit	Setting range	i	-		Specification
ıme			all er	lity	GMFY		ı	Digital display	display		
	Output of back tacking output (B) during OT1 output ON inhibited	S7C.	1422	0	OF	1	•	5 <i>1</i> .C.	3°	ON OF	The output of the backstitching output (B) with input S7 is inhibited while the virtual output (OT1) is ON.
	Medium speed (M) limit mode during OT1 output ON	LIM.	1423	0	OF	-	•	า เก	30 30	ON OF	The speed will be limited to that set in medium speed M while virtual output (OT1) is ON.
	Simultaneously ON of OP1 output during OT1 output ON	01P.	1424	0	OF	,	•	o 1P.	3°	ON OF	OP1 output will turn ON simultaneously when virtual output (OT1) is ON.
	Disregard of S3 signal of Lever Unit	LVB.	1425	0	ON	1	•	lub.	30 30	ON OF	When the lever unit run signal S1 is ON, the presser foot lift signal S3 will be ignored even when received.
ø.	1 step heeling setting for the internal lever unit	PD1.	1426	0	OF	,		? Pd	jo	ON OF	The heeling operation of the pedal will be 1 step heeling operation.
mode	Adjustment mode for the internal lever unit	VCSE T.	1427	×	1	1		uESEF.			The neutral of the internal lever unit, toe down, and the heeling position can be adjusted.
→)+( <del>•</del>	Not used.	MTJ.	1428	0	OF	,	•	NF J.	30 30	ON OF	Not used.
- + (-	Not used.	MOA.	1429	0	7	stitche s	$66 \sim 0$	RoB.	*	*	Not used.
+	Not used.	MOB.	1430	0	7	stitche s	$66 \sim 0$	Rob.	*	**	Not used.
<u></u>	Not used.	MOC.	1431	0	7	stitche s	$66 \sim 0$	Rot.	*	*	Not used.
	VC assistance ON/OFF	VCA.	1432	0	OF	1	•	υ[R.	0 5 0	ON OF	The speed curve to the amount of depressing changes depending on the pedal stepping speed.
	Strength of VC assistance	VCP.	1433	0	50	1	$66 \sim 0$	υ[P.	*	**	The amount of the changes by the depressing speed can be set.

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		EPRC s used	
		The EEPROM data is returned to the EEPROM back up state. This is used return the function setting to the factory settings.	
		' '	
Setting		'	
Set	,		
	Digital display		
Function name	igital	€ſ.	
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Mod	de name		

	Specification		This is the virtual output KS1 and KS2 run mode.	The KS1 and KS2 output swill turn ON only during normal operation.	During the one needle stitching, half-stitching (one needle stitching signal S01, needle lift signal U, half-stitching signal UD, backstitching during run signal US, backstitching during run signal UDS, etc.), the outputs KS1 and KS2 will turn ON.	The simple sequence start conditions are set.	The simple sequence will not start.	When the virtual input IO4 is ON.	When the thread trimming is completed.	When run starts.	When the motor starts. (This includes while stopped during the one needle stitching run.)	When stitching starts after thread trimming.	When start tacking is completed. (If the start tacking setting is OFF, the	Normal starting.	The simple sequence forced end conditions are set.	The simple sequence will not forced end.	When the virtual input IO5 is ON level.	When the virtual input IO5 is ON.	When the thread trimming is completed.	When run starts.	When the motor starts. (This includes while stopped during the one needle stitching run.)	When stitching starts after thread trimming.	When start tacking is completed. (If the start tacking setting is OFF, the operation will be identical to [TR].)	Selection stitch amount and time till ON for simple sequence output	"KS1". (Amount have to be set at "K11")	Stitch amount is counted till ON	Time is counted till ON (10 mill-second per each)	Selection stitch amount and time till OFF for simple sequence output "KS1". (Amount have to be set at "K12")	Stitch amount is counted till OFF	Time is counted till OFF (10 mill-second per each)
Setting				NO	PO		9	Z	<b>—</b>	٣	တ	꼰	SB	9		9	2	Z	_	٣	ဟ	꿈	SB			NO	P		NO	OF
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	Function name		KS1, KS2 output run mode			Simple sequence start conditions									Simple sequence forced end conditions									Simple sequence output KS1 output beginning is time or	the number of stitch is selected			Simple sequence output KS1 output is time or the number of stitch is selected		
Mod	de na	me										v.	mode	<b>→</b>	+ (m	<b>1</b> +	- <u></u>													

		e set.					e one		OFF, the	.t.		(6	(C			e one		OFF, the	output			output		
	Specification	The simple sequence output starting point setting [S1S] can be set.	Linked output. (ON edge of the front output)	Virtual input ON point. (KS1:IO6, KS2:IO7, KS3:IO8, KS4:IO9)	When the thread trimming is completed.	When run starts.	When the motor starts. (This includes while stopped during the one needle stitching run.)	When stitching starts after thread trimming.	When start tacking is completed. (If the start tacking setting is OFF, the operation will be identical to [TR].)	The simple sequence output end point setting [S1E] can be set.	Linked output. (Each output starting point)	Virtual input OFF point. (KS1:IO6, KS2:IO7, KS3:IO8, KS4:IO9)	Virtual input ON point. (KS1:IOA, KS2:IOB, KS3:IOC, KS4:IOD)	When the thread trimming is completed.	When run starts.	When the motor starts. (This includes while stopped during the one needle stitching run.)	When stitching starts after thread trimming.	When start tacking is completed. (If the start tacking setting is OFF, the operation will be identical to [TR].)	Selection stitch amount and time till ON for simple sequence output "KS2". (Amount have to be set at "K21")	Stitch amount is counted till ON	Time is counted till ON (10 mill-second per each)	Selection stitch amount and time till OFF for simple sequence output "KS2". (Amount have to be set at "K22")	Stitch amount is counted till OFF	Time is counted till OFF (10 mill-second per each)
ng			KS	Z	⊢	ď	တ	ম	SB		KS	占	Z	⊢	œ	S	TR	SB		NO	OF		NO	占
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Function name							5 ñ									.55			.530					
	Setting range																		1			ı		
	Unit	,																				ı		
Factory	setting GMFY	KS								κS									OF			OF		
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	ect call umber	1505								1506									1507			1508		
		S1S.								S1E.									NS2.			NE2.		
	Function name	Output beginning standard of simple sequence output KS1	-							Output end standard of simple sequence output KS1	-								Simple sequence output KS2 output beginning is time or the number of stitch is selected			Simple sequence output KS2 output is time or the number of stitch is selected		
Mod	de name			_	_	_		_		_	_	_	_	_	_	_	_				_			_

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	Specification		The simple sequence output starting point setting [S2S] can be set.	Linked output. (ON edge of the front output)	Virtual input ON point. (KS1:IO6, KS2:IO7, KS3:IO8, KS4:IO9)	When the thread trimming is completed.	When run starts.	When the motor starts. (This includes while stopped during the one needle stitching run.)	When stitching starts after thread trimming.	When start tacking is completed. (If the start tacking setting is OFF, the operation will be identical to [TR].)	The simple sequence output end point setting [S2E] can be set.	Linked output. (Each output starting point)	Virtual input OFF point. (KS1:IO6, KS2:IO7, KS3:IO8, KS4:IO9)	Virtual input ON point. (KS1:IOA, KS2:IOB, KS3:IOC, KS4:IOD)	When the thread trimming is completed.	When run starts.	When the motor starts. (This includes while stopped during the one needle stitching run.)	When stitching starts after thread trimming.	When start tacking is completed. (If the start tacking setting is OFF, the operation will be identical to [TR].)	Selection stitch amount and time till ON for simple sequence output "KS3". (Amount have to be set at "K31")	Stitch amount is counted till ON	Time is counted till ON (10 mill-second per each)	Selection stitch amount and time till OFF for simple sequence output "KS3". (Amount have to be set at "K32")	Stitch amount is counted till OFF	Time is counted till OFF (10 mill-second per each)
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Function name	<u> </u>							52E.												n£ 3.					
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	Unit		,																	1			1		
Factory	setting	GMFY	KS								χ S									JO.			OF		
Оре	erabilit	у	0								0									0			0		
		I	1509								1510									1511			1512		
			S2S.								S2E.									NS3.			NE3.		
				-							Output end standard of simple sequence output KS2									Simple sequence output KS3 output beginning is time or the number of stitch is selected			Simple sequence output KS3 output is time or the number of stitch is selected		
Mod	de nam	ie										Ø	mode	-	+ (										

	Specification	The simple sequence output starting point setting [S3S] can be set.	Linked output. (ON edge of the front output)	Virtual input ON point. (KS1:106, KS2:107, KS3:108, KS4:109)	When the thread trimming is completed.	When run starts.	When the motor starts. (This includes while stopped during the one needle stitching run.)	When stitching starts after thread trimming.	When start tacking is completed. (If the start tacking setting is OFF, the operation will be identical to [TR].)	The simple sequence output end point setting [S3E] can be set.	Linked output. (Each output starting point)	Virtual input OFF point. (KS1:IO6, KS2:IO7, KS3:IO8, KS4:IO9)	Virtual input ON point. (KS1:IOA, KS2:IOB, KS3:IOC, KS4:IOD)	When the thread trimming is completed.	When run starts.	When the motor starts. (This includes while stopped during the one needle stitching run.)	When stitching starts after thread trimming.	When start tacking is completed. (If the start tacking setting is OFF, the operation will be identical to [TR].)	Selection stitch amount and time till ON for simple sequence output "KS4". (Amount have to be set at "K21")	Stitch amount is counted till ON	Time is counted till ON (10 mill-second per each)	Selection stitch amount and time till OFF for simple sequence output "KS4". (Amount have to be set at "K22")	Stitch amount is counted till OFF	Time is counted till OFF (10 mill-second per each)
		È	KS	S Z	× ⊢	<u>ح</u>	S Z	TR W	SB W	È	KS	OF Vi	≥ Z	<u>&gt;</u> ⊢	ձ	S N	TR	SB W	o <del>I</del>	NO NO	OF Ti	Ω÷	NO NO	OF Ti
Setting																								
	Digital display		~n	Ē	L	L	ഗ	L L_	56		-U	0	ē	L_	L	ഗ	L.	5		C	U O		0	οĘ
Function	Digital								53E.									ب ب						
	Setting range	,								•												1		
	Unit																					1		
Factory	setting	XS								XS S									OF			OF		
Оре	erability	0								0									0			0		
	ect call umber	1513								1514									1515			1516		
		S3S.								S3E.									NS4.			NE4.		
	Function name	Output beginning standard of simple sequence output KS3	-							Output end standard of simple sequence output KS3	-								Simple sequence output KS4 output beginning is time or the number of stitch is selected			Simple sequence output KS4 output is time or the number of stitch is selected		
Mod	de name										ഗ	mode	-	•) +	+ 🖺	- - -								

1	Function name		Direct ca	Operabil	Factory setting	Unit	Setting	Function	Setting	bu l	Specification
				lity	GMFY			Digital	Digital display		
Outpu simple	Output beginning standard of simple sequence output KS4	S4S.	1517	0	KS			545			The simple sequence output starting point setting [S4S] can be set.
•									.U	KS	Linked output. (ON edge of the front output)
									ć	Z	Virtual input ON point. (KS1:106, KS2:107, KS3:108, KS4:109)
									L	L	When the thread trimming is completed.
									L	2	When run starts.
									Un	တ	When the motor starts. (This includes while stopped during the one
									<u>L</u>	TR	When stitching starts after thread trimming.
									56	SB	When start tacking is completed. (If the start tacking setting is OFF, the operation will be identical to [TR].)
Outpu simple	Output end standard of simple sequence output KS4	S4E.	1518	0	KS			34E.			The simple sequence output end point setting [S4E] can be set.
-	-								رب د	KS	Linked output. (Each output starting point)
									الر	PF	Virtual input OFF point. (KS1:106, KS2:107, KS3:108, KS4:109)
									ć	Z	Virtual input ON point. (KS1:IOA, KS2:IOB, KS3:IOC, KS4:IOD)
									<b>L</b>	Τ	When the thread trimming is completed.
									L	~	When run starts.
									ഗ	တ	When the motor starts. (This includes while stopped during the one needle stitching run.)
									L.	TR	When stitching starts after thread trimming.
									56	SB	When start tacking is completed. (If the start tacking setting is OFF, the operation will be identical to [TR].)
KS1 o	KS1 output start [Time]/[No. of Stitches] setting	K11.	1519	0	7	X10 msec stitche	66 ~ 0	 	**	*	The output start time/output start No. of stitches for the simple sequence output KS1 can be set. When using time, the setting value will be $(7) \times 10 = 70$ msec. When using No. of stitches, the setting value will be $(7) \times 1 = 7$
	•					S					stitches.
KS1 c Stitch	KS1 output [Time]/[No. of Stitches] setting	K12.	1520	0	7	X10 msec stitche s	66 ~ 0	<del>د</del> بک	* *	* *	The output time/output start No. of stitches for the simple sequence output KS1 can be set. When using time, the setting value will be $(7) \times 10 = 70$ msec. When using No. of stitches, the setting value will be $(7) \times 1 = 7$ stitches.
KS2 o	KS2 output start [Time]/[No. of Stitches] setting	K21.	1521	0	7	X10 msec stitche	66 ~ 0	£ 2 !	* *	* *	The output start time/output start No. of stitches for the simple sequence output KS2 can be set. When using time, the setting value will be $(7) \times 10 = 70$ msec. When using No. of stitches, the setting value will be $(7) \times 1 = 7$ stitches.
KS2 o Stitche	KS2 output [Time]/[No. of Stitches] setting	K22.	1522	0	2	X10 msec stitche s	66 ~ 0	£ 22.	* *	* *	The output time/output start No. of stitches for the simple sequence output KS2 can be set. When using time, the setting value will be $(7) \times 10 = 70$ msec. When using No. of stitches, the setting value will be $(7) \times 1 = 7$ stitches.
KS3 o	KS3 output start [Time]/[No. of Stitches] setting	K31.	1523	0	7	X10 msec stitche	66 ~ 0	? E 7	*	* *	The output start time/output start No. of stitches for the simple sequence output KS3 can be set. When using time, the setting value will be $(7) \times 10 = 70$ msec. When using No. of stitches, the setting value will be $(7) \times 1 = 7$ stitches
						,					

				Оре	Factory			Function	Setting	ng	
Func	Function name		ect call umber	erability	setting	Unit	Setting range	Digital	Digital display		Specification
KS3 output [Time]/[No. of Stitches] setting	e]/[No. of	K32.	1524	0	2	X10 msec stitche	66 ~ 0	£ 32.	*	* *	The output time/output start No. of stitches for the simple sequence output KS3 can be set. When using time, the setting value will be $(7) \times 10 = 70$ msec. When using No. of stitches, the setting value will be $(7) \times 1 = 7$ stitches.
KS4 output start [Time]/[No. of Stitches] setting	Time]/[No.	K41.	1525	0	2	X10 msec stitche s	66 ~ 0	ب 2- 	*	* *	The output start time/output start No. of stitches for the simple sequence output KS4 can be set. When using time, the setting value will be $(7) \times 10 = 70$ msec. When using No. of stitches, the setting value will be $(7) \times 1 = 7$ stitches.
KS4 output [Time]/[No. of Stitches] setting	ie]/[No. of	K42.	1526	0	2	X10 msec stitche	66 ~ 0	د لارک درک	*	* *	The output time/output start No. of stitches for the simple sequence output KS4 can be set. When using time, the setting value will be $(7) \times 10 = 70$ msec. When using No. of stitches, the setting value will be $(7) \times 1 = 7$ stitches.
KS1 output run mode	mode	K1M.	1527	×	NO	ı	ı	r 17.			This is the output KS1 run mode for when the simple sequence start conditions [SQS] are set to NO.
									0 7	N P	The KS1 output is output each time the start conditions are established.  The KS1 output is output only when the start conditions are established after thread trimming.
Run prohibit during KS1 output ON	ring KS1	K1D.	1528	0	OF.			<del>د</del> نظ	0 C	8 P	Running is prohibited while the output KS1 is ON. (This is valid only when the simple sequence start conditions [SQS] are set to NO.)
K11, K12 time clear during KS1 output ON	slear during	K1C.	1529	0	OF			£ 1C.	00 0 F	OP	The K11 and K12 timers will be cleared and the KS1 output will be turned OFF when the sewing machine stops (motor turns OFF) even when the output KS1 timer is continuing. (This is valid only when the simple sequence start conditions [SQS] are set to NO.)
K21, K22 time clear during KS2 output ON	clear during	K2C.	1530	0	OF		,	ŁZC.	0 0 Crr	N N N	The K21 and K22 timers will be cleared and the KS2 output will be turned OFF when the sewing machine stops (motor turns OFF) even when the output KS2 timer is continuing. (This is valid only when the simple sequence start conditions [SQS] are set to NO.)
K31, K32 time clear during KS3 output ON	clear during	K3C.	1531	0	OF		•	t 3C.	90	OF	The K31 and K32 timers will be cleared and the KS3 output will be turned OFF when the sewing machine stops (motor turns OFF) even when the output KS3 timer is continuing. (This is valid only when the simple sequence start conditions [SQS] are set to NO.)
Increase the number of K11 through K42 by ten	umber of K11 ten	KSL.	1532	0	OF	ı	ı	Ł5ł.	00 0 £	NO PO	Increase the number of K11, K12, K21, K22, K31, K32, K41, K42 by ten. (ex. 10mS =>100mS, note: Stitch number is not changed.)
Sequence output time setting/No. of stitch setting each by ten times setting	rut time titch setting les setting	KL1.	1533	0	OF	ı	,	177	0 0 Crr	N P	Sequence output [KS1] [KS2] [KS3] [KS4] time setting/No. of stitch setting each by ten times. [ON]Time setting/No. of stitch setting by ten times ([K11][K12]x10,) [OF]Time setting/No. of stitch setting
Sequence output time setting/No. of stitch setting each by ten times setting	ut time titch setting es setting	KL2.	1534	0	OF		,	£13.	₹°	NO PO	Sequence output [KS1] [KS2] [KS3] [KS4] time setting/No. of stitch setting each by ten times. [ON]Time setting/No. of stitch setting by ten times ([K21][K22]x10,) [OF]Time setting/No. of stitch setting
Sequence output time setting/No. of stitch setting each by ten times setting	ut time itch setting es setting	KL3.	1535	0	OF	1	•	£13.	90 96	ON OF	Sequence output [KS1] [KS2] [KS3] [KS4] time setting/No. of stitch setting each by ten times. [ON]Time setting/No. of stitch setting by ten times ([K31][K32]x10,) [OF]Time setting/No. of stitch setting
Sequence output time setting/No. of stitch setting each by ten times setting	ut time titch setting es setting	KL4.	1536	0	OF			ት የ ተ	0 ئ	O O P	Sequence output [KS1] [KS2] [KS3] [KS4] time setting/No. of stitch setting each by ten times. [ON]Time setting/No. of stitch setting by ten times [(K41][K42]x10.) [OF]Time setting/No. of stitch setting ([K41][K42])

# 25 Table of input/output function for signal on C mode

	Input signal	Input signal setting table
(The item enclosed with can be used even by "O mode".) <pre><examp< pre=""></examp<></pre>	A. P 5	U
<examp< td=""><td>ole&gt;</td><td></td></examp<>	ole>	

	signal setting table	0	<del>†</del> .	
No.	Setting name	Setti	ng value Digital display	Specification
1	Nothing signal	NO	no	The sewing machine will do nothing even if input NO is turned ON.
2	Low speed run signal	S0	50	If input S0 is turned ON, the sewing machine will run at the speed set low speed L.
3	Variable speed run signal	S1	51	This signal is equivalent to full toe down when using the pedal. It is operated at the speed which was set with the [C] [D] key of control switch panel when the automatic operation AT is ON input S1 at the time of ON.
4	Medium speed run signal	S5	55	If input S5 is turned ON, the sewing machine will run at the speed set medium speed M.
5	High speed run signal	S4	54	If input S4 is turned ON, the sewing machine will run at the speed set maximum speed H.
6	Stop position random run signal	RND	rnd	If input RND is turned ON, the sewing machine will run at the speed s in low speed L, and when stopping the sewing machine will stop at random regardless of the needle position.
7	Correction stitching signal	COR	Cor	If input COR is turned ON, correction stitching will be performed at the speed set in low speed L.
8	Thread trimmer signal	S2	52	This signal is equivalent to full heeling when using the pedal. When is ON and thread trimming or needle UP position stop has been completed, the wiper will operate. After that, the automatic presser for lifting will function while the signal is ON.
9	1 stitch signal	S01	50 1	If input S01 is turned ON, 1 stitch operation will start.
10	Needle lift signal	U	l l	If input U is turned ON, the needle lift operation will start.
11	Half-stitch signal	UD	Ud	If input UD is turned ON, half-stitch operation will start.
12	Constant angle [reverse run/forward run] signal	BC	ЬĈ	The needle is stopped just above the fabric to confirm the fabric puncture position. Each time the signal turns ON, the operation will alternate between forward - reverse - forward run. If the pedal is toed down or the external run signal (S1) turns ON after that, forward run start from that position. The needle position stop angle can be set will needle position stop angle C8 in the [B] mode.
13	Constant angle [reverse run/forward run] signal	BCR	b[r	The needle is stopped just above the fabric to confirm the fabric puncture position. Each time the signal is turned ON, the operation valternate between forward - reverse - forward run. If the pedal is toedown or the external run signal (S1) turns ON after stopping at a external run signal (S1) turns ON after stopping at a forward run position, forward run will start after reverse run. If stopped at a rever run position, the sewing machine will forward run from that position. The needle position stop angle can be set with needle position stop angle C8 in the [P] mode.
14	Constant angle reverse run signal	USR	USr	Reverse run needle lift will be performed to the set angle. The set and can be adjusted from the DOWN position to UP position with reverse run angle K8 in the [P] mode. This is effective for blind stitch sewing machine.
15	Needle lift, presser foot lift signal	UF	UF	If input UF is turned ON, the presser foot will lift after needle lifting.
16	Presser foot lifter signal	S3	53	If input S3 is turned ON after trimming, the presser foot will lift. If input S3 is turned ON before trimming, the presser foot will lift, after delay time. The delay time is set by S3D the [P] mode of the 132 page.
17	Presser foot lifter signal	F	F	If input F is turned ON, the presser foot lifter operation will start.
18	Needle UP position priority stop signal	PSU	P5U	If input PSU is turned ON while the sewing machine is running, the needle will stop at the UP position after swing PSU stitches and thre trimming. The no. of stitches after PSU input is set by PSU the [P] mode of 130 page.

<sup>2.</sup> The setting name will display in the ascending order with each press of the [C] key.

Ī			Settir	ng value	
	No.	Setting name		Digital	Specification
		3		display	·
	19	Needle DOWN position priority stop signal	PSD	PSd	If input PSD is turned ON while the sewing machine is running, the needle will stop at the DOWN position after swing PSD stitches. The no. of stitches after PSD input is set by PSU the [P] mode of 130 page.
_	20	Emergency stop signal	ES	£5	If input ES is turned ON while the sewing machine is running, all running states will be canceled, and the sewing machine will stop with the brakes.
	21	One shot signal	SH	SH	If input SH is turned ON, one shot operation will start. The operation mode set in [P] mode SHM function will be entered.
Noted	22	Reverse run signal	CW	[8	If input CW is turned ON while running with pedal toe down or external run signal, reverse run will be enabled while the signal is ON.
Note1	23	Thread trimmer protection signal	S6	56	If input S6 is turned ON while the sewing machine is running, the sewing machine will stop. If input S6 is turned ON during thread trimming, the operation will be completed, and operation will not be possible until input S6 is turned OFF.
	24	Thread trimmer cancel signal	TL	ΓL	If pedal full heeling or thread trimmer signal S2 is turned ON while input TL is ON, the thread will not be trimmed. After the thread trimmer interlock time passes, the presser foot lifting operation will start. When TLS of [D] mode is ON, and TL signal is turned ON a little time, next thread trimming is prohibited only once.
	25	Low speed signal	SPL	SPL	If input SPL is turned ON while the sewing machine is running, the sewing machine will run at the speed set in low speed setting L while the signal is ON.
	26	Medium speed signal	SPM	SPN	If input SPM is turned ON while the sewing machine is running, the sewing machine will run at the speed set in medium speed setting M while the signal is ON.
	27	End tacking speed signal	SPB	SPb	If input SPB is turned ON while the sewing machine is running, the sewing machine will run at the speed set in end tacking speed V while the signal is ON.
	28	High speed signal	SPH	SPH	If input SPH is turned ON while the sewing machine is running, the sewing machine will run at the speed set in high speed setting H while the signal is ON.
	29	Variable speed signal	SPV	5Քս	If input SPV is turned ON while the sewing machine is running, the sewing machine will run at a speed proportional to the variable speed voltage VC while the signal is ON.
	30	Tacking cancel signal	BTL	PLF	If input BTL is turned ON, start and end tacking will be prohibited while the signal is ON. When BTS of [D] mode is ON, and BTL signal is turned ON a little time, next tacking is prohibited only once.
	31	Start tacking cancel signal	SB	56	If input SB is turned ON, start tacking will be prohibited while the signal is ON. When BS of [D] mode is ON, and SB signal is turned ON a little time, next start tacking is prohibited only once.
$\uparrow$	32	End tacking cancel signal	EB	٤6	If input EB is turned ON, end tacking will be prohibited while the signal is ON. When BS of [D] mode is ON, and EB signal is turned ON a little time, next end tacking is prohibited only once.
	33	Backstitching during run signal	S7	57	If input S7 is turned ON while the sewing machine is running, backstitching (reverse feed) will start. Nothing will happen if input S7 is turned ON while the sewing machine is stopped.
	34	Backstitching during run signal	UDS	Ud5	If input UDS is turned ON while the sewing machine is running, backstitching (reverse feed) will start. Half-stitch operation will start if input UDS is turned ON while the sewing machine is stopped.
Note2	35	Backstitching during run signal	US	U5	If input US is turned ON while the sewing machine is running, backstitching (reverse feed) will start. Needle lift operation will start if input US is turned ON while the sewing machine is stopped.
	36	Backstitching signal [when running when stopped]	BSL	65L	If input BSL is turned ON when the sewing machine is running or stopped, backstitching (reverse feed) will start.
	37	Backstitching signal when running	UCR	UEr	If input UCR is turned ON while the sewing machine is running, backstitching (reverse feed) will start. 1 stitch operation will start if input UCR is turned ON while the sewing machine is stopped.

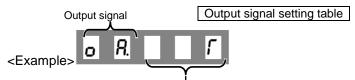
<sup>2.</sup> The setting name will display in the ascending order with each press of the [C] key.

			Setti	ng value	
	No.	Setting name		Digital	Specification
	38	Backstitching signal when running	UBR	übr	If input UBR is turned ON while the sewing machine is running, backstitching (reverse feed) will start. 1 stitch operation with backstitching (reverse feed) will start if input UBR is turned ON while the sewing machine is stopped.
	39	Thread trimmer output confirmation signal	TON	Fon	The thread trimmer output T can be turned ON or OFF only when the sewing machine is stopped. (Thread trimmer solenoid confirmation signal)
	40	Needle cooler output during rotation forced [OFF] signal	NCL	n[L	If input NCL is turned ON, the needle cooler output NCL during sewing machine rotation will forcibly be turned OFF.
	41	1 position priority signal	P12	b 15	1 position will be set forcibly.
	42	Weak brake [ON] signal	BK	<b>6</b> E	If input BK is turned ON, the weak brake will turn ON. Use this with the BK of the [D] mode set to [OF].
Note1	43	Sensor input signal	SEN	5En	This is the cloth edge sensor input.
	44	Wiper output cancel signal	WL	RL	If input WL is turned ON, the wiper output W will not be output.
	45	Slow start signal	SL	5Ł	If the SL signal is ON, the slow start operation will be valid. Use this with the normal mode [B,SL] key set to [OF].
	46	Preset stitching forced [ON] signal	N	n	If input N is turned ON, preset stitching will start forcibly from that point.
$\downarrow$	47	Continuous tack stitching forced [ON] signal	СВТ	ЕЫГ	If input CBT is turned ON, continuous backstitching will start forcibly from that point.
·	48	Non-stitching feed input	FWD	FR9	If input FWD is turned ON, output OT3, output NCL and output FU will be turned ON forcibly. Output ROL and output PUL will be turned OFF forcibly.
	49	Up counter clear signal	CCU	EEU	If input CCU is turned ON, it clears an up counter in [0].
	50	Down counter clear signal	CCD	[[d	If input CCD is turned ON, it clears an down counter in [the setting value].
	51	Signal output to virtual output 1 during operation	IR1	ir l	If input IR1 is turned ON, output OT1 turns ON only when the sewing machine is running.
	52	Signal output to virtual output 2 during operation	IR2	الد ح	If input IR2 is turned ON, output OT2 turns ON only when the sewing machine is running.
	53	Signal output to virtual output 3 during operation	IR3	1. 3	If input IR3 is turned ON, output OT3 turns ON only when the sewing machine is running.
	54	Signal output to virtual output 1 when stopped	IS1	ı5 I	If input IR1 is turned ON, output OT1 turns ON only when the sewing machine is stopped.
<b>↑</b>	55	Signal output to virtual output 2 when stopped	IS2	,52	If input IR2 is turned ON, output OT2 turns ON only when the sewing machine is stopped.
	56	Signal output to virtual output 3 when stopped	IS3	·53	If input IR3 is turned ON, output OT3 turns ON only when the sewing machine is stopped.
	57	Signal output to virtual output 1	IO1	101	If input IO1 is turned ON, output OT1 will always be turned ON.
Note2	58	Signal output to virtual output 2	IO2	105	If input IO2 is turned ON, output OT2 will always be turned ON.
	59	Signal output to virtual output 3	IO3	103	If input IO3 is turned ON, output OT3 will always be turned ON.
	60	Signal output to virtual output 4	IO4	104	If input IO4 is turned ON, output OT4 will always be turned ON.
	61	Signal output to virtual output 5	IO5	105	If input IO5 is turned ON, output OT5 will always be turned ON.

<sup>2.</sup> The setting name will display in the ascending order with each press of the [C] key.

			Settin	ng value	
	No.	Setting name		Digital	Specification
		Ü		display	Specification
	62	Signal output to virtual output 6	IO6	,o5	If input IO6 is turned ON, output OT6 will always be turned ON.
Note1	63	Signal output to virtual output 7	107	٦٥،	If input IO7 is turned ON, output OT7 will always be turned ON.
	64	Signal output to virtual output 8	IO8	.08	If input IO8 is turned ON, output OT8 will always be turned ON.
	65	Signal output to virtual output 9	IO9	.09	If input IO9 is turned ON, output OT9 will always be turned ON.
	66	Signal output to virtual output A	IOA	ıoR	If input IOA is turned ON, output OTA will always be turned ON.
\	67	Signal output to virtual output B	IOB	ob	If input IOB is turned ON, output OTB will always be turned ON.
	68	Signal output to virtual output C	IOC	,o[	If input IOC is turned ON, output OTC will always be turned ON.
	69	Signal output to virtual output D	IOD	,0ರ	If input IOD is turned ON, output OTD will always be turned ON.
	70	Signal output to virtual output E	IOE	·oΕ	If input IOE is turned ON, output OTE will always be turned ON.
	71	Signal output to virtual output F	IOF	ıoF	If input IOF is turned ON, output OTF will always be turned ON.
	72	Signal output to virtual output G	IOG	ناه،	If input IOG is turned ON, output OTG will always be turned ON.
	73	End tacking speed run signal	S5V	550	If input S5V is turned ON, the sewing machine will run at the speed set in end tacking speed V.
	74	Thread break detector input signal	THI	ΓH.	It is possible to use as the input signal of thread break detector.
	75	Sensor stop input signal 1	PS1	P5 !	If input PS1 is turned ON while the sewing machine is running, the needle will stop after swing set stitches. The operation mode at stopping is set by PS1 in the P mode. The no. of stitches after PS1 input is set by [1.] in the P mode.
$\uparrow$	76	Sensor stop input signal 2	PS2	P52	If input PS2 is turned ON while the sewing machine is running, the needle will stop after swing set stitches. The operation mode at stopping is set by PS2 in the P mode. The no. of stitches after PS2 input is set by [2.] in the P mode.
	77	Thread trimmer and tacking cancel signal	TLB	LLP	If input TLB is turned ON, end tacking and thread trimming will be prohibited
	78	Variable speed run signal set to medium speed setting	SVM	5 <sub>0</sub> N	The sewing machine can be operated at the variable speed set to medium speed M when this signal SVM is turned ON and during ON while machine operates.
Note2	79	Needle down signal	D	ರ	When needle down signal D is turned ON, needle down operation will start.
140162	80	Thread trimmer signal after reverse needle lift	URT	Urſ	Not used.

<sup>2.</sup> The setting name will display in the ascending order with each press of the [C] key.



	) utnu	t signal setting table					
	Juipu	t signal setting table	Cotti	ng value			
	No.	Setting name	Setti	Digital display	Specification		
	1	Output for slow start	SL	5Ĺ	During the no. of the setting stitches, SL output is turned ON. The setting no. of stitches can select SLN on [P] mode or HOF on [G] mode by setting SLH on [F] mode		
	2	Run output 1	OP	oP	OP output is turned ON while the sewing machine is running (not including needle lifting during thread trimming).		
Note1	3	Run output 2	OP1	oP 1	OP1 output is turned ON while the sewing machine is running. (not including needle lifting during thread trimming) OP1 output will turn ON during needle lifting when directly heeling.		
	4	Run output 3	OP2	oP2	OP1 output is turned ON while the pedal is toed down, the external operation signal (S0, S1, SH), full pedal heeling or thread trimming signal (S2) is ON.		
	5	Output for run signal	S1	5 !	S1 output is turned ON when the run signal is ON except during on 1 stitch sewing.		
	6	Output for blower	VAC	JRC	VAC output is turned ON during pedal full heeling or while thread trimmer signal S2 is ON.		
•	7	Output for needle cooler	NCL	nEL	NCL output is turned ON while the sewing machine is running (including needle lifting).		
	8	Output for vacuum signal	VCM	υ[Π	VCM output is turned ON during pedal full heeling or while thread trimmer signal S2 is ON while the sewing machine is stopped.		
	9	Output for signal during tacking	ВТ	55	BT output is turned ON during tacking.		
	10	Roller lift output	ROL	rol	ROL output is turned ON when presser foot lifter output FU is ON, backstitching output B is ON, or when input IO2 signal is ON. ROL output is turned ON while tacking and while thread trimming if RLM of [F] mode is ON.		
	11	Thread trimmer output	Т	5	Thread trimming starts.		
	12	Thread release output	L	1	Thread release operation starts.		
	13	Wiper output	W	Ŗ	Wiper operation starts.		
	14	Backstitch output (Condensed stitch)	В	<u>5</u>	Backstitching (reverse feed) starts. (Condensed stitch)		
	15	[CH2] output	СН	[H	CH2 output for chain stitches.		
	16	[TF] output	TF	ΓF	TF output for chain stitches. Refer to pages 93 and 94 for the output timing.		
<b>^</b>	17	[KS1] output	KS1	£5 !	Behind operation signal ON, KS1 output is turned ON after the setting delay time. Refer to pages 95~97 for the output timing.		
	18	[KS2] output	KS2	£52	After the motor stopped, KS2 output is turned ON after the setting delay time. Refer to pages 95~97 for the output timing.		
	19	[KS3] output	KS3	٤53	After trimming and stopped up position, KS3 output is turned ON after setting delay time. Refer to pages 95~97 for the output timing.		
	20	[KS4] output	KS4	£54	Simple sequence output 4. Refer to pages 95~97 for the output timing.		
N-4 C	21	[TB] output	TB	ГЬ	TB output for chain stitches. Refer to pages 93 and 94 for the output timing.		
Note2	22	Presser foot lifter output	FU	FU	Presser foot lifter operation starts. The operation mode set in the [P] mode FUM function and FU function will be entered.		
	23	Output for UP position when stopped	UC	UE	UC output is turned ON if at the needle UP position when the sewing machine is stopped.		
	24	Needle UP position output	UPW	UPB	UPW output is turned ON if at the UP position when the, sewing machine is stopped, and while moving from the UP position to the DOWN position when the sewing machine is running.		

<sup>2.</sup> The setting name will display in the ascending order with each press of the [C] key.

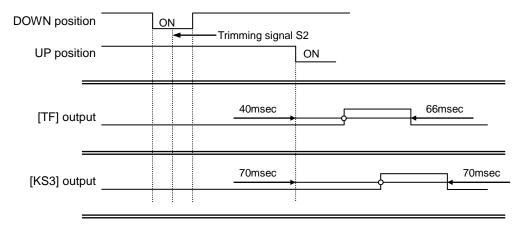
			Sett	ing value	
	No.	Setting name		Digital	Specification
-	25	Needle DOWN position output	DNW	display dod	DNW output is turned ON if at the DOWN position when the, sewing machine is stopped, and while moving from the DOWN position to the UP position when the sewing machine is running.
	26	Output for error occurrence confirmation	ERR	Err	This is output when an error occurs. (Note that this is not output when error code E9 occurs.)
Note1	27	Output for power [OFF] confirmation	IPF	,p¢	Not used.
	28	Puller output	PUL	PUL	PUL output is turned ON during the presser foot lifter operation, during the IO2 output is ON.
	29	Count up output	CUP	[UP	When +1 up counter does, the [CUP] output is turned on.
	30	Thread break detector output	THO	ГНо	When detecting thread break detector, THO output is turned ON. (When re-operation, the signal is turned off)
	31	Vacuum output for holding thread	FUW	FUB	FUW output is turned ON during the presser foot lifter operation or during wiper operation.
	32	[NO] output	NO	no	Nothing is output.
	33	Virtual output 1	OT1	of I	OT1 output is turned ON according to each input specifications while inputs IO1, IR1 and IS1 are ON.
	34	Virtual output 2	OT2	015	OT2 output is turned ON according to each input specifications while inputs IO2, IR2 and IS2 are ON.
	35	Virtual output 3	ОТ3	of 3	OT3 output is turned ON according to each input specifications while inputs IO3, IR3 and IS3 are ON.
	36	[OT4]output	OT4	οſЧ	OT4 output is turned ON according to each input specification while input IO4 is ON.
	37	[OT5]output	OT5	oF5	OT5 output is turned ON according to each input specification while input IO5 is ON.
	38	[OT6]output	OT6	o/5	OT6 output is turned ON according to each input specification while input IO6 is ON.
	39	[OT7]output	OT7	٥٢٦	OT7 output is turned ON according to each input specification while input IO7 is ON.
	40	[OT8]output	OT8	of8	OT8 output is turned ON according to each input specification while input IO8 is ON.
	41	[OT9]output	ОТ9	of 9	OT9 output is turned ON according to each input specification while input IO9 is ON.
	42	[OTA]output	ОТА	οſR	OTA output is turned ON according to each input specification while input IOA is ON.
	43	[OTB]output	ОТВ	ofb	OTB output is turned ON according to each input specification while input IOB is ON.
	44	[OTC]output	OTC	oΓE	OTC output is turned ON according to each input specification while input IOC is ON.
	45	[OTD]output	OTD	olq	OTD output is turned ON according to each input specification while input IOD is ON.
	46	[OTE]output	OTE	ore	OTE output is turned ON according to each input specification while input IOE is ON.
Note2	47	[OTF]output	OTF	οΓF	OTF output is turned ON according to each input specification while input IOF is ON.
	48	[OTG]output	OTG	of 5	OTG output is turned ON according to each input specification while input IOG is ON.
	49	[CUE] output	CUE	EUE	This output becomes ON when Up-counter becomes end. This output becomes OFF when "CCU" input is turned on.

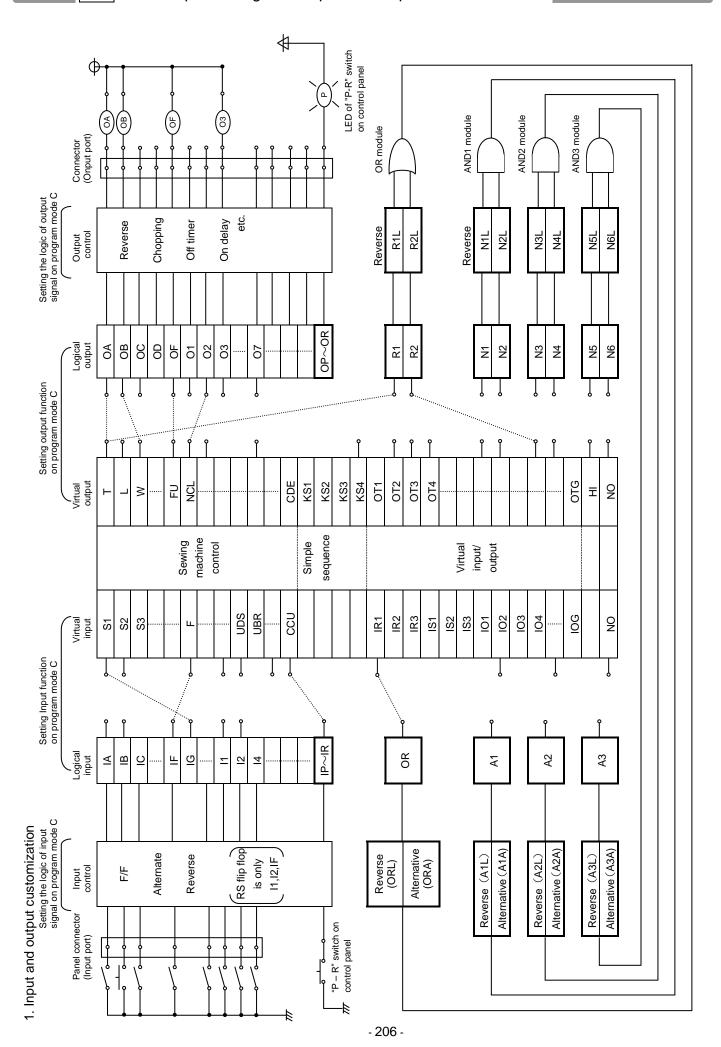
<sup>2.</sup> The setting name will display in the ascending order with each press of the [C] key.

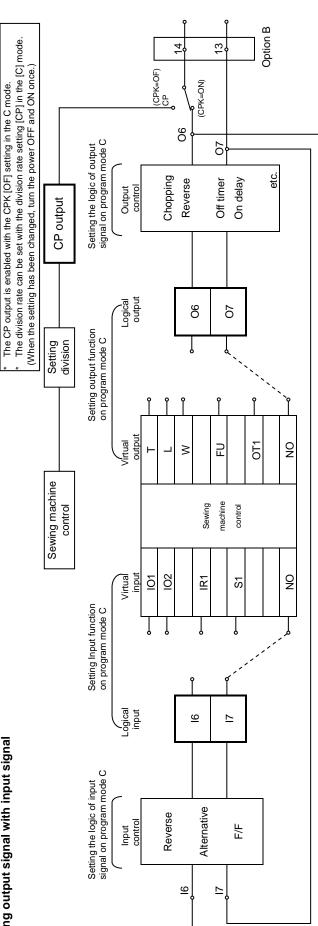
			Setti	ing value	
	No.	Setting name	Digital		Specification
Note1	50	[CDE] output	CDE	CdE	This output becomes ON when Down-counter becomes end. This output becomes OFF when "CCD" input is turned on.
	51	Output for the PSU counting	PSU	PSU	Output signal for the during PSU counting. PSU output will turn ON during the PSU counting.
	52	Output for the PSD counting	PSD	P54	Output signal for the during PSD counting. PSD output will turn ON during the PSD counting.
	53	Output for the PS1 counting	PS1	P5 !	Output signal for the during the sensor input signal PS1 counting. PS1 output will turn ON during the PS1 operation.
<b>,</b>	54	Output for the PS2 counting	PS2	P52	Output signal for the during the sensor input signal PS2 counting. PS2 output will turn ON during the PS2 operation.
	55	[SPC] output for the reached setting speed	SPC	SP[	SPC output is turned ON when reached setting speed. The setting speed is set by [C.] in the C mode.
	56	[SPD] output for the reached setting speed	SPD	5Pd	SPD output is turned ON when reached setting speed. The setting speed is set by [D.] in the C mode.
Note2	57	[SPE] output for the reached setting speed	SPE	SPE	SPE output is turned ON when reached setting speed. The setting speed is set by [E.] in the C mode.
	58	Always ON output	HI	χ.	In case of the power on, [HI] output is always ON.

2. The setting name will display in the ascending order with each press of the [C] key.

Notice The TF output and KS3 output timings are as shown below.



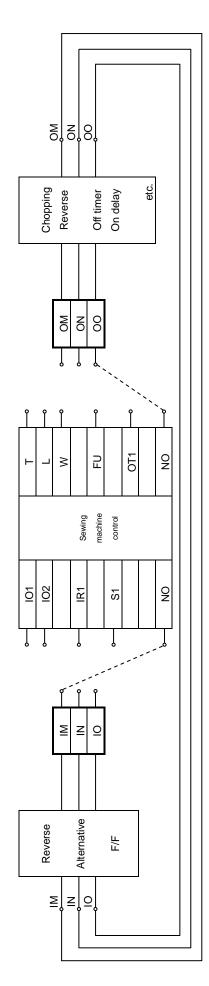




\* The input function settings [16], [17] are coupled to each the output function setting [06], [07] by software.

\* No.13 pin and No.14 pin of the option B connector are not the input/output common port. (Only output port.)

\* The factory settings of the output function settings [O6], [O7] and [16], [17] are all [NO].

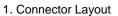


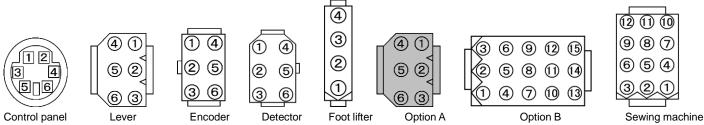
\* The factory settings of the input function settings [IM], [IN], [IO] are all [NO].

\* The factory setting of the output function settings [OM], [ON] are all [NO].

\* The input function settings [IM], [IN], [IO] are coupled to each the output function setting [OM], [ON], [OO] by software.

Variable operation are possible by adding external signals to the option connector. A current of approximately 1.5 mA flows through the switches used





Lever (White)

Signal name	Factory setting		
0V	0V	1	
IG	S1 : Run (Variable speed)	2	<u> </u>
IH	S2 : Thread trimming	3	S2 S2
11	S3 : Presser foot lifter	4	S3 External
VC	VC : Variable speed command	5	VC → variable resister
+12V	+12V	6	₩ 10kΩ

### 0V +12V TXD0

TXD1

Communication /

Control panel (Note 4) RXD1 RXD0

2

3

4

5

				Encoder (Note 4)	
resser foot lifter			F	0V	1
OV	0V	1		EA	2
IF	F : presser foot input	2		EB	3
OF	FU+ : presser foot lifter output +	3	(FU)	+12V	4
Oi	FU- : presser foot lifter output -	4		Ground	5
				_	6

Sewing machine

cowing machine			Sewing machine unit
Ground	Ground	1	
OB	W : Wiper output	2	= (w)_
+24V/(+30V)	+24V	3	
OA	T : Thread trimming output	4	<del>                                     </del>
0V	0V	5	
ID	TL: Thread trimmer cancel input	6	
OD	L : Thread release output	7	(L )
+24V/(+30V)	+24V	8	
ΙĒ	S7 : Backstitch input	9	S7
O √/(+5V)	0V	10	
+24V/(+30V)	+24V	11	
OC	B : Backstitch output	12	(в )
			$\overline{}$

Detector (Note 4)

Botooto: (Hoto I)	
0V	1
-	2
Ground	3
UP	4
DN	5
+12V	6

Option A (Black)

			1
0V	0V	1	2 2011
IA	PSU: Up position stop input	2	PSU
+12V/(+5V)	+12V	3	
IB	PSD : Down position stop input	4	PSD
04	UPW : Needle Up position output	5	— UPW
IC	S0 : Low speed input	6	

control panel /communication, the encoder, and detector excluding our company's products with the above connectors. Moreover, please do not take out these signals besides an original usage, and do not connect them with other devices. It causes the malfunction and the control box breakdown, and our company doesn't assume the responsibility.

Note4: Please do not connect the connector of the

Note 1: Pin number 5 is for the signal output.

## Option B

Option B				
0V	0V	1	•	
14	No setting	2	0 14	
01	OT1 : Virtual output	3	(01)	¬ Њ
VC2	VC2 : Variable speed command	4	VC2	External
15	No setting	5	0 15	resister
I1	(*) IO1 : Virtual input	6	<u> </u>	10kΩ
+5V/(+12V)	+5V	7		+
+24V/(+30V)	+24V	8		<b>→</b>
12	(*) U : Needle lift signal	9	<u>l2</u>	
0V	0V	10		Signals m
+24V/(+30V)	+24V	11		when the
O2	NCL : Needle cooler output	12	02	or [4730]
07	No setting	13	07	I1: S7
O6/CP	No setting	14	<u></u>	12: 10
O3	TF: "TF" output	15	03	_

Signals marked (\*) will be changed as follows when the function of name [4650], [4652], [4710] or [4730] is selected in simple setting

I1: S7 Backstitch input

I2: IO1input

External variable

Note 2: Pin number 3,12,15 are for the solenoid output.

Note 3: Pin number 13,14 are for the air valve output. (not for the solenoid output)

Connector name	Pin number	The input/output signal nation (Factory setting)	ame	Physics input port name	Specification
	2	Variable speed run signal	S1	IG	This signal is equivalent to full toe down when using the pedal. It is operated at the speed which was set with the [C][D] key of control switch panel when the automatic operation AT is ON input S1 at the time of ON.
nnector	3	Thread trimmer signal	S2	IH	This signal is equivalent to full heeling when using the pedal. When S2 is ON and thread trimming or needle UP position stop has been completed, the wiper will operate. After that, the automatic presser foot lifting will function while the signal is ON.
Lever connector	4	Presser foot lifter signal	S3	II	If input S3 is turned ON after trimming, the presser foot will lift. If input S3 is turned ON before trimming, the presser foot will lift after delay time. The delay time is set by S3D the [P] mode of the 132 page.
	5	Variable speed command voltage	VC1	VC1	It is speed regulation input from outside. By giving variable speed command voltage (0-11V), the speed which is proportional to the voltage is gotten.
	6	Constant voltage power supply	+12V	+12V	This is the power for the variable speed command. A DC12V (max.40mA) is out put.
	2	Wiper output	W	OB	Wiper operation starts.
ō	4	Thread trimmer output	T	OA	Thread trimming starts.
Sewing machine connector	6	Thread trimmer cancel signal	TL	ID	If pedal full heeling or thread trimmer signal S2 is turned ON while input TL is ON, the thread will not be trimmed. After the thread trimmer interlock time passes, the presser foot lifting operation will start. When TL of [D] mode signal is turned ON a little time and TLS setting is ON, next thread trimming is prohibited at once.
등	7	Thread release output	L	OD	Thread release operation starts.
ewing ma	9	Backstitching during run signal	S7	ΙE	If input S7 is turned ON while the sewing machine is running, backstitching (reverse feed) will start. Nothing will happen if input S7 is turned ON while the sewing machine is stopped.
Se	12	Backstitch output (Condensed stitch)	В	OC	Backstitching (reverse feed) starts. (Condensed stitch)
	2	Presser foot lifter signal	F	IF	If input F is turned ON, the presser foot lifter operation will start.
Presser foot lifter	3	Presser foot lifter output	FU+ FU-	OF	Presser foot lifter operation starts. The operation mode set in the [P] mode FUM function and FU function will be entered.
<u></u>	2	Needle UP position priority stop signal	PSU	IA	If input PSU is turned ON while the sewing machine is running, the needle will stop at the UP position after swing PSU stitches and thread trimming. The no. of stitches after PSU input is set by PSU the [P] mode of 130 page.
necto	3	Constant voltage power supply	+12V	+12V	The constant voltage power supply. DC +12V (max.40mA)
Option A connector	4	Needle DOWN position priority stop signal	PSD	IB	If input PSD is turned ON while the sewing machine is running, the needle will stop at the DOWN position after swing PSD stitches. The no. of stitches after PSD input is set by PSD the [P] mode of 130 page.
Opti	5	Needle UP position output	UPW	O4	The UP position signal is output. This can be used as the signal for the stitch count, etc. The output voltage is DC 12V/5V (max. 10mA). The factory setting is 12V.
	6	Low speed run signal	S0	IC	If input S0 is turned ON, the sewing machine will run at the speed set in low speed [L].
	2	Nothing signal	NO	14	Factory setting is NO setting. Refer to the [C mode input signal setting table].
	3	Virtual output 1	OT1	O1	OT1 output is turned ON according to each input specifications while inputs IO1, IR1 and IS1 are ON.
	4	Variable speed command	VC2	VC2	This is the input for external speed command. By applying the variable speed command voltage, the speed that is relative to the voltage is obtained.
	5	Nothing signal	NO	15	Factory setting is NO setting. Refer to the [C mode input signal setting table].
ector	6	Signal output to virtual output 1	IO1	I1	If input IO1 is turned ON, output OT1 will always be turned ON.
Option B connector	7	Rated voltage power supply	+5V	+5V	A DC 5V is output (max.50mA). This can be used as the power source for the photoelectric switches in the amplifier.
n E	9	Needle lift signal	U	12	If input U is turned ON, the needle lift operation will start.
Optio	12	Output for needle cooler	NCL	O2	NCL output is turned ON while the sewing machine is running (including needle lifting).
	13	Nothing output	NO	07	This port is for the air valve output. And it is an input/output coupling port. Factory setting is NO setting. Refer to page 207.
	14	Nothing output	NO	O6/CP	This port is for the air valve output. And it is an input/output coupling port. Factory setting is NO setting. Refer to page 207. When using as the CP output, make 159 page C mode CPK OFF setting.
1	15	[TF] output	TF	O3	TF output for chain stitches. Refer to pages 93 and 94 for the output timing.

3. To use as a standing work type sewing machine. (Turn the program mode [C] function [PDS] ON.)

The sewing machine can be used as a standing work type sewing machine with the three connections below using the lever connector. However, take special care to the intrusion of noise, and use the shortest wiring possible.

### [Note: Procedure for changing the lever connector]

- Be sure to turn OFF the power switch when connecting or disconnecting the lever connector.
- Do not connect the lever connector when you set the function [PDS] to ON in the program mode [C] (Direct call number = "530")

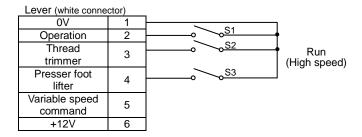
[Basic procedure]

(1) Disconnect the lever connector after turning OFF the power switch

resistor  $10k\Omega$ 

- (2) Turn ON the power switch and then, set the function [PDS] to ON. The lever connector still disconnects.
- (3) Connect the lever connect after turning OFF the power switch.
- (4) Turn ON the power switch and confirm the operation.
  - % When the error code MA is displayed, press D key and then, it is released.
- (1) When operating with an external variable resistor ("XC-G500" Control switch panel [auto] and AT in [P] mode is OFF)

Lever (white connector) 0V S1 Operation 2 S<sub>2</sub> Thread 3 trimmer Presser foot 4 lifter Variable speed VC 5 command +12V 6 External variable (2) For operating with a high speed ("XC-G500" Control switch panel [auto] or AT in [P] mode is ON)



# 28 Error Display

When the control box detects an error, the error code is flickered on the control switch panel display. Confirm the error code, and investigate with the following table.

Error code	Probable cause	Inspection					
P&r.oF	Is the power voltage too low? Is the power supply capacity too small?	Check the power voltage. Check the power supply capacity.					
/POWER.OI	Note: It does this display when power supply is turned C	Note: It does this display when power supply is turned OFF, but this is not an error.					
<b>E !</b> / E1	Is the wire to the motor short-circuited?	Check the motor wiring.					
<b>└</b>	Is the sewing machine load torque too high?	Check the sewing machine.					
<b>E2</b> /E2	Is the power voltage too high?	Check the power voltage.					
<b>LL</b> /E2	Is the sewing machine inertia too high?	Lengthen the deceleration time.					
	Is the connector to the motor encoder securely inserted?	Check the connector insertion.					
6.3	Are the signals from the motor encoder broken ?	Check the ECA and ECB signal.					
E 3 / E3	Are the signals from the motor encoder broken?	(Refer to the E mode.)					
	Is the sewing machine locked?	Check the sewing machine.					
	Is the motor locked?	Check the motor.					
<b>E4</b> / E4	Is the motor connector securely inserted?	Check the motor connector insertion.					
<b>└</b>	Are the signals from the motor connector correct?	Check the motor connector.					
<b>E 6</b> / E6	Is an extraordinary signal inputted? (The signal as it repeats ON/OFF at the high frequency.)	Check the input signal.					
	Does the noise from outside enter an input signal?	Remove a noise source.					
6.0	Is the position detector connector securely inserted?	Check the detector connector insertion.					
<b>68</b> / E8	Are the signals from the detector broken?	Check the detector UP/DOWN signals.					
	(UP/DOWN signal interruption)	(Refer to the E mode.)					
<b>E9</b> / E9	Is the solenoid wiring short-circuited?	Check the solenoid wiring.					
<b>└ J</b> / E9	Solenoid defect (coil defect)	Replace the solenoid.					
<b>E    </b> <sub>/E11</sub>	Is the fuse for +12V power supply broken?	Check the fuse for the 12V power supply.					

\*E11 error code is not confirmed on the control switch panel when it happens because the LEDs on the control switch panel is turned OFF, but the status display LED on the control box flickers in orange colored as the interval of 0.3 sec. It will be confirmed in error code history after returning to a normal condition.

0.5	An error of the copy mode using the control switch panel.	
115 / M5	Is the control switch panel connector securely inserted?	Check the connector insertion.
	The voltage or the type of control switch panel is difference.	Check the voltage and the type are right.
<b>ПЯ</b> /ма	The position data of the lever unit is defective.  When power supply is turned ON, the pedal is not neutral position. (The status display LED on the control box turn on in orange colored.)	The pedal is neutralized. (It returns automatically 1 second later.) (Refer to the VCSET setting (page 39).)

Others	Probable cause	Inspection		
	Are the operation signals from the lever unit broken?	Check the lever unit signal.		
The sewing machine does not	The the operation digitals from the level unit broken.	(Refer to [E] mode S1 signal.)		
run when the pedal pressed.	Is the input signal S6 broken ?	Check the status display LED. If flickering, reset		
Turi when the pedal pressed.	is the input signal 30 bloken !	the signal.		
		Confirm the sewing machine connector.		
	It does not display 99 in normal mode.	Change 99 using control box [D] key.		
The sewing machine does not	le the veriable appeal voltage with the pedal tood down low?	Check the variable speed voltage. (Refer to [E]		
run at the high speed.	Is the variable speed voltage with the pedal toed down low?	mode.)		
	Is the motor pulley diameter too small?	Check the motor pulley diameter.(Refer to [5]-3)		
The thread is not trimmed even	Is the thread trimming signal (S2) from the lever unit broken?	Check the signal S2. (Refer [E] mode.)		
	Is the cancel thread trimmer operation S2L(mode[P]) ON?	Set S2L(mode[P]) to OFF.		
with heeling.	Is the trim key of the control switch panel OFF?	Set the trim key to ON.		
The presser foot lifter output	Is the light heeling signal (S3) or the thread trimming signal (S2) from the lever unit broken?	Check signals S2 and S3. (Refer [E] mode.)		
	Is the presser foot lift signal (F) broken?	Check signal F. (Refer [E] mode.)		
does not operate.				
	Is the presser foot output (FU) broken?	Check FU output. (Refer [E] mode.)		

# 29 Specifications

Voltage and Frequency Specifications		110V single phase 50/60 Hz	230V single phase, 3-phase 50/60 Hz				
	Model name			XL-G554-10 (Y)	XL-G554-20 (Y)	XL-G754-20 (Y)	
	Voltage Rated output		100 to 120 V 200 to 240 V				
N4-4				550	W 750W		
Motor	Rated torque		orque	1.47N∘m (	1.96N∘m (0.2kg∘m)		
	Rated speed		speed		3,600 rpm		
		Wei	ght		6.9 kg (Main unit)		
	Model name	automatic thread		XC-GMFY-10-05	XC-GMFY-20-05	XC-GMFY-20-07	
	Speed control range Control  Voltage Sewing machine shaft Meter shaft		100 to 120 V 200 to 240 V				
Control			machine	70 to 4,000 (MAX 8,999) rpm 50 to 3,600 rpm			
box	Solenoid voltage			DC 24 V / 30 V			
			ing Voltage	±10%			
	Ambient temperature Ambient humidity Storage temperature			5 ~ 35 °C			
			numidity	45 - 85%RH (with no dew condensation)			
			-25 ~ 55°C (no freezing)				
	Altitude			Under 1000m above mean sea level			
Weight		3.5kg (Main unit)					
Position detector		XC-KE-01P					

### Solenoid output

O a la mari d	Impedance $(\Omega)$			
Solenoid	24VDC Setting	30VDC Setting		
OF (Presser foot lifter output FU)	8 or more (continuous time rating)	10 or more (continuous time rating)		
OA (Thread trimming output T)	4 or more (short time rating)	5 or more (short time rating)		
OB (Wiper output W)	4 or more (short time rating)	5 or more (short time rating)		
OC (back stitch output B)	4 or more (short time rating)	5 or more (short time rating)		
OD (Thread release L)	4 or more (short time rating)	5 or more (short time rating)		
O1 (Output)	4 or more (short time rating)	5 or more (short time rating)		
O2 (Needle cooler output NCL)	4 or more (short time rating)	5 or more (short time rating)		
O3 (TF output TF)	4 or more (short time rating)	5 or more (short time rating)		

- Note 1. In the brackets of solenoid output, it is a factory setting.
  2. The continuous time rating of "OF" output is 50 percentage of chopping duty.
  - 3. The maximum output current rating is 2.0A for 24VDC and 1.6A for 30VDC.
  - 4.24VDC setting is a factory setting.

Rated output current of value output

O6, O7: Total maximum current is 0.3 A. Rated maximum output current

<Reference> Table of digital display

eterence> Table	or digita	ai uispia	у	1	1	1			1	
No.	0	1	2	3	4	5	6	7	8	9
Digital display		;	2	3	4	5	5	7	8	9
No.	Α	В	С	D	E	F	G	Н	I	J
Digital display	æ	Ь	L	o	E	F	[	H	•	C.
No.	K	L	М	N	0	Р	Q	R	S	Т
Digital display	'n	L	C	C	0	P	9	r	5	<u></u>
No.	J	V	W	X	Υ	Z				
Digital display	U	C	R	11	μ	-				

Options	Model name	Specifications
Control panel	XC-G500-Y	"XC-G500-Y" and "XC-G10" cannot be used together.
Automatic presser foot lifter	XC-FM-2	Electromagnetic type (for 24V)
inter	XC-FM-3	It is possible to use it for LS2-1380. (for 24V)
	LE-FA	Pneumatic type (common for 30V/24V)
Variable speed pedal	XC-CVS-2	3-series pedal, for standing operation sewing machine
Lever unit	XC-GL-1-SET	For one-step pedal heeling
(separated type)		(installation plate, extension cable set)
	XC-GL-2-SET	For two-step pedal heeling
		(installation plate, extension cable set)

Extention cable	Parts No.
Motor cable 1.0m ( for 200V )	M97318099
Detector cable 0.6m	K14M71324830
Encoder cable 1.0m	K14M71725402
Detector cable for Singer machine	K14M72025530
Sewing machine cable for Basting machine	K14M72025730

Installation plate	Parts No.	Specifications
Mounting plate of motor	K14M72354001	XL-G554 motor and old control box
and control box	K14M72354101	Old motor and XC-GMFY control box

### 1. Motor assembly

### (1) Clean periodically the dust filter in Fig. 1.

(Clogged filter causes the overheat of motor.)





Fig. 1 Dust filter

# (2) Internal inspection of motor

There is no need to disassemble the motor normally. However, when the revolution is not smooth, abnormal noises are generated or the encoder is replaced, inspect it with following procedures.

- 1) Turn off the power.
- 2) Remove the belt cover, belt and motor pulley.
- 3) Disassemble the motor from the sewing machine table.
- 4) Remove the end cover mounting screws (3 pcs.). (Fig. 2.)
- 5) Remove the end cover and check for any foreign substance on the motor cooling fan, motor shaft, etc. or looseness of motor cooling fan mounting screws. To remove the motor cooling fan, unfasten the mounting screws. (Fig. 3)



Fig. 2 Cover mounting screw

### Caution

Encoder appears (Fig. 4) as the motor cooling fan is removed. Since the encoder is a highly sensitive component, a sufficient care should be taken not to apply a strong shock when the motor inside is cleaned or the motor cooling fan is removed. If the motor cooling fan mounting screws become loose, abnormal noises may be generated. Lock them securely to avoid loosening. (appropriate tightening torque is about 3 N-m.) Use the screw lock agent when they are fastened.

6) When the encoder sensor is replaced, remove the encoder sensor mounting screw A, B and encoder lead wire mounting screws. (Fig. 4) When the sensor is installed, keep pressing the sensor against the sensor stop on the motor frame (toward the motor shaft) and lock the sensor mounting screw A first and B next.

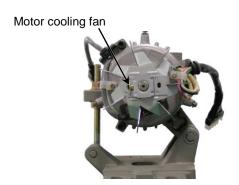


Fig. 3 Motor cooling fan mounting screw

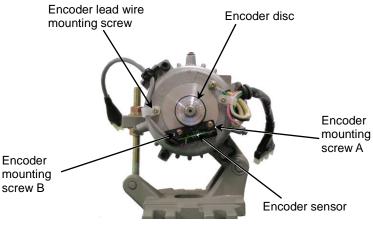


Fig. 4 Encoder

As the screws A and B are locked orderly while the motor frame stop is pressed against the sensor stop of motor frame, the gap between the sensor and the disc is determined automatically.

Since the encoder sensor (Fig. 5) is a highly sensitive component, a sufficient care should be taken not to damage it.

# Motor frame stop

Fig. 5 Encoder sensor

### Caution

When replacing only the encoder sensor section, the work can be done without removing the motor cooling fan explained on the previous page. When the fan has been removed, always apply a screw locking agent to fix it.

- 7) When the encoder disc is replaced, remove the disc set screws using a small hexagon wrench. To install the encoder disc, adjust the gap between the encoder disc and the encoder sensor at 0.14 ± 0.04 mm (Fig. 6) and adjust the space between the encoder disc and the motor frame at 10.0 ± 0.1 mm and fasten the lock screw. If the difference of this gap is larger, the encoder may fail to detect the motor revolution. Make sure to install it precisely.
- 8) When the bearing is replaced, remove first the encoder sensor and the disc. Remove next the encoder, then the lead wire mounting screws, motor frame lock screws and disassemble the motor frame. (Fig. 7) Separate the bearing from rotor and install a new bearing. Since the special type bearing is used, contact us if you have none in stock. After the bearing has been replaced, assemble in the order of encoder disc and encoder sensor with reference to the steps 6) and 7) above.

# Encoder disc O.14 ± 0.04 mm Encoder sensor Motor frame Sensor stop of motor frame

Fig. 6 Installation of encoder disc

### Caution

Fix securely the motor frame lock screws with the torque of more than 6 N-m.

Assemble the components in the reverse order of removal.

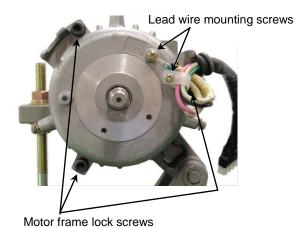


Fig. 7 Disassembly of motor

